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COMMONWEALTH OF AUSTRALIA

DEPARTMENT OF NATIONAL DEVELOPMENT

BUREAU OF MINERAL RESOURCES, GEOLOGY AND GEOPHYSICS

Record No. 1970/67

023045

**A Computer Programme for Analysing
Directional Data designed for use on
A CDC3600**



by

B. G. Jones

**BMR
Record
1970/67
c.4**

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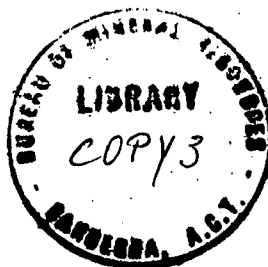
A COMPUTER PROGRAMME FOR ANALYSING
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ABSTRACT

A computer programme has been developed to correct three dimensional directional data for the effects of regional tilt. The data may be presented either as a strike and dip measurement using a single cardinal point for the dip direction, or as an azimuth and dip measurement. After correcting each measurement back to an assumed original horizontal attitude arithmetic and two and three dimensional vectorial analysis of the data may be undertaken (optional) at three hierarchial levels to provide mean vector directions, vector magnitudes, and confidence limits about the vector mean.

INTRODUCTION

This report describes a programme developed to correct cross-bed data for regional tilt and to produce a vectorial analysis for current direction studies. The effect of regional tilt on directional features is quite pronounced even at dips as low as 20° . In any study of paleocurrent trends the first consideration is, therefore, to apply tilt corrections to directional structures such as cross-bedding so as to calculate the original attitude of the cross-strata. The second step involves vectorial analysis of the corrected azimuths so as to calculate a mean azimuthal trend. The programme is designed to handle three dimensional data such as cross-stratification as well as two dimensional directional or linear data.

Each individual entry specifies 'locality' and 'stratigraphic' references as well as orientation of regional tilt and the directional feature. A separate card is required for each directional feature. The 'locality' parameter controls the third level of grouping and may be alpha-numerical. The 'stratigraphic' reference parameter is numerical and changes in its value trigger the first and second levels of grouping.

The programme output may be varied according to the requirements of the operator. The calculated parameters are grouped according to the information which they contain. They are stored in the computer until all calculations are completed and they are then printed out in

tabular form. The tables, in order of output, contain original and corrected individual cross-bed measurements; number and percentage frequency distributions of individuals per group; calculated means for groups of beds; calculated means for specified group intervals; and calculated means for each locality.

TILT CORRECTION

Each directional feature is corrected for regional tilt by a trigonometric solution using lower hemisphere projections. The method only corrects for simple unidirectional tilting of the beds about a horizontal axis. Where plunge of the beds is also important the programme would have to be run twice - once to correct for the plunge and then again for the tilting. Plunge correction is only necessary where the plunge of a bed is greater than about 20° . With high plunges care would also have to be taken to ensure that other tectonic deformation has not affected the beds and produced further anomalies.

ANALYSIS OF DIRECTIONAL FEATURES

Corrected cross-bed trends may be studied in terms of direction analysis as may other two and three dimensional data. Direction analysis may be visual or vectorial and data for both options is available as output from the programme, although current roses are not plotted and are just provided in numerical form.

Vectorial analysis of the data is undertaken at three hierarchical levels of grouping. The lowest level of grouping that can be specified groups individual data measurements from one bed,

stratigraphic level, or geographic locality depending upon the type of analysis being conducted. The second level of grouping yields two values, the first based on the mean of all individual readings and the second based on the vectorial means of lower level groups. The highest level of grouping uses the same data as the second level of grouping but groups the beds, stratigraphic intervals, or localities to provide an overall analysis of all the data in one set. The method of grouping data is illustrated in the flow diagram in Figure 1.

Two Dimensional Analysis

The procedure for analysing the directional data follows Potter and Pettijohn (1963). Analysis may be simply visual and this is accomplished by plotting number or percentage frequency distributions for each grouping as a histogram or current rose. Numerical results for these distributions are given in the second table of output. The distribution is recorded in 30° intervals from 0° to 29.99° etc.

The first level of data grouping utilized in this programme is controlled by the number given as the group reference parameter, (second entry on all data cards). Any change in this number initiates the calculation of vector means for the preceeding set of directional features where the group reference parameter remained constant. Any number of individuals can be included in a group although no output will result when attempting to group one sample. When only two individuals are grouped various three dimensional parameters are not calculated, but for groups of three or more individuals, all parameters are calculated.

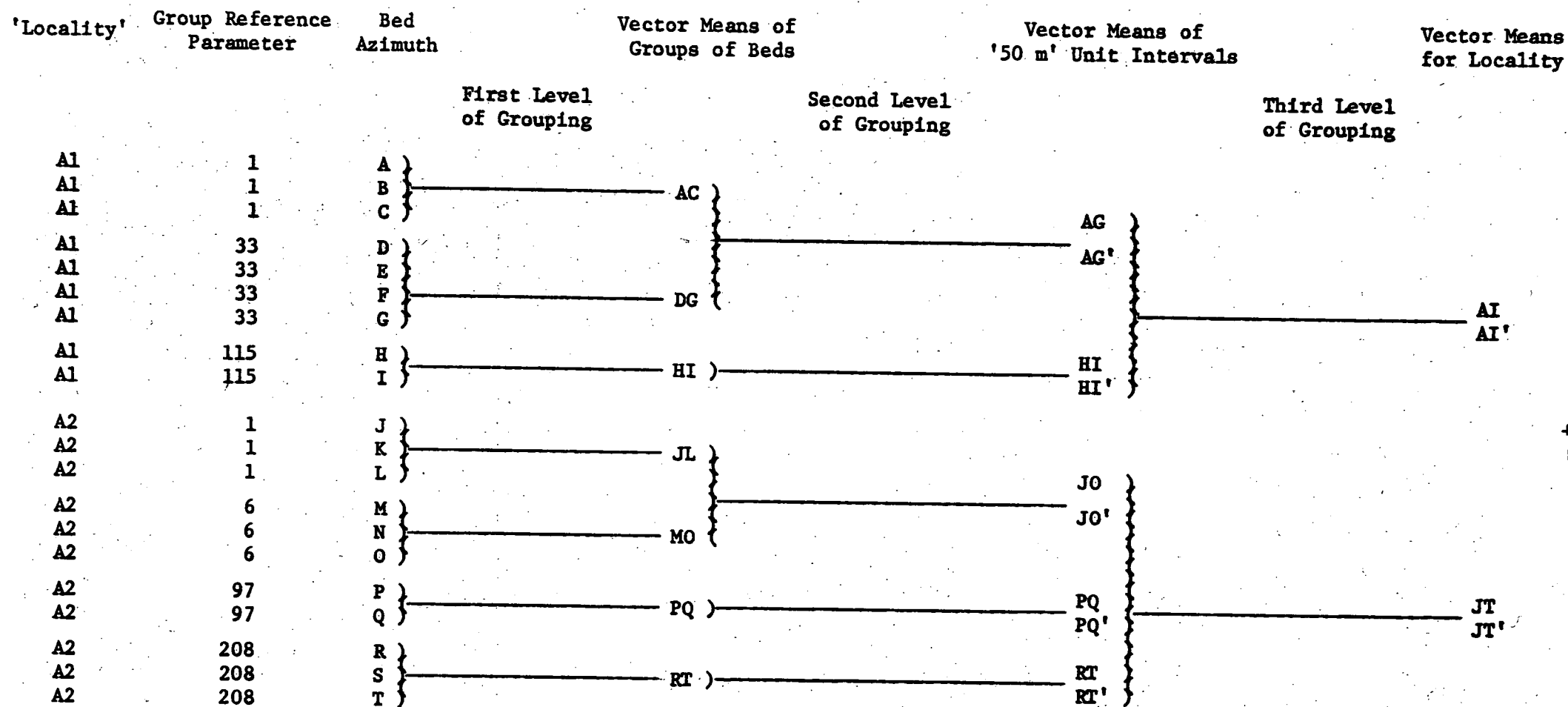


Figure 1 A flow diagram illustrating the methods of grouping data into three hierarchical levels. The second and third levels of grouping each produce two vector means - one utilizes the individual data measurements and is thus weighted by the number of readings in a group while the second uses unweighted vector means of the group to give a normally distributed resultant vector.

Averages calculated at the first level of grouping include arithmetic, vectorial and three dimensional parameters while at higher levels of data grouping only vectorial analyses are presented. The arithmetic mean is calculated for each sample although it is not a good measure of central tendency (Potter and Pettijohn, 1963). The average cross-bed dip and thickness (where measured) are also determined arithmetically but no statistical measures of consistency are calculated for them. Vectorial analysis is the simplest and most reliable method of determining the mean direction from data with a relatively wide scatter about the dominant direction. The use of vectorial analysis has been described in Potter and Pettijohn (1963). The programme is designed so that the following parameters, as defined in Potter and Pettijohn (1963), are calculated: -

vector trend, vector magnitude and vector magnitude expressed as a percentage of the possible unidirectional magnitude, the variance and standard deviation about the vector trend, the Rayleigh probability of randomness and its equivalent significance level.

The magnitude percent gives an indication of the consistency of the vector direction with higher percentages indicating greater consistency. The magnitude percent negatively correlates with variance (Curry, 1956) and is a useful method of representing directional consistency. The variance and standard deviation both give estimates of the spread of the data and the variance can be used to statistically test the data for randomness by means of an F ratio. The variance of a random data spread (Su^2) in a 360° field is $Su^2 = 10,800$ (Griffiths and Rosenfeld, 1953).

The F-ratio is obtained from the expression $F = s_u^2/s_d^2$ where s_d^2 is the observed variance and it is compared with tables of the F-distribution using the same number of degrees of freedom for the numerator and denominator (e.g. Pearson and Hartley, 1962, Table 31, p.179). If the F-ratio is less than the tabled value the data does not differ significantly from a random distribution.

The Rayleigh test of significance is also a test of randomness. A modified version of the test (Durand and Greenwood, 1958) was used in this programme and it provides a statistic of randomness for samples of more than five individuals. The comparable five percent confidence level is also calculated for each sample and if this is larger than the associated Rayleigh probability then the sample can be considered to be randomly distributed.

Both the F-ratio and Rayleigh tests only test for randomness of distribution. If they indicate that the distribution is not random this cannot be taken as a statistical proof that the data is oriented (Griffith and Rosenfeld, 1953).

The second level of grouping is controlled by IC on Control Card 1. The unit interval (IP) over which averages are produced may be selected by the operator, but for any set of data under the same control cards the interval is constant. The arithmetic average thickness and dip is computed from every individual cross-bed measurement in the specified interval. Likewise, the average two dimensional vector trend and associated vector magnitude and magnitude percent is calculated from every individual cross-bed in the specified interval. In addition, the vector means obtained for groups of individuals are analysed without

weighting, and the resultant average group vectors and group vector magnitude percent are recorded. The latter parameters give a better representation of overall current direction if each group, from a single stratigraphic horizon, is considered to represent a sample of a normal population of current trends at the sampling locality.

The third level of grouping is controlled by a change in locality identity in the data deck. It initiates a similar set of calculations to the above with two dimensional vectorial analysis of every individual in the locality as well as analysis of the unweighted group vectors.

Three Dimensional Vector Analysis

A three dimensional vector analysis is included at the first level of grouping to enable the programme to handle three dimensional data such as paleomagnetic measurements, imbrication of grains or clasts, as well as providing a three dimensional approach to determining cross-bed azimuth directions.

The method follows Steinmetz (1962) who reviewed much of the earlier relevant literature. He suggested that a three dimensional analysis of three dimensional data gives a more accurate indication of vectorial direction and also enables confidence limits to be calculated about the resultant. Azimuth and dip values of cross-beds, corrected for regional tilt, are used in the programme as the basic data for vectorial analysis, and the following parameters are calculated: -

$\bar{A}$ = average vector direction of dip which may be interpreted as the mean direction of current, etc.

$$= \arctan(\Sigma(\sin A \cdot \cos D) / \Sigma(\cos A \cdot \cos D))$$

$$R = \text{magnitude of resultant three dimensional vector}$$

$$= ((\sum(\sin A \cos D))^2 + (\sum(\cos A \cos D))^2 + (\sum(\sin D))^2)^{\frac{1}{2}}$$

$\bar{D}$ = inclination of resultant vector. Does not equal average dip of cross-beds

$$= \arcsin (\sum(\sin D)/R)$$

$\theta_{.05}$ = spherical radius of circle of 95 percent confidence around the resultant vector

$$= \arccos (1 - ((N-R)((\frac{1}{P})^{1/(N-1)} - 1)/R))$$

K = estimate of precision with $2(N-1)$ degrees of freedom

$$= (N-1)/(N-R)$$

where A = azimuth direction

D = dip of azimuth

N = number of readings

P = probability level required

The resultant three dimensional vector magnitudes can be tested for randomness by simply determining their length and comparing this with the tables of five percent and one percent values of significant randomness (Watson, 1956, p.161) for sample sizes up to 20. For groups with between 20 and 100 samples the five percent significance points may be estimated by evaluating $N\chi_3^2/3$ where $\chi_3^2 = 7.815$. The values obtained are all 0.04 above the true value. One percent significance points can be approximated to within 0.15 above true values from $N\chi_3^2/3$ where $\chi_3^2 = 11.345$. Provided the resultant vector length is greater than the equivalent significance value the vector direction can be considered reasonably reliable i.e. significantly different from a random distribution.

The meaning of $\theta_{.05}$ is that there is a five percent probability that the true azimuth direction of the data deviates by more than θ^0

in any direction from the calculated resultant vector direction.

K values from various groups of data may be used to test whether the resultant vector means are significantly different from each other. The same number of samples are required in each group (i.e. $v = N-1$) for the test to be correct. An approximate test can be made using the mean values of N and v, but for more accurate work an M test of variance should be used (Pearson and Hartley, 1962, p.61).

PROGRAMME OPERATION

Data Control Variables

The first two variables on each data card are parameters which control and initiate various functions in the programme. Both are usually required for the successful running of the programme and they may be true or dummy variables. The first variable controls the third grouping level and an individual run is terminated if this field is left blank. The variable may be any combination of eight or fewer alpha-numeric characters except zero and any change in any of the characters initiates averaging of all data since the preceeding change of the characters. This variable is usually used to represent a location or subregion in which a variable number of readings have been taken.

The second variable, the group reference parameter, is a numerical floating point variable which controls the averaging of data in groups and over specified intervals. Any change in the number initiates averaging of all individuals within the group denoted by the preceeding number. Averaging over a specified unit

interval is controlled by the change of the second variable number from one group interval to the next. An example of the use of the second variable follows. If the specified unit interval (IP on Control Card 1) equals 100, unit interval averages will be calculated when the second variable changes from the range 0-99.9 to 100-199.9 etc, and the group averages will be calculated at any change in the second variable e.g. 1 to 1.5, or 10 to 60, or 5 to 287 etc. The second variable may be used to conveniently represent stratigraphic height at a locality or it may be a dummy variable used to represent individual sampling localities.

For large programmes requiring more hierarchical levels of grouping the programme would have to be run more than once with the second run requiring vectorial analysis only. Provision is made for punching the result at the first grouping level (controlled by IB = 2).

The third, fourth and fifth variables are used to record the regional tilt. The third variable may be used to give either the regional strike or the azimuth of the regional dip. The fourth variable gives the regional dip while the fifth variable is only used when the regional strike is given in the third variable. In this case the fifth variable must be given in terms of the cardinal points N, E, S or W. If the strike, or its reciprocal, is the same as the cardinal direction given for the dip the reading is rejected from the analysis (e.g. strike 270 dip 17°E).

The sixth, seventh and eighth variables give the equivalent information for the cross-bed reading. However, when the dip of the cross-bed is zero put the azimuth or strike of the cross-bed equal to the azimuth or strike of the regional dip.

In the case of two dimensional data, such as current lineation, no correction for regional tilt is provided. However, the vectorial analysis of such data may be carried out using this programme. Provision is made for analysing such data in two forms, one when the sense of the directional feature is known and the other when the sense is unknown. However, these two cases cannot be run concurrently. In both cases the only information required for the programme operation is the first two variables and the strike or direction of the sense of the structure being analysed. Provision has to be made on the data card, however, for the third, fourth and fifth variables (e.g. three blanks on the data card and equivalent formats 2F1.0, R1).

The ninth to twelfth variables are optional and they are not necessary for the functioning of the programme. The ninth variable is numerical and is averaged in the first level of grouping. It may be used for bed thickness or similar information. The following three variables may be alpha-numeric and they are simply copied onto the output.

Deck Structure

The complete deck is composed of the standard operation control cards together with the programme deck in fortran or binary. This is followed by three control cards, the data deck and either a blank card or, at the end of a run, by an end of file card.

Fortran Programme Deck

1. Job card: - Column 1 *JOB, Charge Code, DIRECT, time limit
2. Fortran card: - Column 1 *FTN, L, X
3. Programme deck in Fortran
4. Scope card: - Column 10 SCOPE
5. Load card: - Column 1 *LOAD
6. Run card: - Column 1 *RUN, time, maximum lines of print.

Binary Programme Deck

1. Job card: - Column 1 *JOB, Charge code, DIRECT, time limit
2. Binary object programme
3. Run card: - Column 1 *RUN, time, maximum lines of print.

Data Deck(s)

One or more separate data decks can be run at a time and each is preceeded by three control cards.

Control Card 1 (analysis specification)

Controls method of data analysis and output specifications.

Column 5 IA = 0 Do not print individual bed corrections

= 1 Print individual bed corrections

= 2 END PROGRAMME EXECUTION

Column 10 IB = 0 Do not analyse or print groups of beds

= 1 Analyse and print groups of beds

= 2 Analyse, print and punch groups of beds

Column 15 IC = 0 Do not analyse or print unit intervals

= 1 Analyse and print unit intervals

specified by control IP

Column 20 ID = 0 Do not analyse or print locality averages

= 1 Analyse and print locality averages

Column 25 IE = 0 Do not analyse or print 30⁰ quadrant measures

= 1 Analyse and print 30⁰ quadrant measures

Column 30 IG = 0 Analyse as three directional data e.g. x-beds

= 1 Analyse as two dimensional data with sense

e.g. flute casts

= 2 Analyse as two dimensional data without

sense e.g. current lineation.

Columns 31-35 IP = x required when IC = 1 to specify unit

interval, x, over which averages are

required. e.g. 100 for 100m intervals as

from 100 to 199, 200 to 299 etc. Operates

on data supplied in second statement on

input card. May be omitted when IC = 0

Columns 36-40 AMAG = correction factor for magnetic deviation

if required. Read in F5.1 format and if

correction factor is negative it must be

written here as such. May be omitted

if no correction is necessary.

Control Card 2 (Format statement)

The second control card contains the format statement for data input. It is variable but has the following limitations. The entries must be in the following order unless statement number 80 in the Fortran programme deck is altered: -

1.	'Locality'	A format	
2.	'Group'	F format	
3.	Regional strike or azimuth of regional dip	F format	
4.	Regional dip	F format	
5.	Regional dip direction (only required if regional strike used)	R1 format	
6.	Cross-bed strike or azimuth of cross-bed dip	F format	
7.	Cross-bed dip	F format	
8.	Cross-bed dip direction (only required if cross-bed strike used)	R1 format	
9.	Cross-bed thickness	F format	} presence of data optional
10.	Additional information to be copied onto output	3A formats	

The F formats are of free size while the first and last 3A formats are variable up to a maximum of eight characters. If the last 3 A formats are eight characters each, the information they contain will be copied, without breaks, onto the output and may be used for any information that the programmer desires. The restricted formats are the R1 formats following the bedding and cross-bedding dip measurements. A suggested data sheet layout and appropriate format statement is given in Table 1, line numbers (1) and (2). If the thickness and comment columns are not required the format may remain as in (2) or be altered to (3).

Control Card 3 (title card)

Any information that the programmer requires can be written on all 80 columns of the title card and it will be simply copied

CSIRO DATA SHEET

PROGRAM

NAME

JOB

DATE

PAGE NO.

DIRECT.

TABLE 1

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 79 80 COMMENT

COMPUTER RUN CONTROL CARDS

*JOB, CBDMRCTO, DIRECT, 4

*FTN, L, X

OR

*FTN, L, X, P

{PRINTS OUT BINARY DECK}

SCOPE

*LOAD

*RUN, 4, 5000

SUGGESTED DATA LAYOUT AND FORMATS FOR PROGRAMME DIRECT

	LOCATION	GROUP	BEDDING TREND D.I.P.	CROSS-BED TREND D.I.P.	THICK	SHAPE	GRAIN	OTHERS
(1)	(A8, F7.0, 1X, 2(4X, 2F5.0, R1), F9.0, 1X, 3A8)							
(2)	(A8, F7.0, 1X, 2(4X, 2F5.0, R1), I1, 3A1)							
(3)	(A8, F7.0, 1X, 2(4X, 2F5.0, R1), I1, 3A1)							

{MAY BE USED WHEN THERE IS NO DATA
IN COLUMNS 51-80}

5 10 15 20 25 30 35 40 45 50 55 60 65 70 75 80

out as a heading. If centred on the card it will be centred on the output.

Data Deck follows immediately after the control cards and is terminated by blank card. Any number of data sets may be included in a single run of the programme and the run is terminated by a card with 2 in column 5 (i.e. by reading Control Card 1 with IA = 2 followed by an end of deck card, *EOD from column 1-4.

Programme Size

The number of individual readings that can be analysed is limited only by the time required for analysis and print-out. However, data grouping levels are restricted in the present programme by the available memory in the computer. The programme as dimensioned here is very close to the maximum available size and it can handle up to 375 first level groups, 250 second level groups and 100 third level groups in any single data set and the number of consecutive data sets that it can handle is limited only by the time required for analysis.

The programme takes about seven minutes to complete a full analysis of 4000 directional features using about 80 percent of the first, second, and third level groupings.

Output

The output begins with a copy of the information on the three control cards and this is followed by the original and calculated data values.

The data from this programme is printed in tabular format under the appropriate headings for each table. The tables, in order of output, contain (1) original and corrected individual cross-bed measurements, (2) number and percentage frequency distribution of individual per group, (3) calculated means for groups of beds, (4) calculated means for specified group intervals, and (5) averages per locality. Any of the five tables may be requested with the parameters on Control Card 1 and the tables are printed on separate pages. Examples of headings and data print-outs are given in Table 2. The headings are all largely self explanatory but the following abbreviations have been used.

APPROX	= approximate
ARITH	= arithmetic
AV	= average
CONFID	= confidence
MAGN(IT)	= magnitude
PC	= percent
PRECIS	= precision
PROB	= probability
RAYLE	= Rayleigh
RAY SIG	= Rayleigh significance
STAT	= statistic
STD	= standard deviation (vectorial)
THICK	= thickness
VAR	= variance (vectorial)
VECT(S)	= vector(s)
X	= cross
3D	= three dimensional

TABLE 2 EXAMPLES OF OUTPUT LAYOUT AND HEADINGS.

LOCATION	STRATIGRAPHIC INTERVAL	BEDDING		X-BEDDING		RESULTANT X-BED TREND	RESULTANT X-BED DIP	THICKNESS	OBSERVATIONS		
		DIP	TREND	DIP	TREND				SHAPE	GRAIN	OTHERS
NHARM H8	40	194	77	173	79	112.29	20.63	30.00	0	M=C	
		194	77	181	83	132.87	14.13	50.00	A	M=C	
		194	77	166	75	101.42	27.22	40.00	A	M=C	
		194	77	193	95	202.22	18.03	65.00	0	C	OU
		194	77	175	84	127.71	19.99	25.00	0	M=C	
		194	77	186	90	167.00	15.23	30.00	0	M=C	
		194	77	187	92	224.34	16.53	30.00	A	M=C	RU
		194	77	163	76	103.44	30.14	15.00	0	M=C	RU
		194	77	188	88	170.14	12.50	45.00	0	C	OU
		194	77	197	93	188.25	16.28	50.00	0	C	
		194	77	175	82	122.10	19.33	40.00	0	M=C	RU
		194	77	164	79	109.62	29.40	20.00	A	M=C	
		194	77	170	84	123.22	24.66	35.00	A	M=C	
		196	75	163	74	104.72	31.78	15.00	A	M	
		196	75	175	80	122.25	21.09	25.00	A	M	
NHARM H8	240										

PERCENTAGE FREQUENCY DISTRIBUTION

LOCATION	GROUP INTERVAL	CLASS	0	30	60	90	120	150	180	210	240	270	300	330	360
NHARM H8	40	0.0	0.0	0.0	30.8	30.8	15.4	15.4	7.7	0.0	0.0	0.0	0.0	0.0	0.0
NHARM H8	240	0.0	0.0	0.0	36.4	27.3	9.1	27.3	0.0	0.0	0.0	0.0	0.0	0.0	0.0
NHARM H8	400	0.0	0.0	0.0	12.5	0.0	6.3	12.5	25.0	18.8	25.0	0.0	0.0	0.0	0.0
NHARM H8	600	0.0	0.0	0.0	11.8	17.6	17.6	17.6	0.0	5.9	23.5	5.9	0.0	0.0	0.0
GLENH H9	10	0.0	0.0	0.0	25.0	25.0	0.0	25.0	0.0	25.0	0.0	0.0	0.0	0.0	0.0
GLENH H9	120	0.0	0.0	0.0	9.1	18.2	18.2	9.1	0.0	27.3	18.2	0.0	0.0	0.0	0.0
GLENH H9	140	0.0	0.0	0.0	30.0	20.0	0.0	20.0	20.0	0.0	10.0	0.0	0.0	0.0	0.0
GLENH H9	300	0.0	0.0	0.0	0.0	25.0	12.5	12.5	12.5	12.5	25.0	0.0	0.0	0.0	0.0
GLENH H9	385	0.0	0.0	0.0	22.2	22.2	22.2	11.1	11.1	11.1	0.0	0.0	0.0	0.0	0.0
GLENH H9	700	0.0	0.0	0.0	5.9	11.8	11.8	11.8	5.9	29.4	17.6	5.9	0.0	0.0	0.0
GLENH H9	880	0.0	0.0	0.0	0.0	10.0	20.0	20.0	20.0	20.0	10.0	20.0	0.0	0.0	0.0

NUMBER FREQUENCY DISTRIBUTION

LOCATION	GROUP INTERVAL	CLASS	0	30	60	90	120	150	180	210	240	270	300	330	360
NHARM H8	40	0.0	0.0	0.0	4.0	4.0	2.0	2.0	1.0	0.0	0.0	0.0	0.0	0.0	0.0
NHARM H8	240	0.0	0.0	0.0	4.0	3.0	1.0	3.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
NHARM H8	400	0.0	0.0	0.0	2.0	0.0	1.0	2.0	4.0	3.0	4.0	0.0	0.0	0.0	0.0
NHARM H8	600	0.0	0.0	0.0	2.0	3.0	3.0	3.0	0.0	1.0	4.0	1.0	0.0	0.0	0.0
GLENH H9	10	0.0	0.0	0.0	1.0	1.0	0.0	1.0	0.0	1.0	0.0	0.0	0.0	0.0	0.0
GLENH H9	120	0.0	0.0	0.0	1.0	2.0	2.0	1.0	0.0	3.0	2.0	0.0	0.0	0.0	0.0
GLENH H9	140	0.0	0.0	0.0	3.0	2.0	0.0	2.0	2.0	0.0	1.0	0.0	0.0	0.0	0.0
GLENH H9	300	0.0	0.0	0.0	0.0	2.0	1.0	1.0	1.0	1.0	2.0	0.0	0.0	0.0	0.0
GLENH H9	385	0.0	0.0	0.0	2.0	2.0	2.0	1.0	1.0	1.0	1.0	0.0	0.0	0.0	0.0
GLENH H9	700	0.0	0.0	0.0	1.0	2.0	2.0	2.0	1.0	5.0	3.0	1.0	0.0	0.0	0.0
GLENH H9	880	0.0	0.0	0.0	0.0	1.0	2.0	2.0	2.0	1.0	2.0	0.0	0.0	0.0	0.0

TABLE 2 (cont.)

AVERAGES FOR BEDS IN ONE GROUP INTERVAL

LOCATION	GROUP	BEDS	ARITH TREND	VECT TREND	VECT MAGN	VECT MAGPC	VECT VAR	VECT STD	RAYLE PROB	RAYSIG STAT	AV DIP	AV THICK	3D TREND	3D AVDIP	VECT MAGNIT	CONFID CIRCLE	APPROX PRECIS
NHERM H8	40	13	144.97	142.58	10.21	78.92	1668.6	40.85	8.0156	2.9384	20.31	36.54	143.75	25.25	10.53	21.04	4.85
NHERM H8	240	11	140.95	139.15	8.85	80.47	2517.4	38.95	7.1232	2.9279	20.39	23.00	140.33	24.81	9.09	22.10	5.23
NHERM H8	400	16	222.04	231.75	10.08	63.80	3489.5	58.65	6.3514	2.9491	16.39	39.38	232.52	24.79	10.73	26.94	2.85
NHERM H8	600	17	201.56	194.33	6.64	39.08	5187.7	72.03	2.5965	2.9519	17.53	77.35	195.64	38.79	8.14	39.13	1.81
GLENH H9	10	4	176.63	173.36	1.91	47.72	5461.4	73.90	0.9107	2.8093	16.60	10.75	174.18	32.08	2.14	119.27	1.61
GLENH H9	120	11	203.69	201.79	5.19	47.14	4450.6	66.71	2.4441	2.9279	20.03	22.55	200.03	37.48	6.18	43.31	2.08
GLENH H9	140	10	172.79	166.53	5.57	55.72	8799.4	93.81	3.1048	2.9212	19.82	33.50	165.08	32.43	6.30	39.80	2.43
GLENH H9	300	8	213.14	212.78	4.74	59.21	3419.6	58.48	2.8047	2.9025	18.84	56.88	212.46	29.86	5.18	44.79	2.48
GLENH H9	385	9	162.55	157.84	5.89	65.48	5977.1	77.31	3.8591	2.9129	15.86	63.89	159.05	23.46	6.15	37.89	2.80
GLENH H9	700	17	220.68	230.10	8.40	49.40	4369.3	66.10	4.1481	2.9519	15.68	23.76	229.28	29.64	9.27	34.09	2.07
GLENH H9	880	10	211.22	209.80	6.85	68.50	2567.3	50.67	4.6922	2.9212	17.59	54.00	209.42	24.78	7.20	32.16	3.22

AVERAGES FOR BEDS IN 100 UNIT INTERVALS

LOCATION	100 INTERVAL	AV TREND	MAGNIT	MAGNPC	NO. XBEDS	AV DIP	AV THICK	AV GROUP VECTS	MAGN AGV PC
NHERM H8	0- 99	142.58	10.21	78.92	13	20.31	36.54	142.58	100.00
NHERM H8	200- 299	139.15	8.85	80.47	11	20.39	23.00	139.15	100.00
NHERM H8	400- 499	231.75	10.08	63.80	16	16.39	39.38	231.75	100.00
NHERM H8	600- 699	194.33	6.64	39.08	17	17.53	77.35	194.33	100.00
GLENH H9	0- 99	173.36	1.91	47.72	4	16.60	10.75	173.36	100.00
GLENH H9	100- 199	183.50	10.25	48.82	21	19.93	27.76	184.15	95.31
GLENH H9	300- 399	182.07	9.49	55.57	17	17.26	60.59	185.31	88.72
GLENH H9	700- 799	230.10	8.40	49.40	17	15.68	23.76	230.10	100.00
GLENH H9	800- 899	209.80	6.85	68.50	10	17.59	54.00	209.80	100.00

AVERAGES FOR BEDS IN EACH LOCATION

LOCATION	AV VECT TREND	MAGNIT	MAGNPC	NO XBEDS	AV DIP	AV THICK	AV GROUP VECTS	MAGN AGV PC
NHERM H8	174.94	27.59	48.40	59	18.40	46.89	175.83	78.67
GLENH H9	197.85	34.56	50.09	69	17.69	37.68	193.23	90.55

Subroutines

The programme DIRECT uses the subroutines AZIMUTH and ROTATE (given) and calls on the following standard computer functions SINF, ASINF, COSF, ACOSF, ATANF, and ASQRTF.

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PROGRAM DIRECT
PROGRAMME CROSS-BED ANALYSIS
PROGRAMME TO CORRECT CROSS-BED MEASUREMENTS FOR TECTONIC TILT
AND TO DETERMINE VECTOR MEAN AZIMUTHAL DIRECTIONS AND AVERAGE
CROSS-BED DIP AND THICKNESS FOR EACH STRATIGRAPHIC INTERVAL
THIS PROGRAMME FOLLOWS P.J. COOK (BMR RECORD 1966/1) AND
J. CURRAY, 1956 (J. GEOL. 64, 117)
INPUT TERMINOLOGY
  STRAT = STRATIGRAPHIC INTERVAL, F FORMAT
  LOC   = LOCALITY, A8 FORMAT
  TP    = TREND OF BEDDING DIP, F FORMAT
  P     = DIP OF BEDDING, F FORMAT
  TQ    = TREND OF CROSS-BEDDING DIP, F FORMAT
  Q     = DIP OF CROSS-BED, F FORMAT
  AMAG  = MAGNETIC DEVIATION CORRECTION FACTOR, F FORMAT
  XST   = NUMBER OF CROSS-BED UNITS IN ONE STRATIGRAPHIC INTERVAL
  CS    = COSINE
  TN    = TANGENT
  SN    = SINE
  AF    = FUNCTION FOR EXPRESSING ANGLES IN RADIANS
  STDA  = ARITHMETIC STANDARD DEVIATION OF CROSS-BED TREND
  TAA   = ARITHMETIC MEAN CROSS-BED TREND
  3DTREND = TREND OF RESULTANT SPHERICAL VECTOR (STEINMETZ, 1962)
  3DAVDIP = DIP OF RESULTANT SPHERICAL VECTOR
  W05   = SPHERICAL RADII OF CONFIDENCE CIRCLE ABOUT 3D VECTOR
  OK    = ESTIMATE OF PRECISION FOR F-RATIO (STEINMETZ, 1962, JSP)

  RPP   = MAGNITUDE OF RESULTANT PLANAR VECTOR - POTTER & PETTIJOHN
  LPP   = PLANAR VECTOR MAGNITUDE IN PERCENT                      1963
  SUBSCRIPT 0 = ORIGINAL
  SUBSCRIPT 1 = RESULTANT
  SUBSCRIPT A = AVERAGE
  SUBSCRIPT I = 100M INTERVAL
  SUBSCRIPT T = LOCALITY INTERVAL

  GRAIN = GRAIN SIZE, FREE A5 FORMAT, NOT AVERAGE
  SHAPE = SHAPE OF CROSS-BED (ALLEN, 1963), FREE A5 FORMAT
  OTHERS = FREE A8 FORMAT
  THK    = THICKNESS OF CROSS-BED UNIT, F FORMAT, AVERAGE CALCULATED
  THE ABOVE 4 PARAMETERS MAY BE USED FOR ANY INFORMATION UNDER THE
  NOTED FORMATS BUT THE OUTPUT IS UNDER THESE HEADINGS IN STATEMENTS
  70,840,880,920

  NOTE WHEN Q0 = 0  PJT TQ0 = TPO

  INTEGER E,G,LOC,LOC1,TLOC,SLOC,ALOC
31  DIMENSION TLOC(375),STR(375),QA(375),TH(375),TAA(375),VAR(375),
    1TA(375),RPP(375),OLPP(375),TSQ(375),TSQD(375),R(375),W05(375),
    20K(375),TXS(375),VSD(375),RAY(375),Z(375)
33  DIMENSION SLOC(250),VA(250),NB(250),XSI(250),TI(250),QI(250),
    1PQI(250),PPI(250),TKI(250),AVL(250),AVR(250)
35  DIMENSION ALOC(100),TUTT(100),TUX(100),RTOT(100),OLT(100),
    1TTQA(100),TTKA(100),ALR(100),ALL(100)
37  DIMENSION V(375,12),X(12),TV(200),FMT(10),TITLE(10)

    PI = 3.1416
    HPI = 1.5708
    HPI3 = 4.7124
    PI2 = 6.2832
    ZP = 2.99573
    ZQ = -0.74574
    AF = PI/180.
38  LOC=STRAT=J=K=L=JJ=0.
    READ 10, IA,IB,IC,ID,IE,IG,IP,AMAG
10  FORMAT(7I5,F9.1)
    IF (IA.EQ.2) GO TO 945
    READ 20,FMT

```

```

20  FORMAT(10A8)
    READ 30, TITLE
30  FORMAT(10A8)
39  PRINT 40, TITLE,FMT,IA,IG,IC,IO,IE,IG,IP,AMAG
40  FORMAT(1H1* CROSS-BED PROGRAMME - B,G;JONES, 1970*/10A8/10A8/715
    1,F5.1)
    PRINT 50, TITLE
50  FORMAT(1H1///30X*PROGRAMME TO CORRECT CROSS-BED MEASUREMENT FOR TE
    1CTONIC TILT*//20X10A8/////))
    IF (IA) 60,80
60  PRINT 70
70  FORMAT(* LOCATION STRATIGRAPHIC BEDDING BEDDING X-BEDDING X-BED
    1DING RESULTANT RESULTANT THICKNESS OBSERVATIONS*/
    213X*INTERVAL DIP TREND DIP DIP TREND DIP*
    3* X-BED TREND X-BED DIP SHAPE GRAIN OTHERS*/)
80  READ FMT, LOC1,STRAT1,TPO,PO,E,T00,Q0,Q,THICK,SHAPE,GRAIN,OTHERS
81  IF (LOC1.EQ.LOC) GO TO 90
    IF (LOC.EQ.0,) GO TO 365
    GO TO 100
90  IF (STRAT1.EQ.STRAT) GO TO 402

```

C
C COMPUTING VECTOR MEAN AND AVERAGE THICKNESS AND DIP
C

```

100  TOXX = TOXX+XST
    TOTS = TOTS+SNQT
    TOTC = TOTC+CSQT
    SNI = SNI+SNQT
    CSI = CSI+CSQT
    TTK = TTK+THKT
    TTQ = TTQ+QT
    THKI = THKI+THKT
    QII = QII+QT
    XSII = XSII+XST
    JJ = JJ+1
    DO 105KK=1,12
105  V(JJ,KK) = X(KK)
    IF (IB) 108,250

```

C
C AVERAGING OF STRATIGRAPHIC GROURS
C

```

108  K = K+1
    TXS(K)= XST
    QA(K) = QT/XST
    TH(K) = THKT/XST
    IF (XSQ.EQ.0,) GO TO 110
    ATQ = STQ/XSQ
110  IF (XSP.EQ.0,) GO TO 120
    ATP = STP/XSP
120  XPQ = ATP-ATQ
    IF (XPQ.LT.180,) GO TO 130
    ATQ = ATQ+360.
    TAA(K)=(ATQ*XSQ+ATP*XSP)/(XSQ+XSP)
    IF (TAA(K).LT.360,) GO TO 140
    TAA(K)= TAA(K)-360.
    GO TO 140
130  TAA(K)= (STQ+STP)/(XSP+XSQ)
140  SNQT2= SNQT*SNQT
    CSQT2= CSQT*CSQT
    RPP(K)= SQRTF(SNQT2+CSQT2)
    OLPP(K)= RPP(K)*100./XST
    TSAB2= TSAB*TSAB
    TCAB2= TCAB*TCAB
    TSB2 = TSB*TSB
    R(K) = SQRTF(TSAB2+TCAB2+TSB2)
    ONR = XST-R(K)
    TSQ(K) = ATANF(TSAB/TCAB)/AF
    TSD = TSB/R(K)
    TSQD(K) = ASINF(TSD)/AF

```

```

IF (XST.LT.3.) GO TO 150
XQ = 1./(XST-1.)
YQ = 20.**XQ-1.
CSW05 = 1.-ONR*YQ/R(K)
IF (ABS(CSW05).GT.1.) GO TO 150
W05(K) = ACOSF(CSW05)/AF
GO TO 160
150 W05(K) = (BH
160 OK(K) = (XST-1.)/ONR
TA(K) = ATANF(SNQT/CSQT)/AF
CALL ROTATE (TA(K),SNQT,CSQT)
NXST = XST
DO 230 IT=1,NXST
TZ = ABSF(TA(K)-TV(IT))
IF (TZ.LE.180.) GO TO 220
TZ = TZ-360.
220 TTV = TTV+TZ*TZ
230 CONTINUE
VAR(K) = TTV/(XST-1.)
VSD(K) = SQRTF(VAR(K))
CALL ROTATE (TSQ(K),TSA0,TCAB)
TLOC(K) = LOC
STR(K) = STRAT
AB = TA(K)*AF
AA1 = AA1+SINF(AB)
AA4 = AA4+SINF(AB)
AA2 = AA2+COSF(AB)
AA5 = AA5+COSF(AB)
AA3 = AA3+1.
AA6 = AA6+1.
RAY(K) = (RPP(K)**2)/XST
Z(K) = ZP+ZQ/XST

IF (IG.NE.2) GO TO 250
240 TA(K) = TA(K)/2.
VAR(K) = VAR(K)/4.
VSD(K) = VSD(K)/2.
TSQ(K) = TSQ(K)/2.
250 IF (IC) 260,310
C
C AVERAGES FOR 100 UNIT INTERVALS
C
260 II = STRAT1/IP
IF (LOC1.NE.LOC) GO TO 265
IF (II.EQ.I) GO TO 390
265 J = J+1
NA(J) = I*IP
NB(J) = NA(J)+IP-1
I = II
TI(J) = ATANF(SNI/CSI)/AF
OI(J) = OII/XSII
TKI(J) = TKI/XSII
POI(J) = SORTF(SNI*SNI+CSI*CSI)
PPI(J) = POI(J)*100./XSII
XSI(J) = XSII
SLOC(J) = LOC
CALL ROTATE (TI(J),SNI,CSI)
IF (IB) 270,280
270 AVLL = SQRTF(AA1*AA1+AA2*AA2)
AVL(J) = AVLL*100./AA3
AVR(J) = ATANF(AA1/AA2)/AF
CALL ROTATE (AVR(J),AA1,AA2)
GO TO 300
280 AVL(J) = AVR(J)=0.
300 IF (IG.NE.2) GO TO 310
TI(J) = TI(J)/2.
AVR(J) = AVR(J)/2.
310 IF (ID) 320,380

```

C
C
C

LOCALITY AVERAGES

```

320 IF (LOC1, EQ, LOC) GO TO 380
    L = L+1
    TTOA(L) = TTO/TOXX
    TTKA(L) = TTK/TOXX
    TOX(L) = TOXX
    ALOC(L) = LOC
    TS2 = TOTS*TOTS
    TC2 = TOTC*TOTC
    RTOT(L) = SQRTF(TS2+TC2)
    OLT(L) = RTOT(L)*100./TOXX
    TOTT(L) = ATANF(TOTS/TOTC)/AF
    CALL ROTATE (TOTT(L), TOTS, TOTC)
    IF (IB) 340, 350
340 ALLT = SQRTF(AA5*AA5+AA4*AA4)
    ALL(L) = ALLT*100./AA6
    ALR(L) = (ATANF(AA4/AA5))/AF
    CALL ROTATE (ALR(L), AA4, AA5)
    GO TO 360
350 ALL(L) = ALR(L)*0.
360 IF (IG, NE, 2) GO TO 370
    TOTT(L) = TOTT(L)/2.
    ALR(L) = ALR(L)/2.
    GO TO 370

```

C
C
C

END OF AVERAGES

```

365 I = STRAT1/IP
370 TOTS=TOTC=TTK=TTQ=TOXX=AA4=AA5=AA6=0.
380 SNI=CSI=THKI=XSII=QII=AA1=AA2=AA3=TTV=0.
390 IF (LOC1, EQ, 8H ) GO TO 750
    LOC = LOC1
    STRAT = STRAT1
    XST=THKT=QT=TSAB=TCAB=TSB=SNQT=CSQT=STQ=XSQ=STP=XSP=ATP=ATQ=0
    SDP=SDQ=Y=0.
    DO 391 M=1, 12
391 X(M) = 0.
402 IF (IG) 685, 403
403 IF (E, EQ, 608) GO TO 404
    CALL AZIMUTH (E, TPQ, ZZ)
    IF (ZZ) 80, 404
404 IF (G, EQ, 608) GO TO 405
    CALL AZIMUTH (G, TQO, ZZ)
    IF (ZZ) 80, 405

```

C
C
C

CORRECTION FOR X-BED AZIMUTH AND DIP

```

405 XST = XST+1.
    TP = TPQ+AMAG
    TQ1 = TQO+AMAG
    TPQ = TP-TQ1

```

C
C
C

CORRECTION FOR TILT IF TRENDS 180 APART OR EQUAL

```

    IF (ABS(TPQ), NE, 180.) GO TO 410
    Q1 = QO+PO
    GO TO 630
410 IF (TPQ, NE, 0.) GO TO 420
    Q1 = QO-PO
    IF (Q1, GT, 0.) GO TO 630
    Q1 = -Q1
    TQ1 = TQ1+180.
    IF (TQ1, LT, 360.) GO TO 630
    TQ1 = TQ1-360.
    GO TO 630

```

C
C NORMAL BEDDING PLANES HORIZONTAL

C
420 P = (90,-P0)*AF
SNP = SIN(P)
IF (SNP,NE,1,) GO TO 425
Q1 = Q0
GO TO 630

C
C NORMAL TILT CORRECTIONS

C CONVERTING TREND AND DIP READINGS TO LOWER HEMISPHERE

C
425 IF (TP,LT,180) GO TO 430
TP = TP-180.
GO TO 440
430 TP = TP+180.
440 IF (TQ1,LT,180) GO TO 450
TQ1 = TQ1-180.
GO TO 460
450 TQ1 = TQ1+180.

C
C INCLINED BEDDING PLANES

C
460 CSP = COSF(P)
Q = (90,-Q0)*AF
TP = TP*AF
TQ = TQ1*AF
SNQ = SIN(Q)
CSQ = COSF(Q)
T = TQ-TP
S1=S2=S3=0.
IF (T,GE,0) GO TO 480
T = T+PI2
480 S1 = T
IF (0,GE,0) GO TO 500
IF ((S1,GT,HP13),OR,(S1,LT,HP13)) GO TO 490
GO TO 500
490 SNQ = -SNQ
CSQ = -CSQ
500 IF (PI,GE,T) GO TO 510
T = PI2-T
510 CST = COSF(T)

C
C DIP CORRECTION FACTOR

C
SNQ1 = SNP*SNQ + CSP*CSQ*CST
IF (0,GE,0) GO TO 530
S2 = PI
IF (SNQ1,LT,0) GO TO 520
SNQ = -SNQ
GO TO 530
520 SNQ1 = -SNQ1
530 Q1 = ASINF(SNQ1)
CSQ1 = COSF(Q1)

C
C CORRECTION FOR TREND DIRECTION

C
IF (S2,GE,PI) GO TO 540
FN = SNQ-(SNP*SNQ1)
IF (FN,GE,0) GO TO 550
FN = -FN
S3 = PI
GO TO 550
540 FN = SNQ+(SNP*SNQ1)
550 CSZ = FN/(CSP*CSQ1)
W = ASINF(CSZ)

```

      IF (S3.GE.PI) GO TO 560
      T1 = HPI+W
      GO TO 570
560   T1 = HPI-W
570   IF (S1.LT.PI) GO TO 580
      T1 = PI2-T1
580   TQ1 = T1+TP+S2
      IF (PI2.GE.TQ1) GO TO 590
      TQ1 = TQ1-PI2
590   Q1 = Q1/AF
      TQ1 = TQ1/AF
C
C REVERSE OF STEPS 420 TO 460 RETURNING READINGS TO UPPER HEMISPHERE
C
      IF (Q1.LT.0.) GO TO 620
      IF (TQ1.GT.180.) GO TO 600
      TQ1 = TQ1+180.
      GO TO 610
600   TQ1 = TQ1-180.
610   Q1 = 90.-Q1
      GO TO 630
620   Q1 = -Q1
630   IF (IA) 640,690
640   IF (XST.GT.1.) GO TO 660
      PRINT 650, LOC1,STRAT1,TPO,PO,TQ0,Q0,TQ1,Q1,THICK,SHAPE,GRAIN,OTHE
1RS
650   FORMAT(1H ,1X,A8,F10.0,4X,2F8.0,F9.0,F10.0,2F12.2,F10.2,4X,3A8)
      GO TO 680
660   PRINT 670, TPO,PO,TQ0,Q0,TQ1,Q1,THICK,SHAPE,GRAIN,OTHERS
670   FORMAT(1H ,23X,2F8.0,F9.0,F10.0,2F12.2,F10.2,4X,3A8)
680   IF (IB.EQ.0.AND.IC.EQ.0.AND.ID.EQ.0.AND.IE.EQ.0.AND.IG.EQ.0) GO TO
1 80
      GO TO 690
685   Q1 = Q0
      XST = XST+1.
      IF (IG.EQ.1) GO TO 687
      IF (TQ0.LT.180.) GO TO 686
      TQ0 = TQ0-180.
686   TQ1 = TQ0*2
      GO TO 690
687   TQ1 = TQ0
C
C DATA FOR AVERAGES
C
690   IF (TQ1.GE.180.) GO TO 700
      XSQ = XSQ+1.
      STQ = STQ+TQ1
      GO TO 710
700   XSP = XSP+1.
      STP = STP+TQ1
710   TV(XST)= TQ1
      TQ2 = TQ1*AF
      SNTQ1= SIN(TQ2)
      CSTQ1= COS(TQ2)
      THKT = THKT+THICK
      QT = QT+Q1
      SNQT = SNQT+SNTQ1
      CSQT = CSQT+CSTQ1
      Q1 = Q1*AF
      CB = COS(Q1)
      TSAB = TSAB+SNTQ1*CB
      TCAB = TCAB+CSTQ1*CB
      TSB = TSB+SIN(Q1)
      IF (IE) 720,80
720   MI = (TQ1+30.)/30.
      X(MI)= X(MI)+1
      GO TO 80

```

```

C
C      PRINT OUTS
C
750  IF (IE) 760,820
760  PRINT 770
770  FORMAT(1H1//45X*NUMBER FREQUENCY DISTRIBUTION*///* LOCATION GROU
1P INTERVAL CLASS 0 30 60 90 120 150 180 2
210 240 270 300 330 360*/)
DO 790 JK=1,JJ
PRINT 780, (TLOC(JK),STR(JK),(V(JK,KK),KK=1,12))
780  FORMAT(1H ,R8,F12.0,15X,4F6,1,8F7,1)
790  CONTINUE
PRINT 800
800  FORMAT(1H1//43X*PERCENTAGE FREQUENCY DISTRIBUTION*///* LOCATION
1 GROUP INTERVAL CLASS 0 30 60 90 120 150 180
2 210 240 270 300 330 360*/)
DO 810 JK=1,JJ
Y = 0.
DO 805 KK=1,12
805  Y = Y+V(JK,KK)
DO 806 KK=1,12
806  V(JK,KK) =V(JK,KK)*100./Y
PRINT 780, (TLOC(JK),STR(JK),(V(JK,KK),KK=1,12))
810  CONTINUE
820  IF (IB) 830,860
830  PRINT 840
840  FORMAT(1H1//36X*AVERAGES FOR BEDS IN ONE GROUP INTERVAL*
1//* LOCATION GROUP BEDS ARITH VECT VECT VECT VECT R
2AYLE RAYSIG AV AV 3D 3D VECT CONFID APPROX*/
323X*TREND TREND MAGN MAGPC VAR STD PROB STAT DIP TH
4ICK TREND AVDIP MAGNIT CIRCLE PRECIS*/7
PRINT 850,(TLOC(M),STR(M),TXS(M),TAA(M),TA(M),RPP(M),OLPP(M),VAR(M
1),VSD(M),RAY(M),Z(M),QA(M),TH(M),TSQ(M),TSQD(M),R(M),WDS(M),OK(M),
2 M=1,K)
850  FORMAT(1H ,R8,F6.0,F5.0,1X,2F7.2,2F6+2,F8,1,F6.2,2F7.4,F6.2,2F7.2,
1F6.2,3F7.2)
IF (IB.NE.2) GO TO 860
PUNCH 845, (TLOC(M),STR(M),TA(M),QA(M),TH(M), M=1,K)
845  FORMAT(A8,F7.0,19X,2F5.1,F10.2)
860  IF (IC) 870,900
870  PRINT 880, 1P,1P
880  FORMAT(1H1//13X*AVERAGES FOR BEDS IN*15* UNIT INTERVALS*///* LOCAT
1ION *15 * INTERVAL AV TREND MAGNIT MAGNPC NO,XBEDS AV D
2IP AV THICK AV GROUP VECTS MAGN AGV PC*/)
PRINT 890,(SLOC(M),NA(M),NB(M),TI(M),POI(M),PPI(M),XSI(M),QI(M),
1TKI(M),AVR(M),AVL(M),M=1,J)
890  FORMAT(1H ,1XR8,I8,***14,F12.2,F11.2, F9.2,F8.0,F12.2,F10.2,
12F14.2)
900  IF (ID) 910,940
910  PRINT 920
920  FORMAT(1H1//22X*AVERAGES FOR BEDS IN EACH LOCATION*///* LOCATION
1 AV VECT TREND MAGNIT MAGNPC NO XBEDS AV DIP AV THICK
2AV GROUP VECTS MAGN AGV PC*/)
PRINT 930,(ALOC(M),TOTT(M),RTOT(M),OLT(M),TOX(M),TTQA(M),TTKA(M)
1,ALR(M),ALL(M), M=1,L)
930  FORMAT(1H ,1XR8,F12.2,F13.2,F9.2,F8.0,F12.2,F10.2,2F14.2)
C
940  GO TO 38
945  PRINT 950
950  FORMAT(1H1)
END

```

```

SUBROUTINE AZIMUTH (G,TPO,ZZ)
C
C CORRECTION FOR X-BED STRIKE AND DIP
C
  INTEGER G
  IF (G.NE.8H00000000N) GO TO 392
  IF (TPO.EQ.0.) GO TO 400
  IF (TPO-180.) 396,400,395
392 IF (G.NE.8H00000000S) GO TO 393
  IF (TPO.EQ.0.) GO TO 400
  IF (TPO-180.) 395,400,396
393 IF (G.NE.8H00000000E) GO TO 394
  IF (TPO.LT.90)OR.(TPO.GT.270.) GO TO 395
  IF (TPO.EQ.90)OR.(TPO.EQ.270.) GO TO 400
  GO TO 396
394 IF (TPO.LT.90)OR.(TPO.GT.270.) GO TO 396
  IF (TPO.EQ.90)OR.(TPO.EQ.270.) GO TO 400
395 TPO = TPO+90.
  GO TO 397
396 TPO = TPO-90.
397 IF (TPO.GE.0.) GO TO 398
  TPO = TPO+360
  GO TO 399
398 IF (TPO.LT.360) GO TO 399
  TPO = TPO-360.
399 ZZ = 0.
  GO TO 401
400 ZZ = 1.
401 RETURN
  END

SUBROUTINE ROTATE (T,S,C)
C
  IF (T.NE.0.) GO TO 961
  IF (C.LT.0.) GO TO 960
  T = 0.
  GO TO 964
960 T = 180.
  GO TO 964
961 IF (T.GE.0.) GO TO 962
  IF (S.GE.0.) GO TO 963
  T = T+360.
  GO TO 964
962 IF (S.GE.0.) GO TO 964
963 T = T+180.
964 RETURN
  END
```