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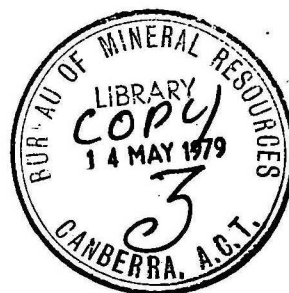


**DEPARTMENT OF
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**INTERPRETATION OF TRANSIENT ELECTROMAGNETIC
MEASUREMENTS USING THE APPARENT CONDUCTIVITY CONCEPT**

by

B.R. Spies

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SUMMARY

Interpretation of transient electromagnetic (TEM) results usually involves comparing the amplitude of the response at various sample times and rules of thumb to gain semi-quantitative information on the source of an anomaly.

Conversion of TEM results into apparent conductivity curves is possible using graphical or computer techniques. TEM data in this form are more amenable to quantitative interpretation. Apparent conductivity is a function of many factors such as sample time, depth of burial, size and conductivity of the body, and loop size.

TEM methods can be used for depth soundings if measurements are made over a suitable time range. TEM depth soundings promise to be much faster than conventional resistivity sounding methods.

The computation of apparent conductivity curves for various numerical and scale models, supported by field results, shows that this method can assist in discriminating between surficial and bedrock conductors and in estimating the true conductivity of some sources.

1. INTRODUCTION

Electromagnetic (EM) methods have been used for over fifty years to search for conductive mineral deposits, assist geological mapping, and make depth soundings.

Most of the EM methods employed to date have operated in the frequency domain. To assist interpretation of frequency domain surveys many papers have been published, particularly in USA and USSR, on the interaction of harmonic electromagnetic fields with conductivity structures. Extensive numerical tables for use in compiling theoretical curves for sounding of horizontally layered structures with frequency domain methods have been published by Frischknecht (1967) and Vanyan et al. (1967).

Although transient EM (TEM) methods were first used in the 1930s, the routine use of TEM in prospecting, mapping, and sounding became common only in the 1970s. Reasons for the delay in the development of TEM methods include problems associated with instrumentation and interpretation. Although TEM fields have been studied since the 1930s, the formulation of the response of TEM systems to even simple conductive structures has proved to be a very difficult problem. However, the advent of cheap and powerful computational techniques such as described in Lee & Lewis (1974) now permits analytical and numerical studies of the response of simple TEM systems to be made. These studies of TEM responses are now leading to the sort of interpretation guidelines that have been available for frequency domain methods for many years.

A particular result of the ability to calculate the response of TEM methods to conductive structures has been the expression of TEM results in the form of an apparent conductivity parameter. Apparent conductivity can provide an insight into the nature of conductivity structures and is therefore a useful aid in the quantitative interpretation of TEM surveys.

2. THE TEM METHOD

The first use of electrical transients in geophysics was in the Eltran method which was based on a patent by Blau (1933). The Eltran method generated transient electromagnetic fields by exciting a grounded dipole with a current pulse. The transient field was detected with an electric dipole in line with the current dipole.

More recent transient systems utilising inductive techniques include the airborne INPUT system and the Russian built MPP0-1 system.

The INPUT system uses a towed receiving coil to detect the transient EM field excited by a large transmitter loop driven by a half-sinusoidal current pulse. The MPP0-1 is a ground prospecting instrument in which a single loop is excited by a square current pulse and is used to detect the transient EM field.

Recently a number of sophisticated TEM systems have become available and offer multiple loop configurations, variable excitation pulses, and, most importantly, very significant noise rejection capabilities (Buselli, 1974; Crone, 1976; Lamontage & West, 1973).

The single-loop method

The single-loop TEM method has been the most common TEM method used in Australia to prospect for subsurface conducting mineral deposits. The method measures the time rate of decay of eddy currents induced in subsurface conductors by the collapse of a magnetic field created by a rectangular current pulse in an insulated loop of wire on the ground. The same loop of wire is used for creating the magnetic field and for measuring the decay of eddy currents between current pulses.

The decaying eddy currents produce in the loop a time-dependent emf $e(t)$ which is measured by the receiver at various sample times (delay times) of from $\frac{1}{2}$ ms to 100 ms. To improve the accuracy of readings, measurements are averaged over several hundred cycles and special filters are used to reduce noise. Loop size is variable, but square loops with side lengths of from 50 to 200 m are commonly used.

The MPP0-1 single-loop TEM system is described by Velikin & Bulgakov (1967), and examples of field and model studies with this system are described by Spies (1976a). A modern single-loop TEM system is described by Buselli & O'Neill (1977).

3. CALCULATION OF APPARENT CONDUCTIVITY

The amplitude of a transient decay curve depends on the loop size. Hence analysis of TEM data would be simplified if the results were in a form which is independent of geometry (or loop size). In the resistivity method, measurements are normalised for the array size by utilising a geometric factor to convert V/I readings to apparent resistivity values. An analogous process can be applied to TEM data.

Apparent resistivity (ρ_a) is defined as the ground resistivity calculated from measurements and a theoretical geometric factor derived for the case where the ground is homogeneous. For the resistivity method, ρ_a is a linear ratio of measured voltage V to applied current I , with a proportionality constant (the geometric factor) which depends on the electrode array. In resistivity soundings the dimensions of the array are expanded and apparent resistivity is calculated as a function of distance.

For electromagnetic methods, calculations of apparent conductivity (σ_a) are performed in the same way as in resistivity methods, but the proportionality constant is usually a more complex expression. The main difference is that apparent conductivity is usually calculated as a function of frequency or time.

In 1969 Morrison et al. introduced the concept of apparent conductivity when describing results from numerical computation of TEM fields from a finite loop over a layered half-space for a source/receiver configuration representative of an airborne system. Lee & Lewis (1974) and Lee (1977) derived expressions for calculating the response of a large loop on a layered ground. From these two papers exact values of the TEM response of a homogeneous half-space can be easily calculated for a wide range of loop sizes, conductivity, and time.

The TEM response of a homogeneous half-space of conductivity is given by Lee & Lewis (1974) as

$$\frac{e(t)}{I} = \frac{-2b\mu\sqrt{\pi}}{t} \cdot F\left(\frac{t}{\sigma\mu b^2}\right) \dots\dots\dots(1)$$

where b = loop radius

μ = magnetic permeability

t = time.

when using a square loop of side d , the expression $b = d/\sqrt{\pi}$ is used. Equation (1) cannot be easily calculated for small values of $t/\sigma\mu b^2$ and is valid only for values of $t/\sigma\mu b^2$ between 0.01 and 30.

In a more recent paper, Lee (1977) gives expressions from which the function $F(t/\sigma\mu b^2)$ can be calculated exactly for values of $t/\sigma\mu b^2$ greater than 1.6 and a table from which the response can be interpolated for values between 0.01 and 1.6. For values under 0.01 the expression is undefined. In practice

this means that for large loops and extremely conductive ground (e.g. 200 m, 20 S/m) calculations may not be possible over some of the time range normally used in TEM surveys.

The calculation of apparent conductivity from single-loop TEM measurements can be easily made from Lee's paper by the use of a computer. Fortran programs suitable for calculating apparent conductivities on an HP2100 computer are described in Appendix 1. Apparent conductivity calculations can also be made using a program written for a HP-67 calculator described by Spies & Raiche (in prep.).

An alternative method of estimating apparent conductivity involves the use of standard curves on which the field decay curve is drawn at an appropriate scale. If the field decay curve follows the shape of a standard curve, the response may be said to be that of a half-space and the apparent conductivity can be estimated. Alternatively, if the field decay curve crosses the standard curve, the time-varying apparent conductivity can be estimated directly from the graph. The Fortran computer program TEMHF described in Appendix 1 can be used to generate standard curves from an HP2100 computer. Standard curves for the TEM response of a homogeneous ground for square loops of size 200, 100, 50, 25, 12.5, 6.25 and 3.12 m are included as Plates 1, 2, 3, 4, 5, 6, and 7 respectively.

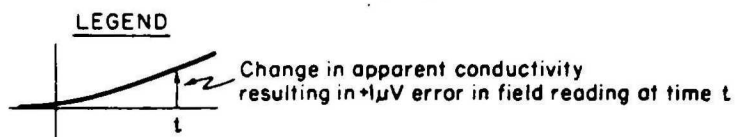
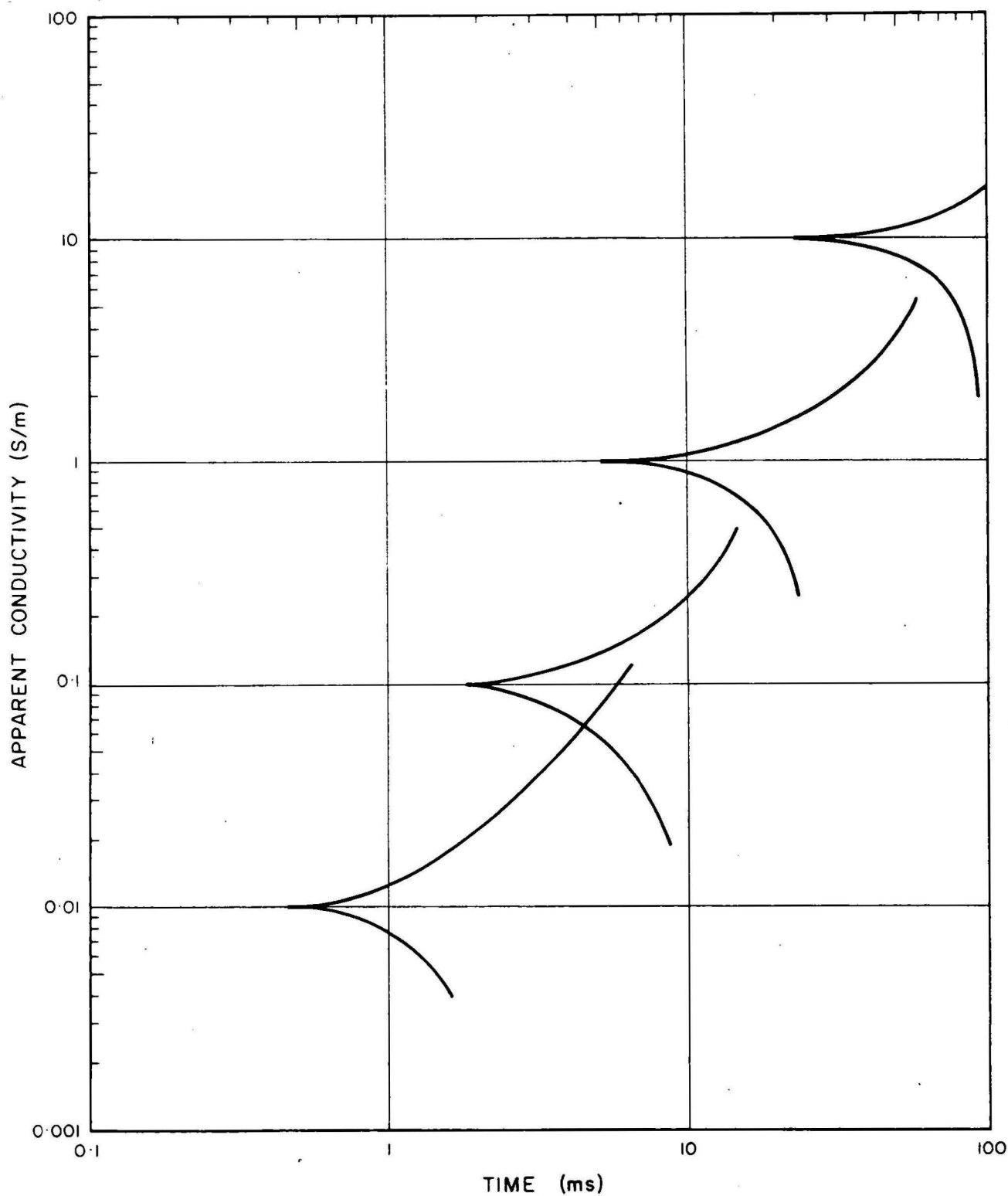
4. PROPAGATION OF ERRORS IN APPARENT CONDUCTIVITY CALCULATIONS

Apparent conductivity is a function of loop size, time, and response. It can easily be shown that errors in apparent conductivity calculations are likely to be greater at late times or for low conductivities because the measured signal, $e(t)/I$, will necessarily be smaller. The main difficulty arises in the measurement of the response at small signal strengths, especially in the microvolt and sub-microvolt range. Recent advances in multi-channel signal-averaging techniques (Buselli, 1974) come a long way in alleviating the problem, and increase the signal-to-noise ratio very considerably. Although it is possible to reduce the noise envelope to less than $0.1 \mu\text{V}$ it is extremely difficult to measure a voltage accurately in the microvolt range with standard amplifiers (the thermal emf of a resistor, for example, is of the order of several microvolts).

A demonstration of the effect of these errors is shown in Figure 1, in which the effect of a measurement error of $\pm 1 \mu\text{V/A}$ is shown on the standard apparent conductivity graph. For early times and large conductivities the

Figure 1

50m LOOP



Errors in apparent conductivity calculations

error is negligible. The error increases substantially at later times and for lower conductivities, and can be extremely large at very late times. For example an apparent conductivity calculation with a 50 m loop over a ground of 0.1 S/m is in error by a factor of 2.4 if the response measured at 10 ms is 1 μ V too high.

5. INTERPRETATION OF DEPTH SOUNDINGS

There are few references on depth sounding using the TEM method, and very few that can be used for interpreting results from the one-loop method. The quantitative interpretation of TEM data is complicated by interference phenomena and the absence of comprehensive numerical and analogue model studies. However, it is possible to use the apparent conductivity concept to qualitatively interpret TEM soundings. The use of the apparent conductivity concept in the interpretation of TEM depth soundings can be illustrated by analysing the results of theoretical, model, and field studies.

Theoretical studies

Lee & Lewis (1974) have calculated the TEM response of a horizontal loop over a layered ground, and found that at short times the response is dominated by the term representing a uniform ground of conductivity equal to the top layer. Morrison et al. (1969) have shown that for an airborne type TEM system, the TEM decay curve asymptotically approaches the curve for a half-space with the conductivity of the bottom layer. The same phenomenon would apply to a ground system at late times.

In a recent paper, Lee (1977) suggested that it is possible to estimate the depth to conductors by the use of electrical transients. This is done by utilising the fact that for plane wave excitation of a half-space of conductivity σ a maximum in the electric field is found at a depth z and time t when $t = z^2 \sigma \mu / 2$. Electrical interfaces in the ground will cause reflections of the primary wave which can be observed in apparent conductivity curves, at times depending on the thickness and conductivity of the upper layers. It was shown that, when using a loop with radius 100 m, the true conductivity of the top layer is approached when $\sigma_1 \mu d^2 / t$ is greater than 0.5, where d is the thickness of the layer.

In calculations of the TEM response of a layered ground, Lee also noted the occurrence of interference effects. In a two-layer case, for instance, these effects can be seen as anomalous apparent conductivity values.

The apparent conductivities are first decreased if the basal layer is a conductor, and are increased if the basal layer is a resistor. These effects have also been observed by Morrison et al. (1969) and Lee & Lewis (1974) when studying more complex sources. Lee & Lewis noted that this may result in the underestimation of the conductivity of the buried layer.

Model studies

The following examples are drawn from scale and numerical model studies of horizontally layered strata, and illustrate the results to be expected when TEM data are converted to apparent conductivity values. Two, three, and four-layer numerical examples are given by Lee & Lewis (1974), and two-layer model study results by Spies (in prep.).

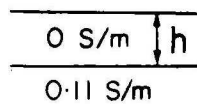
Two-layer cases: The results of scale model studies over two-layered structures are shown in Figures 2 and 3. The scale modelling was carried out using procedures described by Spies (1976b, 1979). The models were constructed of typemetal or graphite, and dimensions were scaled by a factor of 5650.

Figure 2 shows the results over a two-layer case where the top layer has infinite resistivity and the lower layer has a conductivity of 0.11 S/m, for various thicknesses of the top layer. The general trend is for apparent conductivity to increase with time, and to reach the asymptotic value of 0.11 S/m when the top resistive layer is thin. When the layer increases in thickness to 26 m the apparent conductivity at early times has decreased to 0.05 S/m and at late times to 0.1 S/m.

Figure 3 shows the results of several other model studies. Curve 1 is for a 600 m thick bed of 300 ohm-m material underlain by an infinitely resistive layer. The curve departs from the asymptotic value of 0.0033 S/m at early times owing to the effect of the second layer. Curves 2 and 3 are for a 60 m thick layer of 0.11 S/m underlain by a resistive layer (curve 2) and an infinitely resistive layer (curve 3). The effect of the second layer is apparent, and there is almost no difference between the cases of an infinitely resistive and a highly resistive second layer.

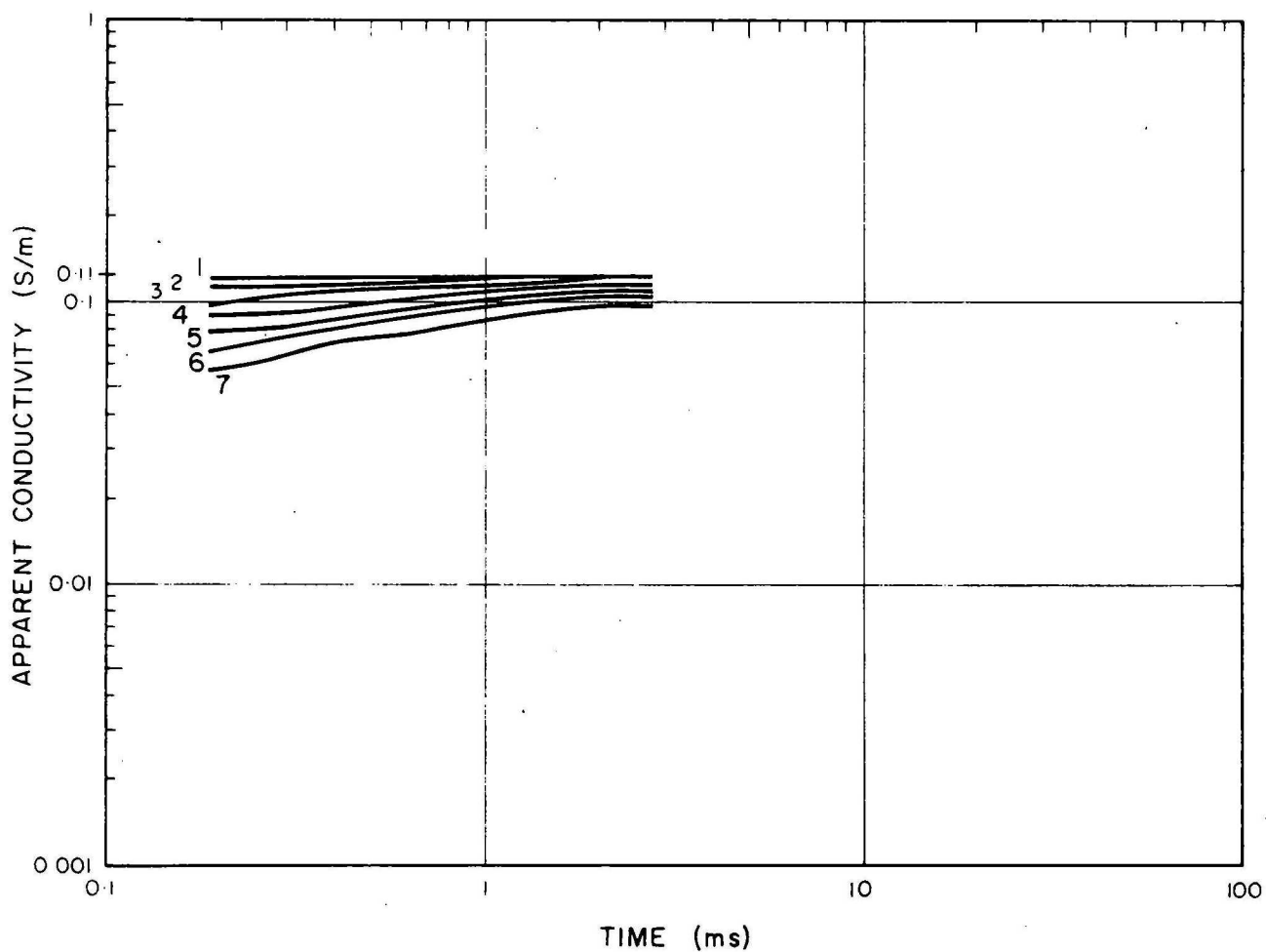
The curves in Figure 4 are taken from numerical results and show the effect of varying the thickness of a layer of conductivity 0.1 S/m overlying a more resistive layer of 0.01 S/m. When the top layer is 200 m thick the curve appears like that from a uniform ground over most of the time range. When the thickness is reduced to 100 m the lower layer is readily visible, and when the thickness is reduced to 10 m the curve almost reaches the true conductivity of the lower layer.

Figure 2



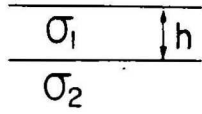
MODEL	1	2	3	4	5	6	7
h (m)	0	4.5	8.2	11.7	15.3	19.8	26

(56m RADIUS LOOP)



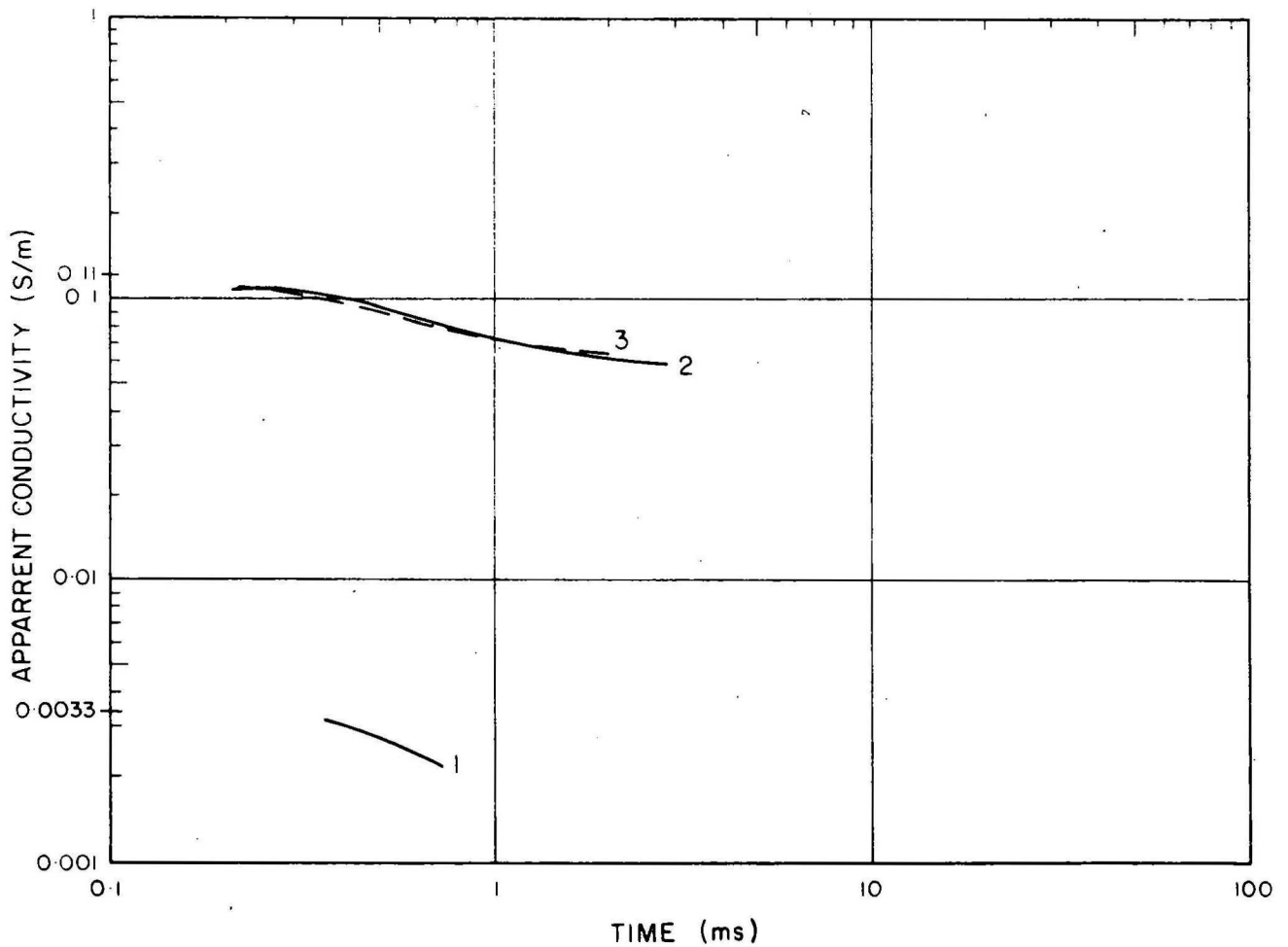
Two-layer case, scale model study

Figure 3



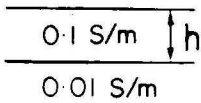
MODEL	1	2	3
σ_1 S/m	0.0033	0.11	0.11
σ_2 S/m	0	0.0033	0
h (m)	600	60	60

(100m SQUARE LOOP)



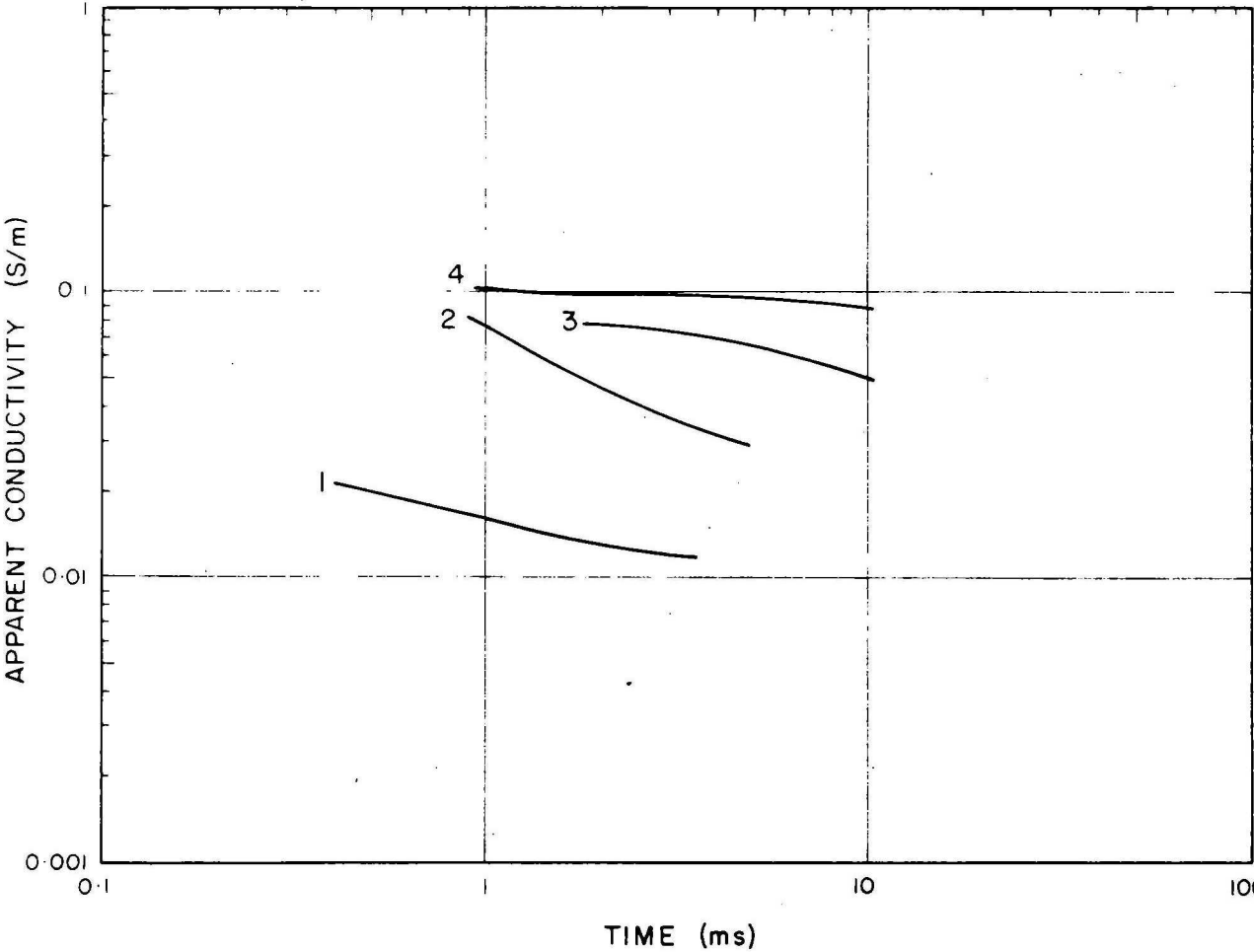
Two-layer case, scale model study

Figure 4



MODEL	1	2	3	4
$h \text{ (m)}$	10	50	100	200

(100m RADIUS LOOP)



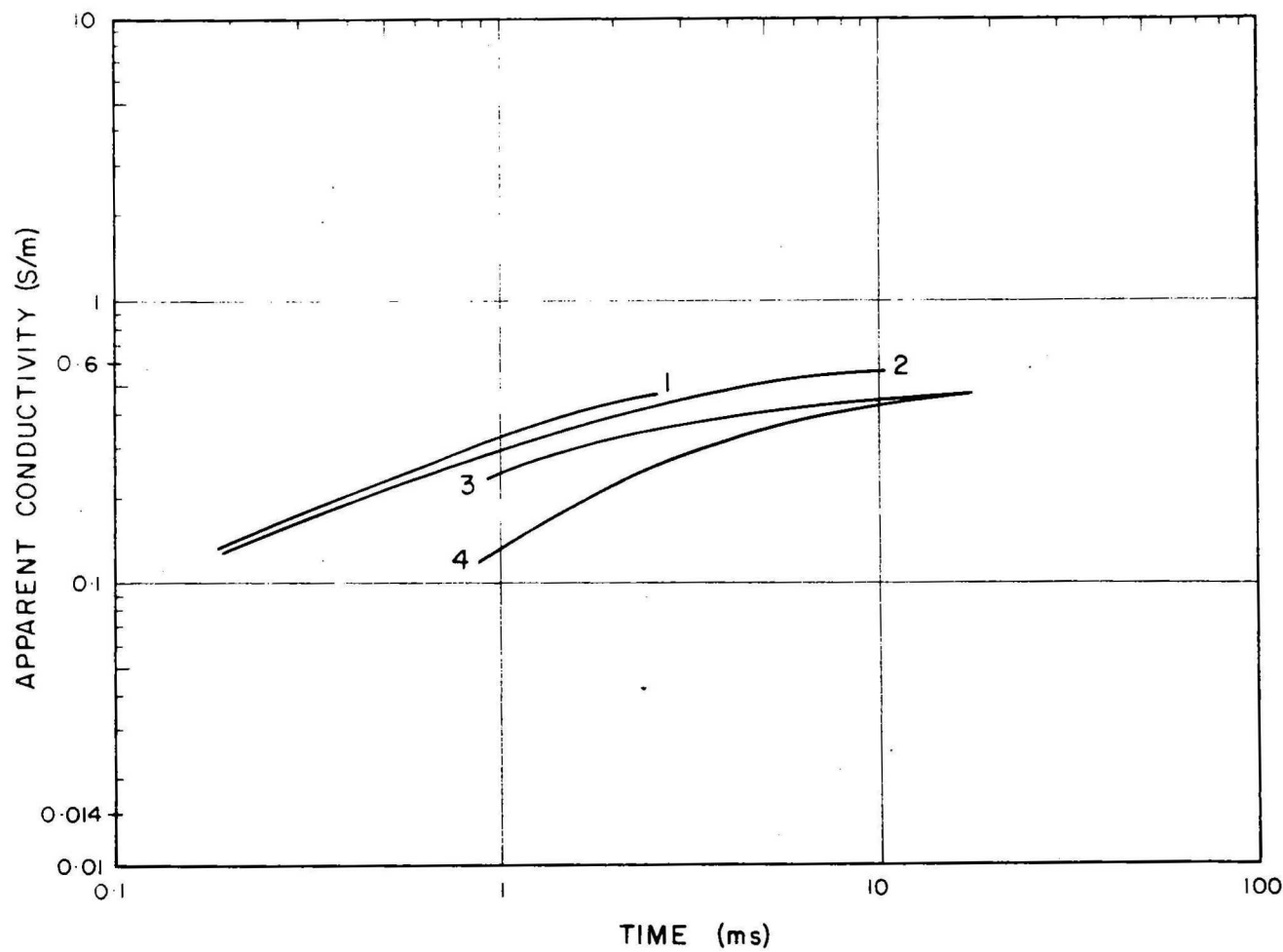
Two-layer case, numerical results

Figure 5

GEO-ELECTRIC SECTION

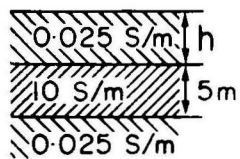
	0 m
0.048 S/m	20 m
0.60 S/m	300 m
0.014 S/m	

CURVE	1	2	3	4
LOOP RADIUS (m)	25	50	100	300



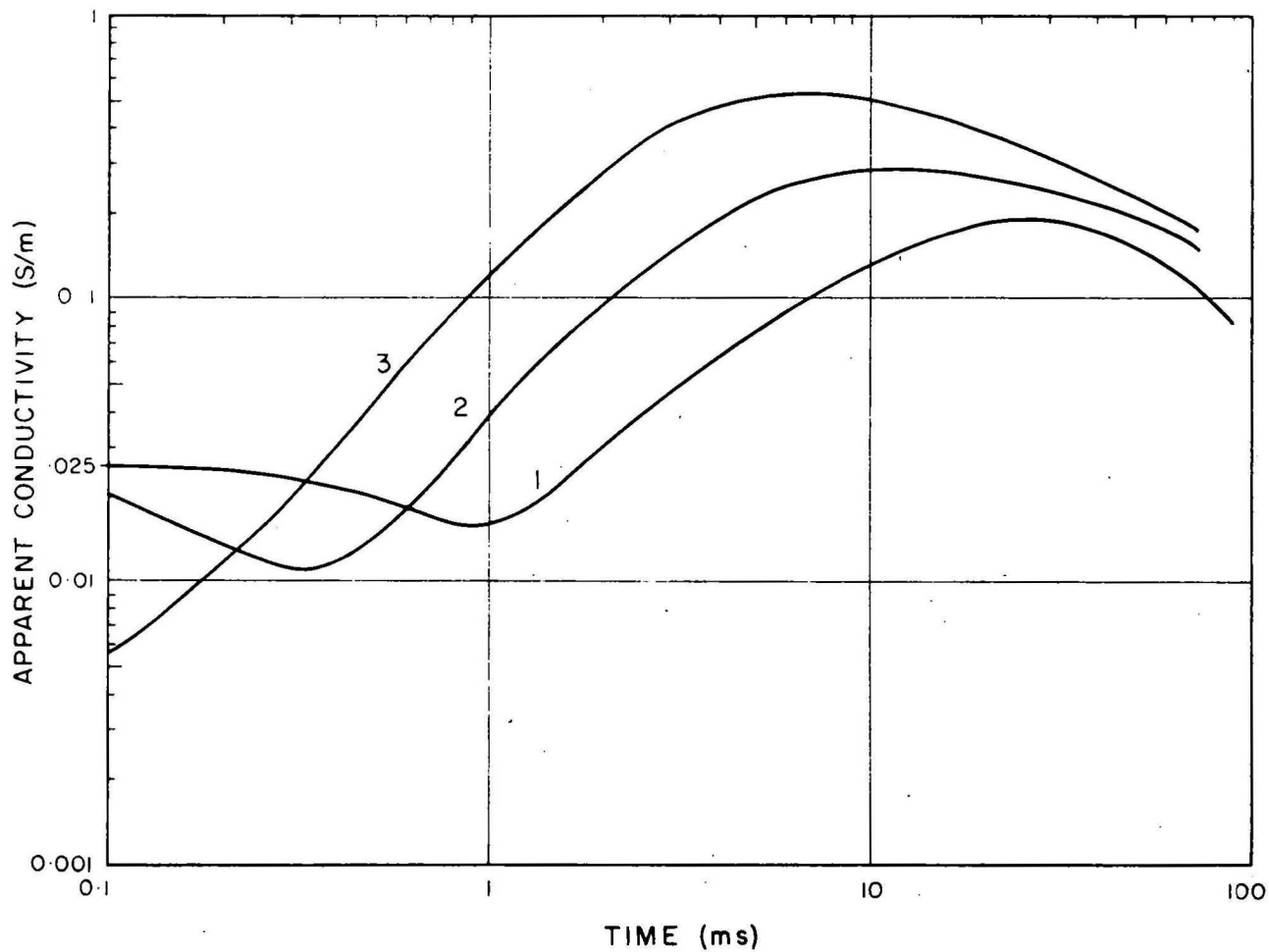
Three-layer case, numerical results

Figure 6



MODEL	1	2	3
$h \text{ (m)}$	200	100	50

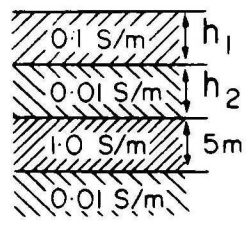
(100m RADIUS LOOP)



FROM LEE & LEWIS (1974) AND LEE (1977)

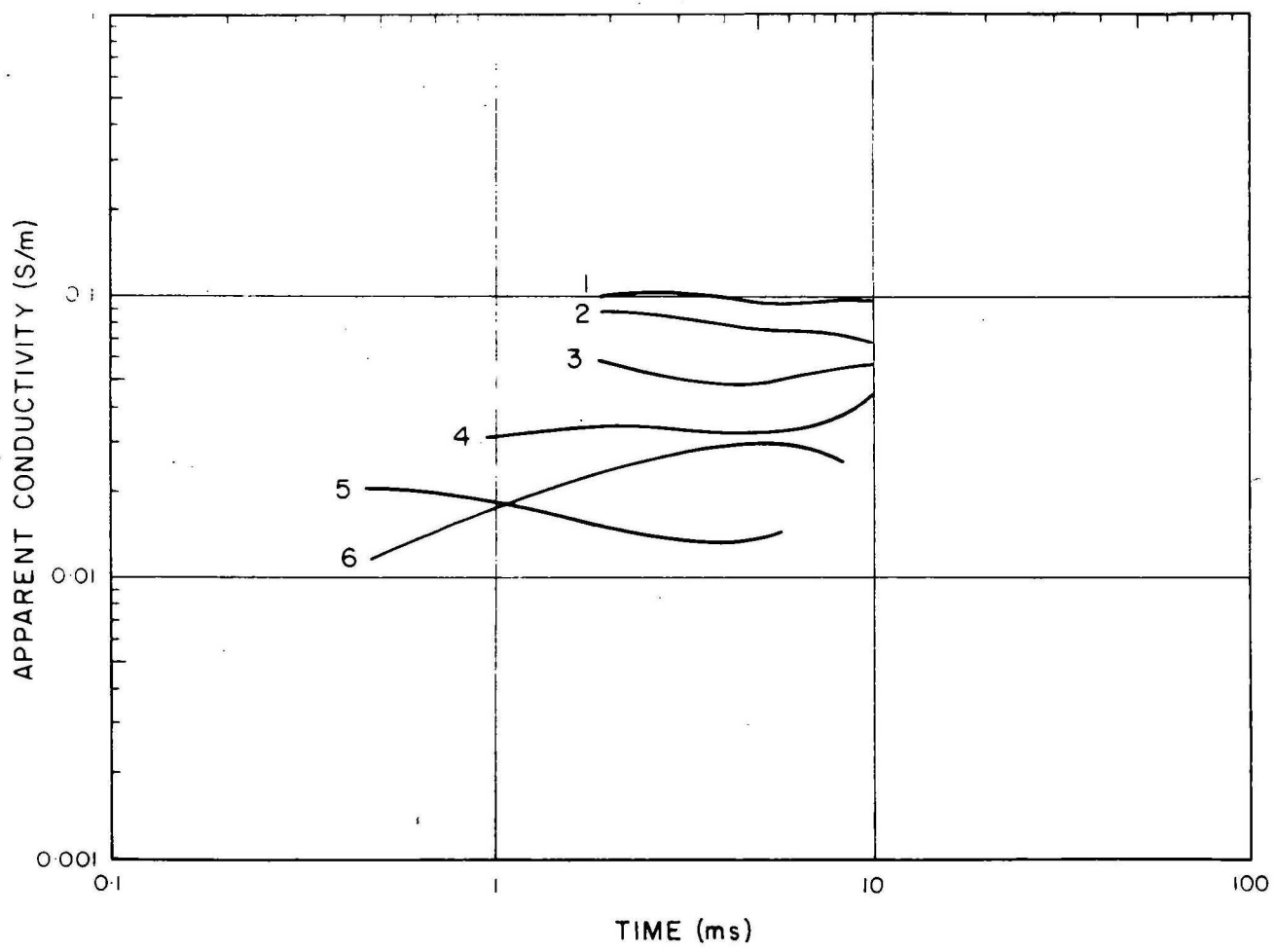
Three-layer case, numerical results

Figure 7



MODEL	1	2	3	4	5	6
h_1 (m)	150	100	50	20	10	0
h_2 (m)	25	75	125	155	165	175

(100m RADIUS LOOP)



Four-layer case, numerical results

The effect of changing loop size over a two-layered resistivity structure is illustrated in the scale model results shown in Figure 18 (sphere absent). In this scale model study curves 1, 3, 5, and 7 illustrate the response obtained with different loop sizes when a 20 m thick conductive layer overlies a resistive half-space. Curves 1 and 3 are for 100 m and 70 m loops respectively and are fairly similar. They appear to be late and early time sections of a composite curve. For the 50 m loop (curve 5) the early time asymptote is nearly reached at 0.5 ms but for other loop sizes, both smaller and larger, the early time asymptote is not reached. The largest loop (100 m, curve 1) appears to be "looking" deepest as it most nearly reaches the 0.01 S/m asymptote.

Three-layer cases: The results shown in Figure 5 were computed from numerical data (Vozoff, pers. comm.) and show the effect of varying loop size. The curves all reach the true conductivity of the thick, 0.6 S/m second layer. The effect of the third layer is not seen because of its depth (300 m).

Numerical results from Lee (1977) and Lee & Lewis (1974) are shown in Figure 6 which shows the response of a conductive layer embedded in a resistive half-space at various depths. The effects of the three layers are clearly evident in the curves, and the times at which the asymptotes due to the layers occur increase with the depth of the layers.

Four-layer case: Figure 7 shows the results of a four-layer case in which a 5 m thick conductive layer (1 S/m) lies in a resistive layer under a cover of medium conductivity (0.1 S/m) overburden. When the surface layer is thicker than 100 m the effects of lower layers are not seen. As the top layer decreases in thickness the apparent conductivity decreases but the effect of the layering is not discernible until the top layer is 10 m thick. Curve 6 reverts to a three-layer case in which the effect of the thin conductive layer can be seen under 175 m of 100 ohm-m material.

Field studies

The use of the apparent conductivity concept for interpreting TEM depth soundings is illustrated by results of field surveys at Pooncarie (NSW), Pirlta, (Vic.), and Alligator River (NT). The examples show how the apparent conductivity parameter can be used in interpretation and in investigating the accuracy of field measurements. The results at Pooncarie and Pirlta were obtained during a test TEM survey conducted jointly by BMR and Macquarie University with MPP0-1 equipment from 25 to 28 November 1975. The Pooncarie and Pirlta sites were chosen as test areas because geo-electric information

(including resistivity depth soundings and magnetotelluric soundings) was available and indicated that the ground was horizontally layered and laterally homogeneous. Drilling and well logs in this area indicate that Quaternary, Tertiary, and Cretaceous sediments in these areas are poorly consolidated, porous and electrically conductive, and overlie more resistive Palaeozoic sediments.

The results of the Alligator River survey were obtained during a geophysical mapping survey by BMR during 1975 (Spies, 1978).

Pooncarie, NSW: A Schlumberger array resistivity depth probe and a magnetotelluric (MT) sounding were carried out on a site near Pooncarie, NSW, by BMR and Macquarie University, Sydney, in 1975. The MT results are given by Vozoff et al. (1975) and the resistivity sounding results by Vozoff (pers. comm.). Supplementary resistivity results for small electrode spacings were obtained during the TEM survey.

The resistivity results were fed into a computer inversion program to derive the geo-electric section (Vozoff, pers. comm.). Possible three-layer and four-layer sections derived in this way are shown in Plate 8, and are compatible with the MT results. Theoretical TEM curves were calculated from these sections using a computer program developed by T. Lee (Macquarie University), and are compared with field results in Plate 8.

The computed TEM results from the four models are fairly similar; the major differences are about 30 percent at early times. It can be seen that for the 300 m loop there is excellent agreement between computed and field results. For loop sizes of 100 and 50 m there are major differences between field and computed results, of about 230 percent at early times and about 160 percent at late times. For smaller loops the differences become much greater. For multi-turn loops of 12.5 m and smaller, discrepancies are very large.

There are several possible explanations for these discrepancies:

- (a) Errors in field measurements: Calibration errors in the MPPO-1 equipment may be an explanation. Currents of 2 or 3 amps were used for loops smaller than 300 m, and multi-turn loops for sizes less than 25 m. It is possible that changes in the current or self inductance of the transmitting loop could change the characteristics of the MPPO-1 equipment.
- (b) TEM computed curve: Another possibility is that there are errors in the theoretical derivations or computer programs, emphasised at large values of $t/\rho\mu d^2$. However, these errors would be expected to increase gradually with

$t/\rho\mu d^2$ and thus would not explain the large difference between the 300 and 100 m loop results.

(c) The presence of a near-surface, thin, horizontal, conductive layer: Such a layer would have a large effect on small loops and a small effect on large loops. It is possible that such a layer would have minor influence on the resistivity results. However this again would not explain the large differences between the 50 and 100 m loop results.

The discrepancies in field results from different loop sizes can also be seen in Figure 8, where the TEM field results have been converted to apparent conductivity curves. The 300 m loop curve changes from 0.2 S/m at early times to 0.46 S/m at late times, i.e. the early times are influenced by the first 20-m thick layer and the curve reaches the asymptotic value for the underlying layer at about 10 ms.

The 50, 25, and 12.5 m loop field results are fairly similar in that apparent conductivities are in the 0.5-1.0 S/m range, significantly higher than that of any layer in the computed resistivity section. With smaller loops the apparent conductivities increase to such an extent that the most probable explanation is errors in the field data as described in (a).

Figure 9 shows apparent conductivity curves obtained from the numerically computed TEM results. There is a fairly smooth transition from the 300 m loop results to the 25 m loop results. For smaller loops the curves appear to show too low an apparent conductivity and suggest inaccuracies in the numerical modelling for small loops.

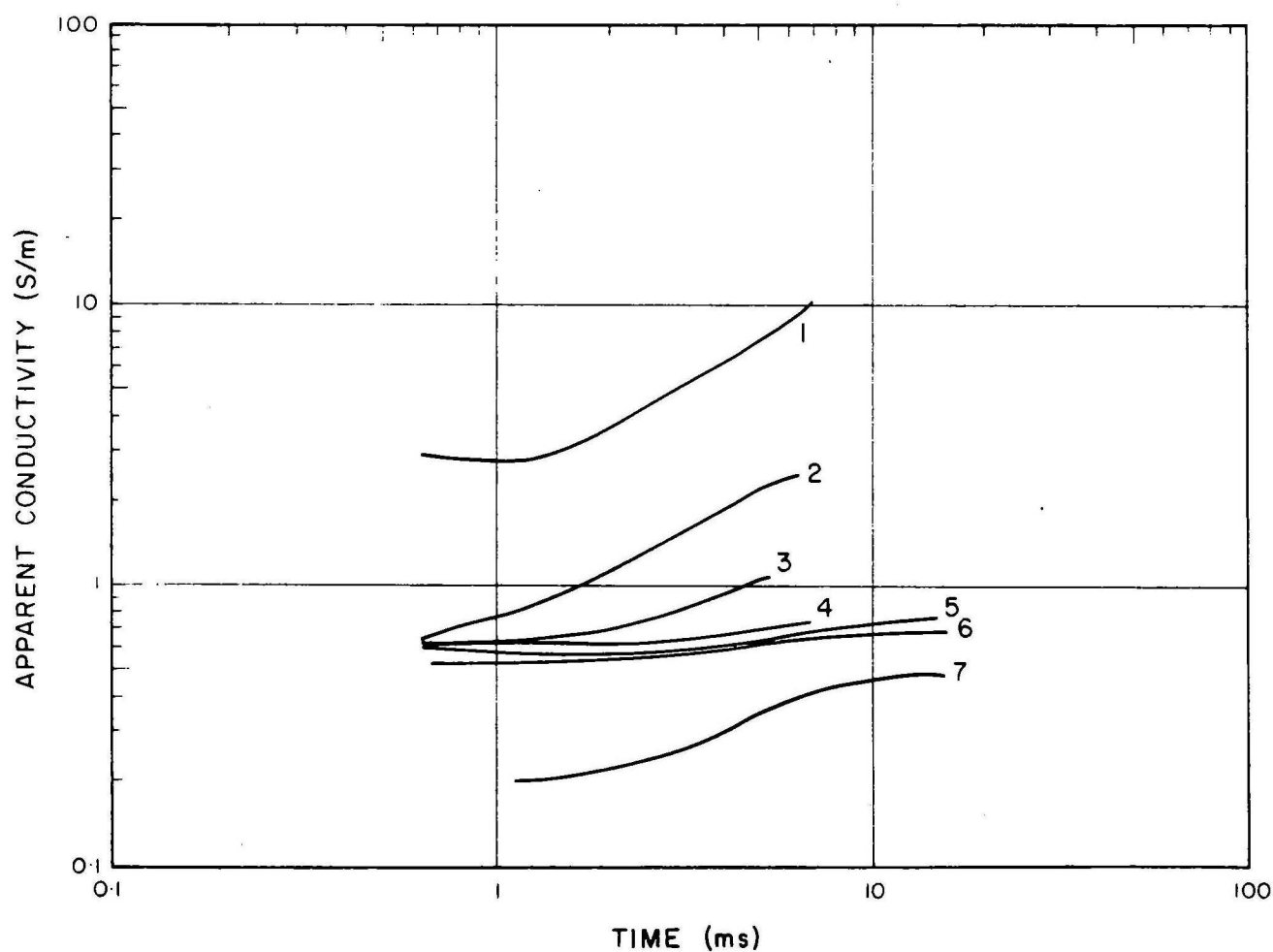
Pirlta, Victoria: This area is located 30 kmsouthwest of Mildura, Victoria, and was chosen as a test area because an earlier BMR resistivity survey had shown that the geo-electric section consists of simple horizontally layered sediments (also supported by MT results, Vozoff, pers. comm.). The inferred section, taken from Dolan et al. (1975), is shown in Plate 9. No computed TEM curves are available.

The TEM field results and geo-electric section obtained from inversion of the resistivity data are presented in Plate 9. A thin surface resistive layer overlies 25 m of 0.2-0.3 S/m sediments, which in turn overlies a 135 m section of 2 S/m material. The TEM fields would probably not penetrate beneath this relatively thick layer.

The apparent conductivity results (Fig. 10) show reasonably consistent results for the 100, 50, and 25 m loops, and appear to be influenced by the 0.2-0.3 S/m and the 2.0 S/m layers over the measured time range. Note that

Figure 8

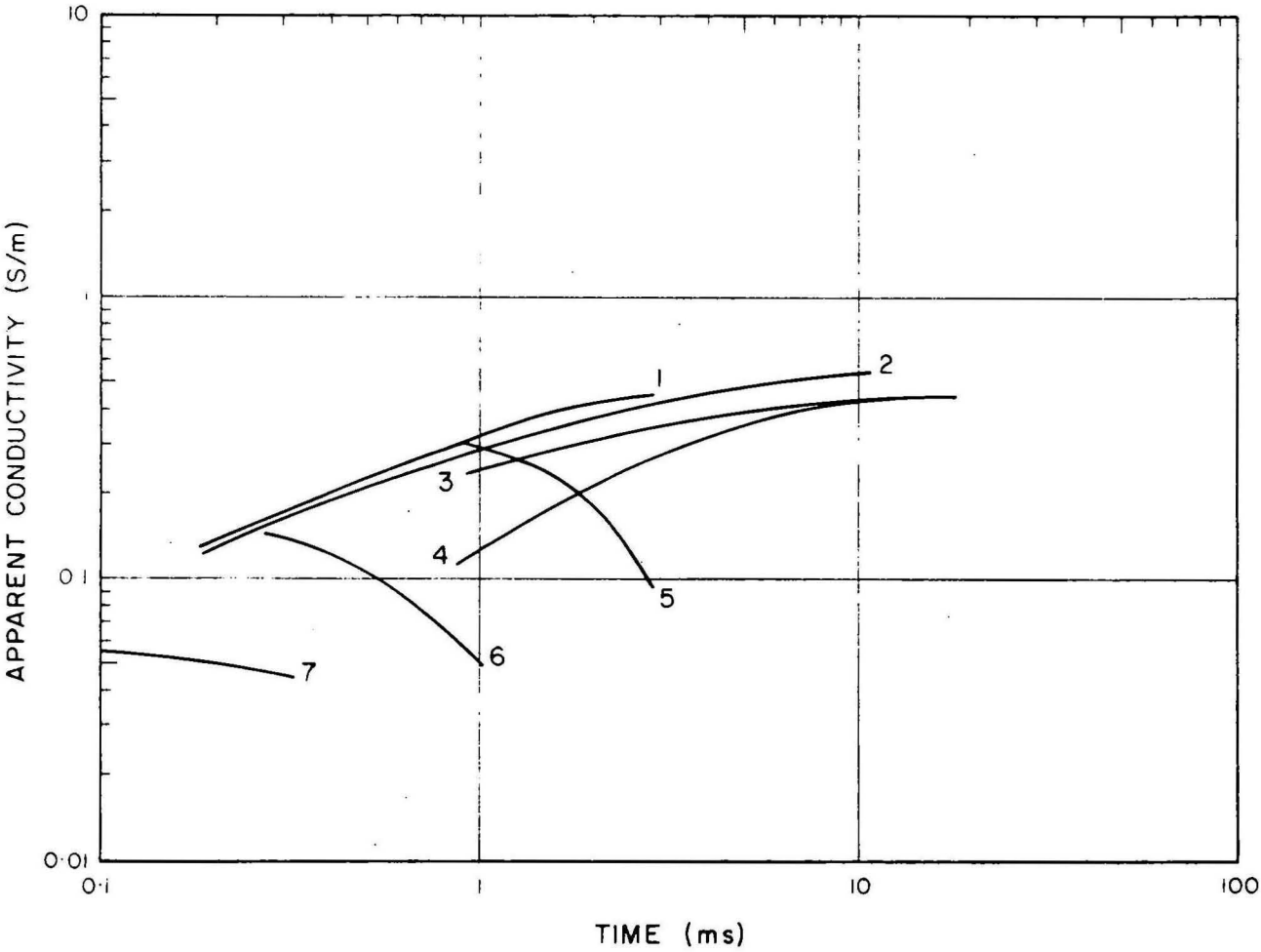
CURVE	1	2	3	4	5	6	7
LOOP SIZE (m)	3.12	6.25	12.5	25	50	100	300



Pooncarie, NSW: Field results

Figure 9

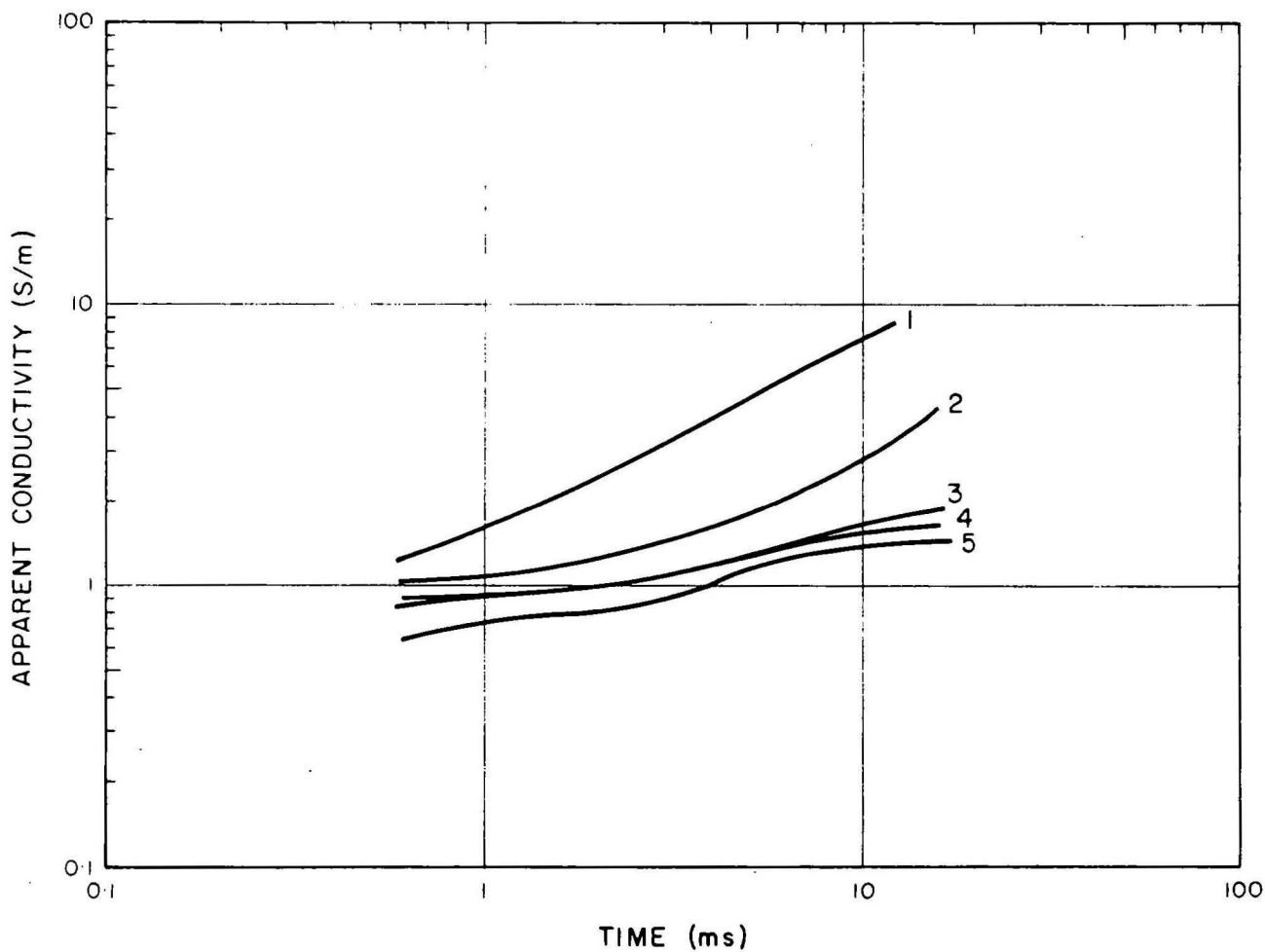
CURVE	1	2	3	4	5	6	7
LOOP SIZE (m)	25	50	100	300	12.5	6.25	3.12



Pooncarie, NSW: Field results

Figure 10

CURVE	1	2	3	4	5
LOOP SIZE (m)	6.25	12.5	25	50	100



Pirlta , Vic.: Field results

the curves do not reach the actual conductivity of the 2.0 S/m layer. As expected, the thin, highly resistive surface layer does not affect the TEM curve.

The results for the smaller multi-turn loops are again higher than expected, and similar reasons are proposed to those in the Pooncarie example.

It appears that further work is desirable to explain or interpret results with the small loops, because the use of small, multi-turn loops has many applications in TEM surveys.

Alligator River, NT

In the 1975 Alligator River survey TEM was used to assist geological mapping by tracing carbonaceous shales beneath alluvial cover. It was observed that TEM anomalies caused by carbonaceous shale could be distinguished from surficial conductors by using apparent conductivity curves.

A detailed traverse along the Arnhem Highway revealed two main anomalies, which have been referred to as anomalies A and B. Geo-electrical control on the anomaly sources was obtained from Schlumberger array resistivity depth probes and holes drilled as part of BMR's geological program. A hole drilled at anomaly A intersected quartzite, clay, and weathered phyllite after passing through 40 m of sandy clay. The resistivity results indicate that a section of the sandy clay from 20-30 m has high conductivity (0.5 S/m) and is bounded by more resistive sediments. This geo-electric section is reflected in the apparent conductivity curves (Fig. 11) which show a decrease in apparent conductivity with time. Anomaly B was found to be caused by conductive (0.02-1.0 S/m) carbonaceous siltstone under a resistive (0.004-0.0012 S/m) weathered cover. The apparent conductivity curve over this type of anomaly shows an increase with time, which indicates there is a continuous depth extent of conductive material.

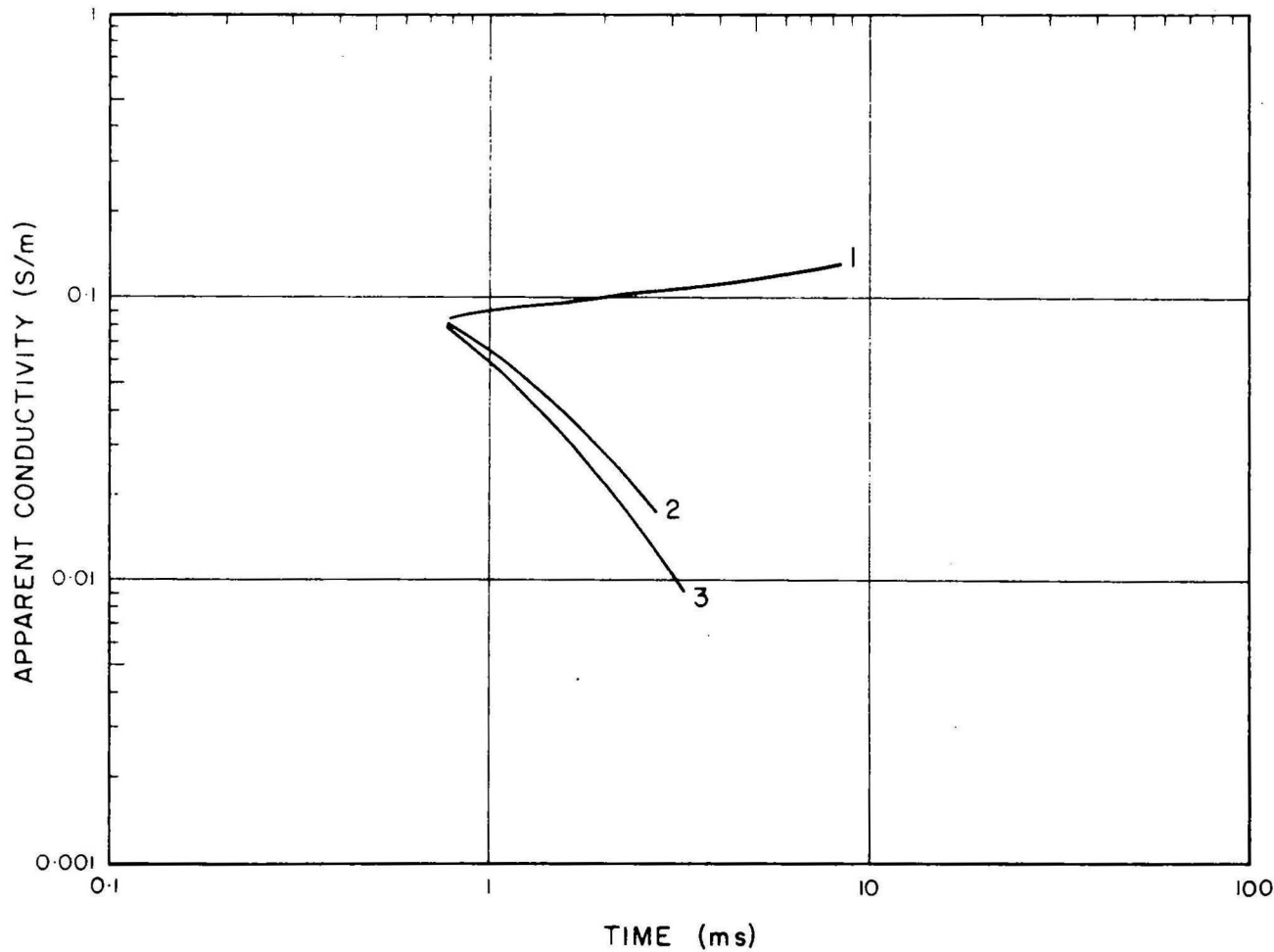
Similar responses to those obtained along the Arnhem Highway were observed in the Red Lily area (Fig. 12), where exploration drillholes had intersected graphitic, pyritic schists at a depth of about 50 m beneath weathered or partly weathered siltstone and phyllite. A resistivity sounding showed that the surface layers (0.08-0.04 S/m) were more resistive than the unweathered graphitic pyritic schist (0.14 S/m). Curve 1 is taken over the site of the resistivity depth sounding. The other curves are arbitrarily chosen from extensions of the Red Lily anomaly. It was also noted that in areas of less conductive carbonaceous shale or thinly interbedded carbonaceous shale/siltstone the apparent conductivity curve sometimes remained constant

Figure 11

GEO - ELECTRIC SECTIONS

ANOMALY A		ANOMALY B	
0.001 S/m	0m	0.0004 S/m	0m
0.03 S/m	10m	0.0012 S/m	10m
0.5 S/m	20m	0.02-1.0 S/m	20m
0.004 S/m	30m		

CURVE	1	2	3
ANOMALY	B	A	A
LOOP SIZE (m)	100	50	100



Alligator River area, NT: Arnhem Highway traverse results

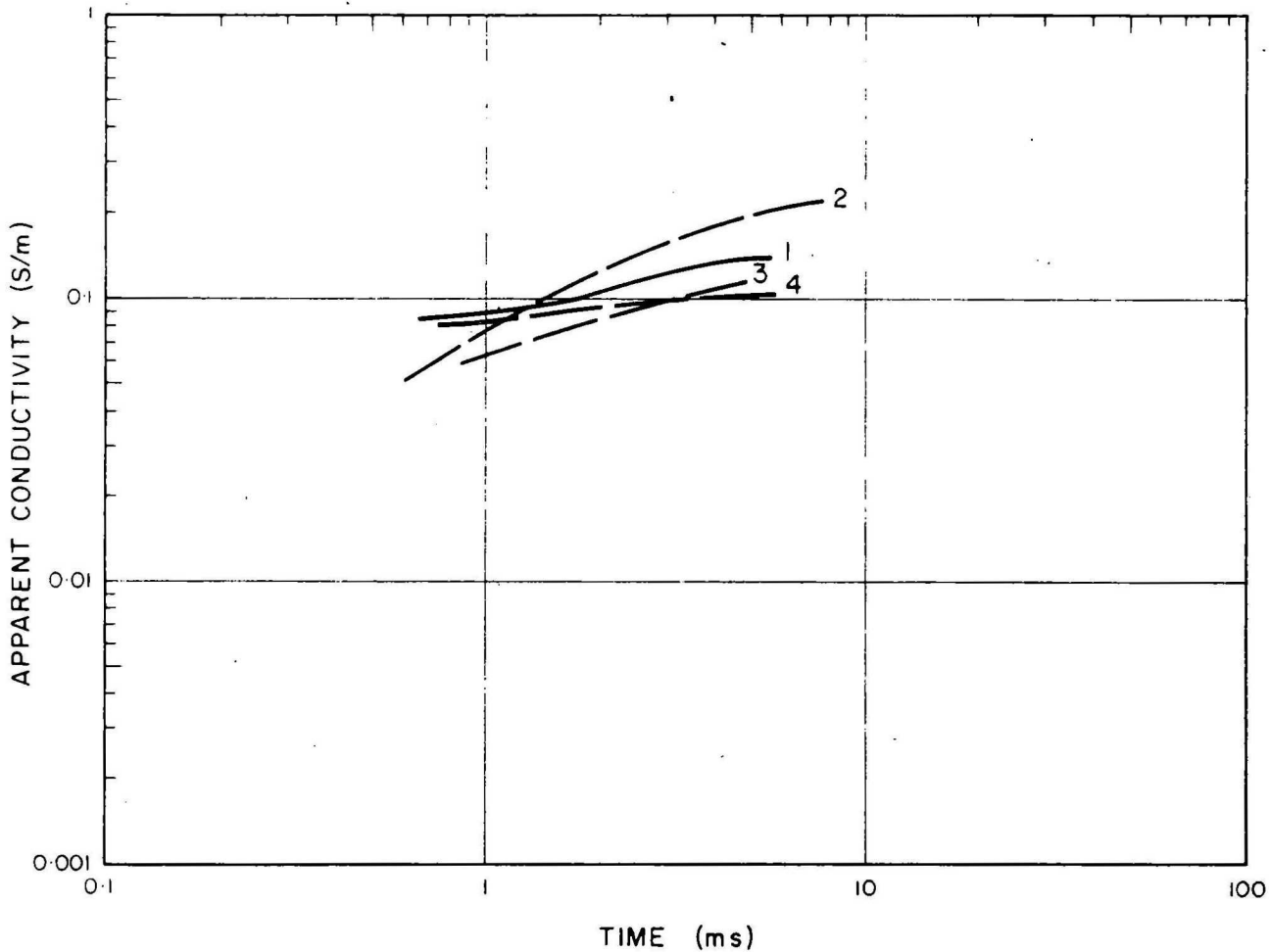
Figure 12

GEOLOGICAL AND ELECTRIC SECTION

L9/300 SE

————— 0m
0.087 S/m laterite, clay
————— 10m
0.043 S/m siltstone, phyllite
————— 50m
0.143 S/m graphitic pyritic
schist

CURVE	1	2	3	4
LINE (SE)	9/300	8.5/425	14/1275	9/250
LOOP SIZE (m)	50	50	50	50



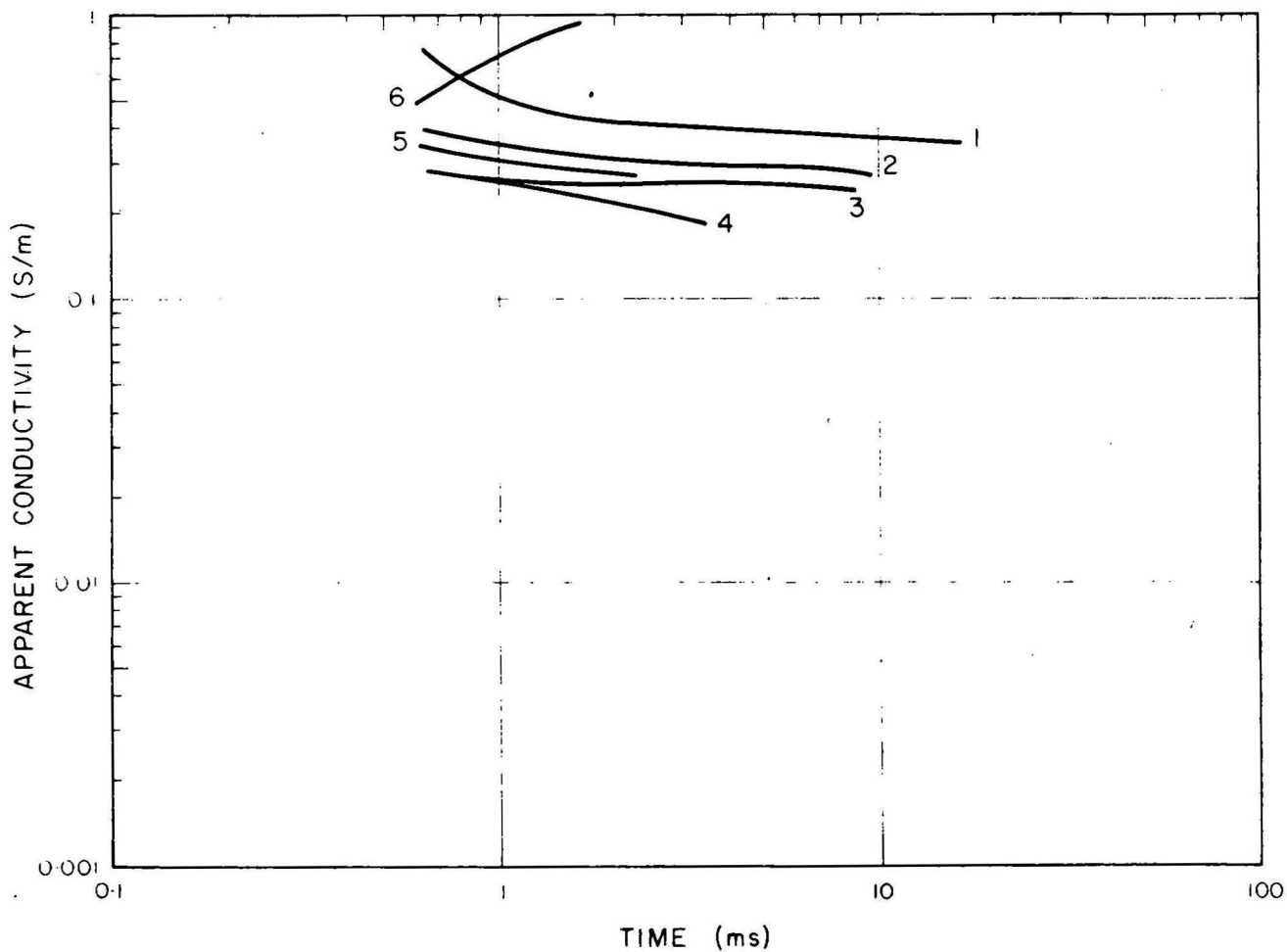
Alligator River area, NT: Red Lilly area results

Figure 13

GEO - ELECTRIC SECTIONS

FOUR-LAYER CASE		THREE-LAYER CASE	
0.5 S/m	0m	0.9 S/m	0m
0.12 S/m	10m	0.08 S/m	6m
0.03 S/m	50m	0.0007 S/m	95m
0.003 S/m	120m		

CURVE	1	2	3	4	5	6
LOOP SIZE (m)	100	50	25	12.5	6	3
No. TURNS	1	1	2	4	8	17



Alligator River area , NT : Flood plain results

with time or even decreased slightly. However, it was easy to distinguish these responses from surficial conductor responses, which decreased rapidly with time.

Very large TEM responses were obtained during this survey when traverses entered the floodplain of the South Alligator River. A geo-electric section obtained from a resistivity depth sounding indicates that the source of these anomalies is conductive surficial sediments as shown in Figure 13. Also shown in Figure 13 are TEM responses obtained with different loop sizes. Referring first to curve 1 it can be seen that at early times (0.6 ms) the curve is asymptotic to the conductivity of the top layer of the three-layer case. At late times the apparent conductivity decreases to a near half-space response of about 0.3 S/m which is higher than that inferred in the resistivity section. However, lateral inhomogeneities are probably the cause of the discrepancy in this case. The lower resistive layer is probably bedrock underlying the floodplain. The responses with the small loops differ from those with the larger loops, but this discrepancy may be explained by inaccuracies in the computation of apparent conductivity for small loops or errors in the field results for small loops.

6. INTERPRETATION OF FINITE RESISTIVITY STRUCTURES

Interpretation of TEM surveys over finite structures is commonly based on analyses of the shape and amplitude of transient decay curves. In the single-loop system, results are normally plotted as profiles or contours of the emf $e(t)$ induced in the loop at sample time t , normalised by dividing by the primary current I . Results are compared at early times (e.g. 1 ms) and late times (e.g. 15 ms) to compare responses from different sources. In general the early-time response is influenced by near-surface conductors and the late-time response by deeper and/or more conductive bodies. The results are usually interpreted by visual or graphical inspection of the results at different times to determine the position and strength of anomalies, and several "rules-of-thumb" based on decay curve shape (Spies, 1976a) have been developed to assist in the identification of buried conductors. A more thorough interpretation of TEM responses over finite structures is very complex, but some further assistance in interpretation can be provided by the use of the apparent conductivity concept. The use of the apparent conductivity concept in interpreting TEM results over finite structures can be illustrated by analysing the results of model and field studies.

Model studies

Sphere in a layered ground: Figures 14 to 18 show the response for a one-loop system to a conductive sphere buried in a uniform ground or layered earth. The responses have been calculated from numerical TEMdata provided by Lee (1975). In Figure 14, a sphere (2 S/m) is buried at different depths. Although the effect of the sphere is evident in the change of apparent conductivity, the time range of measurements (0.4-3 ms) is not great enough to distinguish the sphere from the background. However, a series of profiles over the body would give a circular anomaly pattern and enable the shape of the conductor to be inferred. A smaller loop of 50 m radius is used in Figure 15. In this case the sphere is clearly discernible, even for depths up to 100 m. The effect of varying loop size is demonstrated in Figure 16. This shows that the most distinctive response is obtained if the radii of the loop and the sphere are the same. When the radius of the loop is smaller than that of the sphere, the curve shape is difficult to explain intuitively.

The sphere is placed under a conductive overburden in Figure 17, and is discernible only in the case where the top of the sphere is 25 m from the surface (curve 1). When the top of the sphere is at a depth of 60 m the response is similar to that of a half-space, and for greater depths the effect of the sphere is not discernible. The results shown in Figure 18 are for a case similar to that of Figure 17 except the loop size is varied and the conductivity of the sphere has been reduced. For a 100 m loop a sphere of radius 50 m is not discernible. When the loop is 70 m or smaller, however, the effect of the sphere is readily seen in the curves.

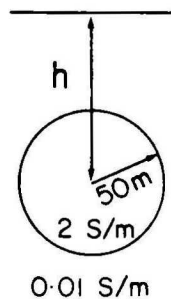
Dipping dyke: This example indicates the result to be expected over a dipping dyke-like structure. The results, presented in Figure 18, are taken from a scale model study by Spies (in prep.) and show the peak response of a profile over a dyke 18 m thick dipping at 45 degrees. The loop radius is 25 m and dyke conductivity is 0.22 S/m.

From $t = 0.1$ ms to $t = 0.5$ ms the apparent conductivity increases to approach the true conductivity of the dyke. However, for times greater than 0.5 ms the response falls off very quickly towards the conductivity of the surrounding medium.

Field study

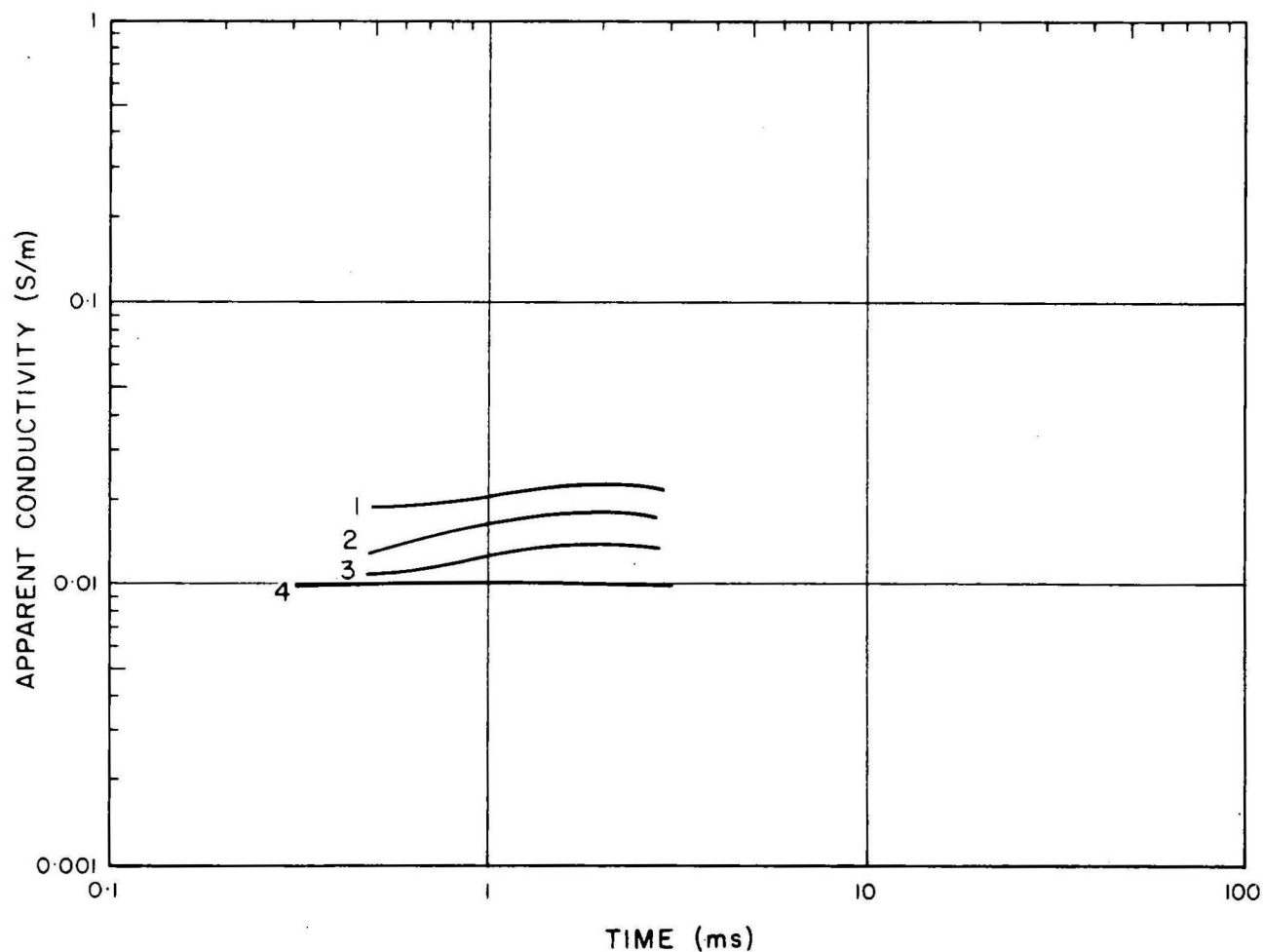
Woodlawn, NSW: The Woodlawn copper-lead-zinc orebody is near Tarago, NSW, and has been studied with a large range of geophysical methods. Both BMR (Young 1976) and CSIRO (G. Buselli, CSIRO, pers. comm.) have conducted experimental

Figure 14



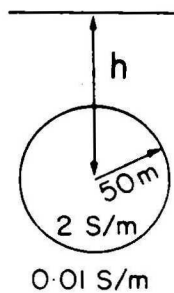
MODEL	1	2	3	4
h (m)	75	100	150	∞

(100m RADIUS LOOP)



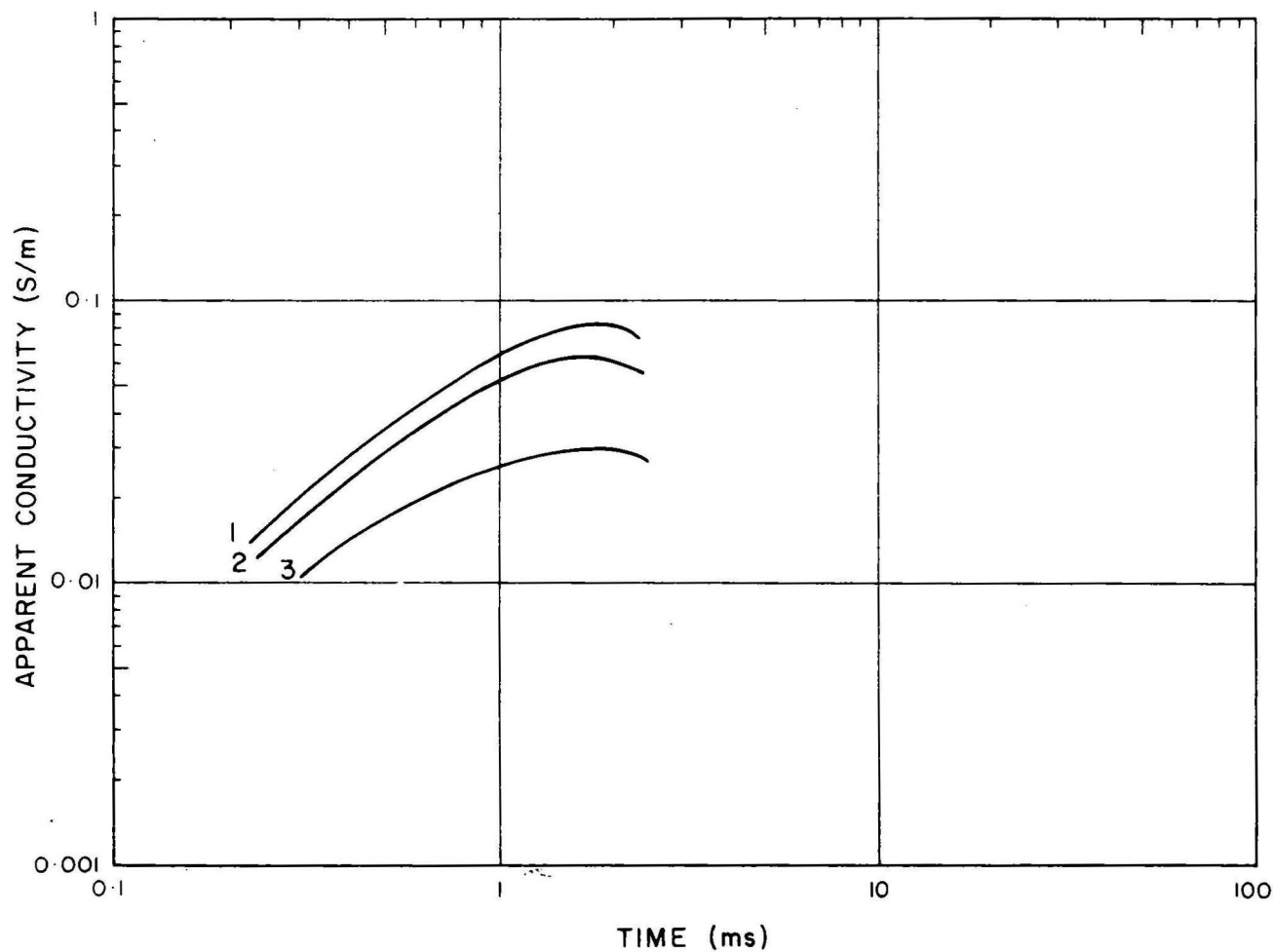
Sphere in uniform ground, varying depth of burial

Figure 15



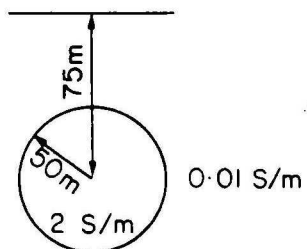
MODEL	1	2	3
h	70	75	100

(50m RADIUS LOOP)

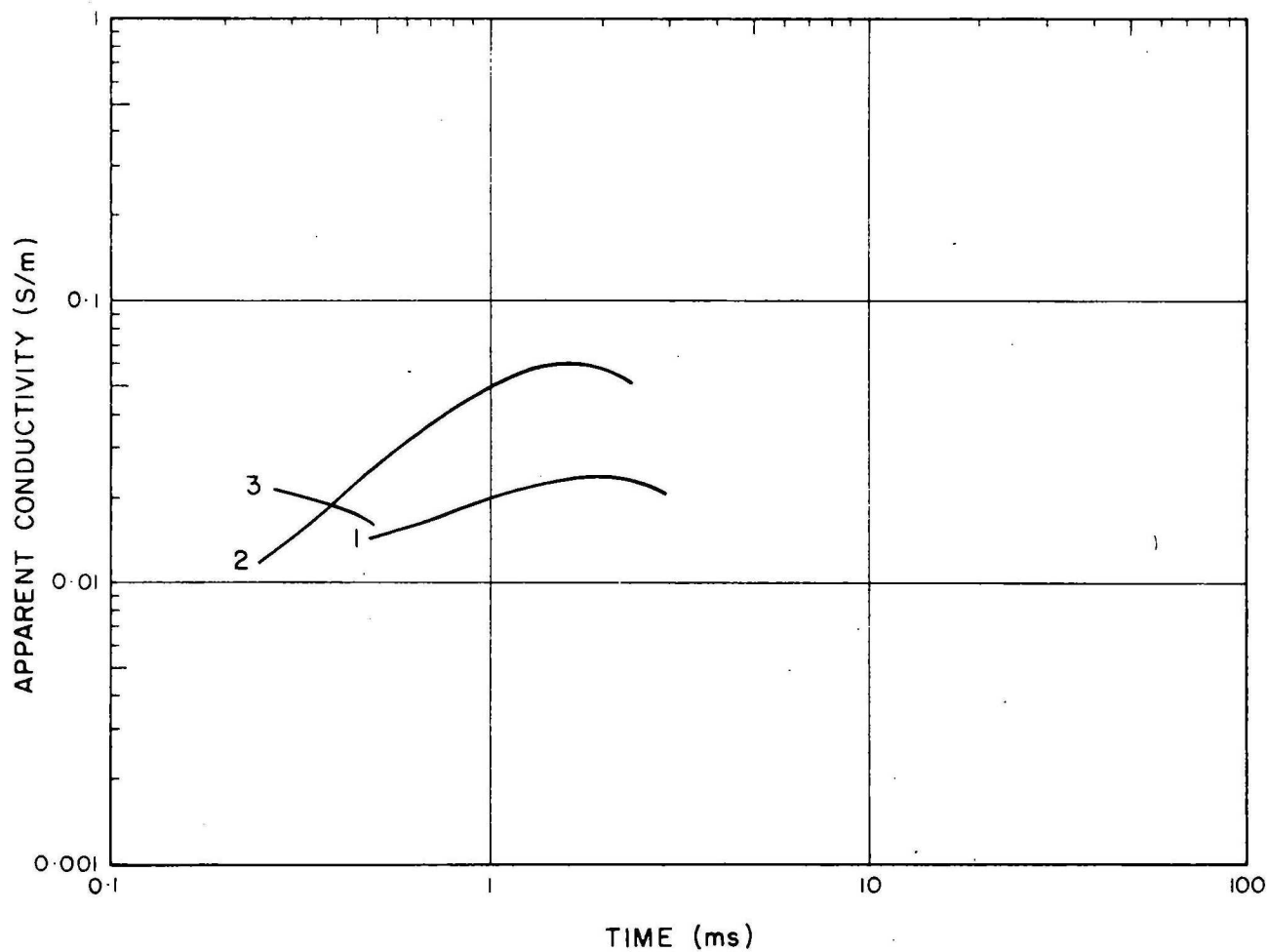


Sphere in uniform ground, varying depth of burial

Figure 16

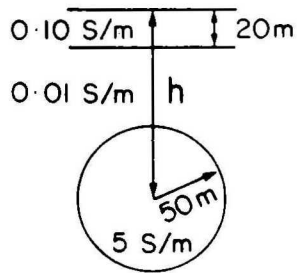


MODEL	1	2	3
LOOP RADIUS (m)	100	50	30



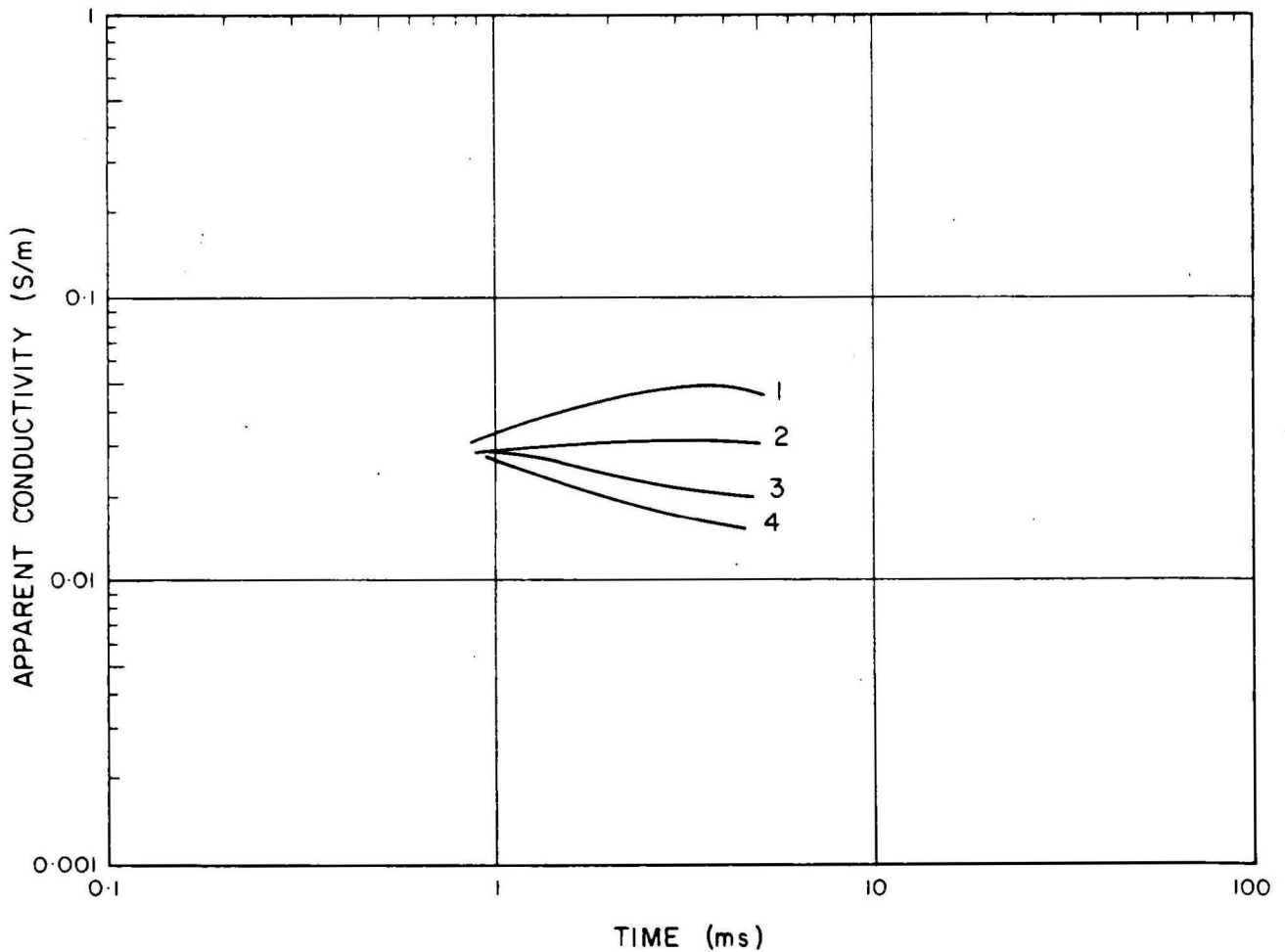
Sphere in uniform ground , varying loop size

Figure 17



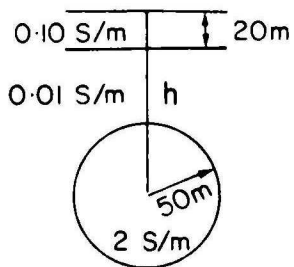
MODEL	1	2	3	4
h (m)	75	110	150	∞

(100m RADIUS LOOP)



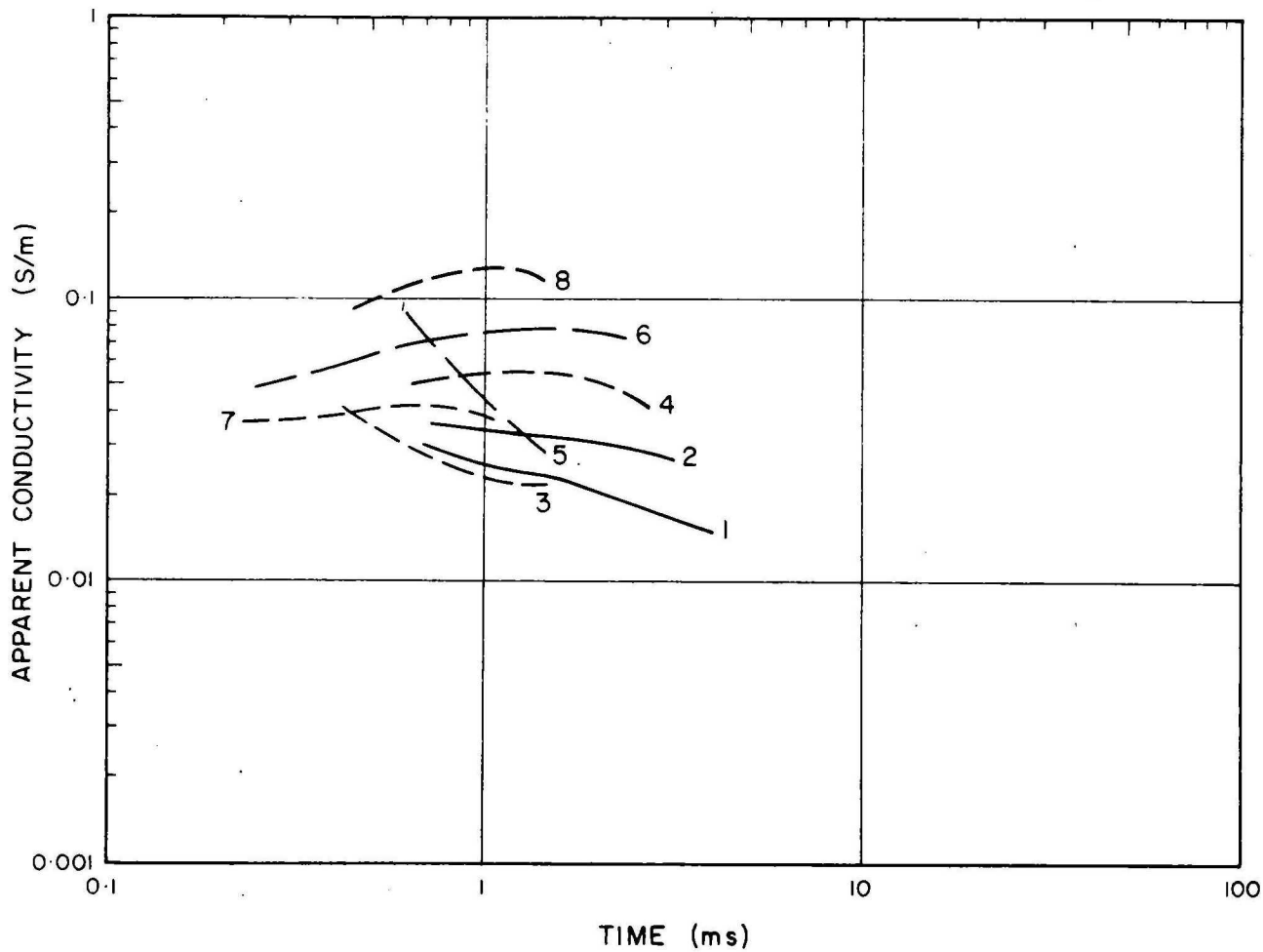
Sphere in layered ground, varying depth of burial

Figure 18



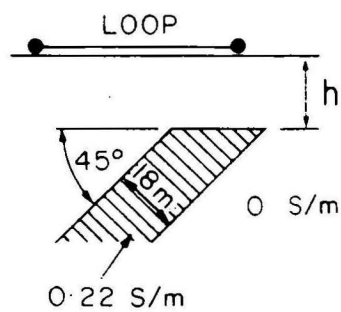
MODEL	1	2	3	4	5	6	7	8
LOOP RADIUS(m)	100	100	70	70	50	50	30	30
WITH SPHERE ?	NO	YES	NO	YES	NO	YES	NO	YES

$h = 75\text{m}$



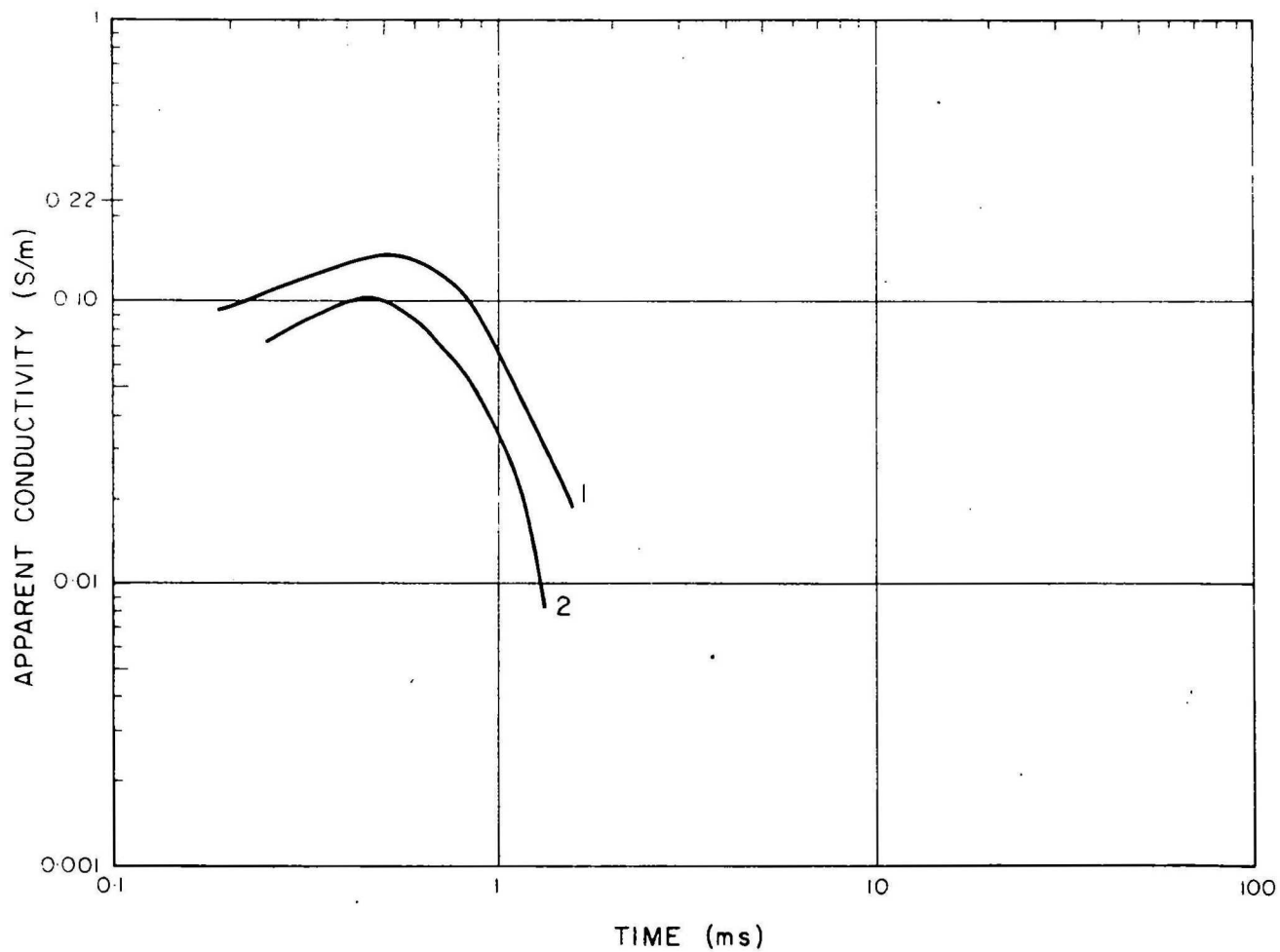
Sphere in layered ground ,varying loop size

Figure 19



MODEL	1	2
h (m)	1.3	6

(25m RADIUS LOOP)



Dipping dyke , scale model study

TEM surveys over the deposit. CSIRO's results are of greater accuracy and cover a wider time range than BMR's results and provide a good field example from which to study the TEM response of finite structures.

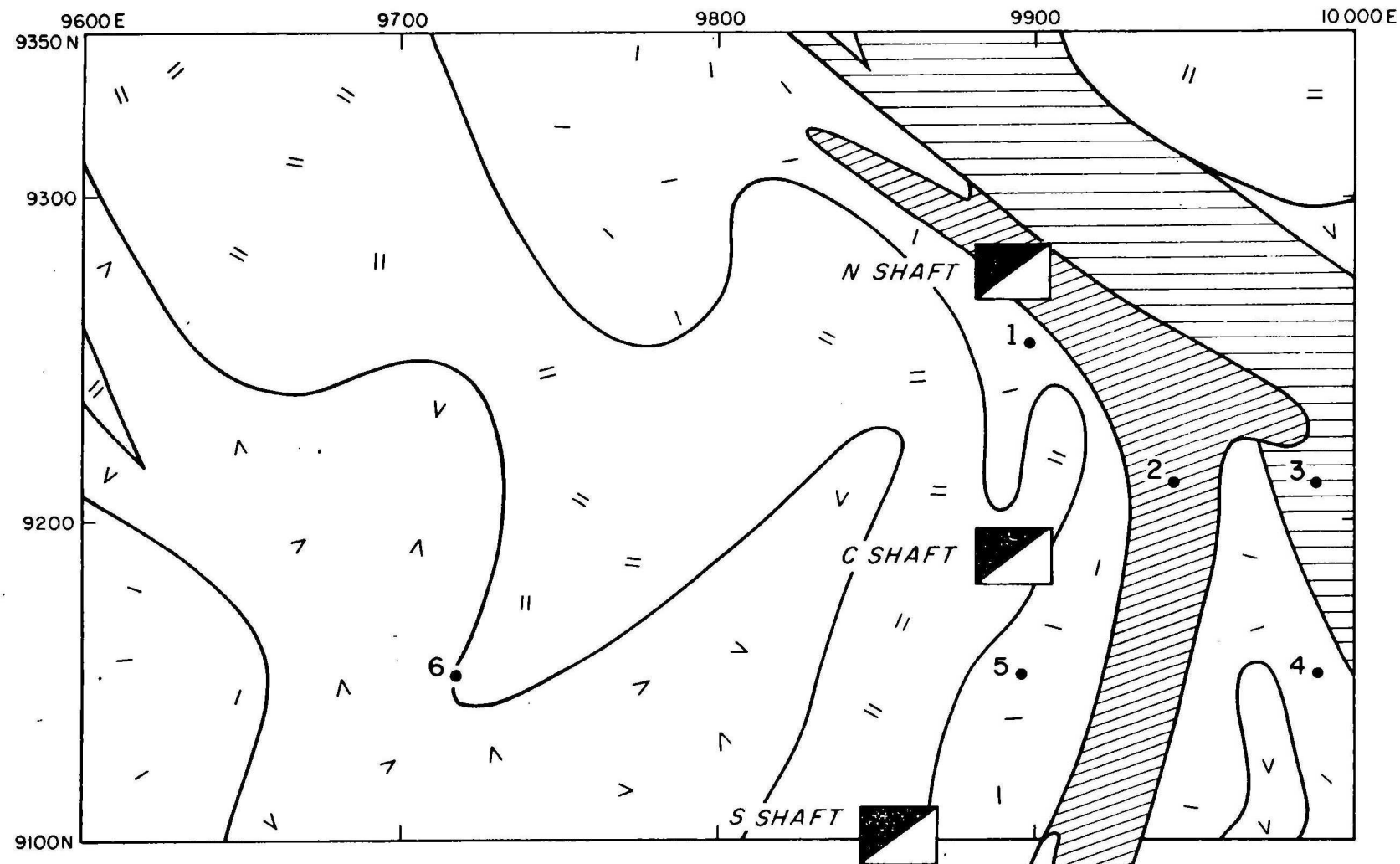
The Woodlawn orebody is a concordant lens of bedded, high-grade Cu-Pb-Zn sulphides, 20 m thick, and dips to the west at about 45° . The near-surface oxidised zone is about 12 m thick, consists mainly of ferruginous clay, and has a sharp contact with the sulphides. A locality plan and surface geological map (taken from Malone et al., 1975) is shown in Figure 20.

The apparent conductivity results shown in Figure 21 were computed from CSIRO data obtained in the loop positions shown in Figure 20. Curves 1 and 2 are measured over the top of the orebody while curve 5 is down-dip. Curves 3 and 4 are up-dip from the orebody, and the response is much less than 1 and 2. Curve 6 is located about 200 m down-dip.

In curves 1 and 2, the apparent conductivity increases steeply from 0.4 S/m at 0.5 ms to between 15 and 20 S/m at 50 ms. This latter figure agrees with results from Spies (1977) who determined bulk conductivity measurements of 5-20 S/m from scale model studies of the orebody. However, other curves do not indicate the conductivity of the orebody as well as curves 1 and 2.

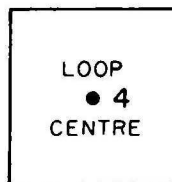
Curve 5 is similar to 1 and 2 at early times but departs significantly for times greater than 8 ms. This departure is difficult to explain, but as explained in Chapter 4 it is possible that errors in field measurements occur at late times.

Curves 3, 4, and 6 are similar; apparent conductivities are less than 0.1 S/m at 1 ms and increase steadily with time. It is likely that the orebody influences the response at late times even at distances equal to several loop sizes. However, it would appear unlikely that at very late times (60 ms) the apparent conductivity would be as high as 2 S/m, which is of the order of the true conductivity of the orebody. Again, the high values of apparent conductivity at very late times in curves 3, 4, and 6 could easily be explained by errors in field measurement. Note that a reading error of $1 \mu\text{V/A}$ would lower these apparent conductivities to about 0.3 S/m.



MIDDLE TO UPPER SILURIAN

- Dolerite
- Shale, fine-grained acid volcanics
- Black shale
- Coarse-grained acid volcanics
- Gossan



45m LOOPS

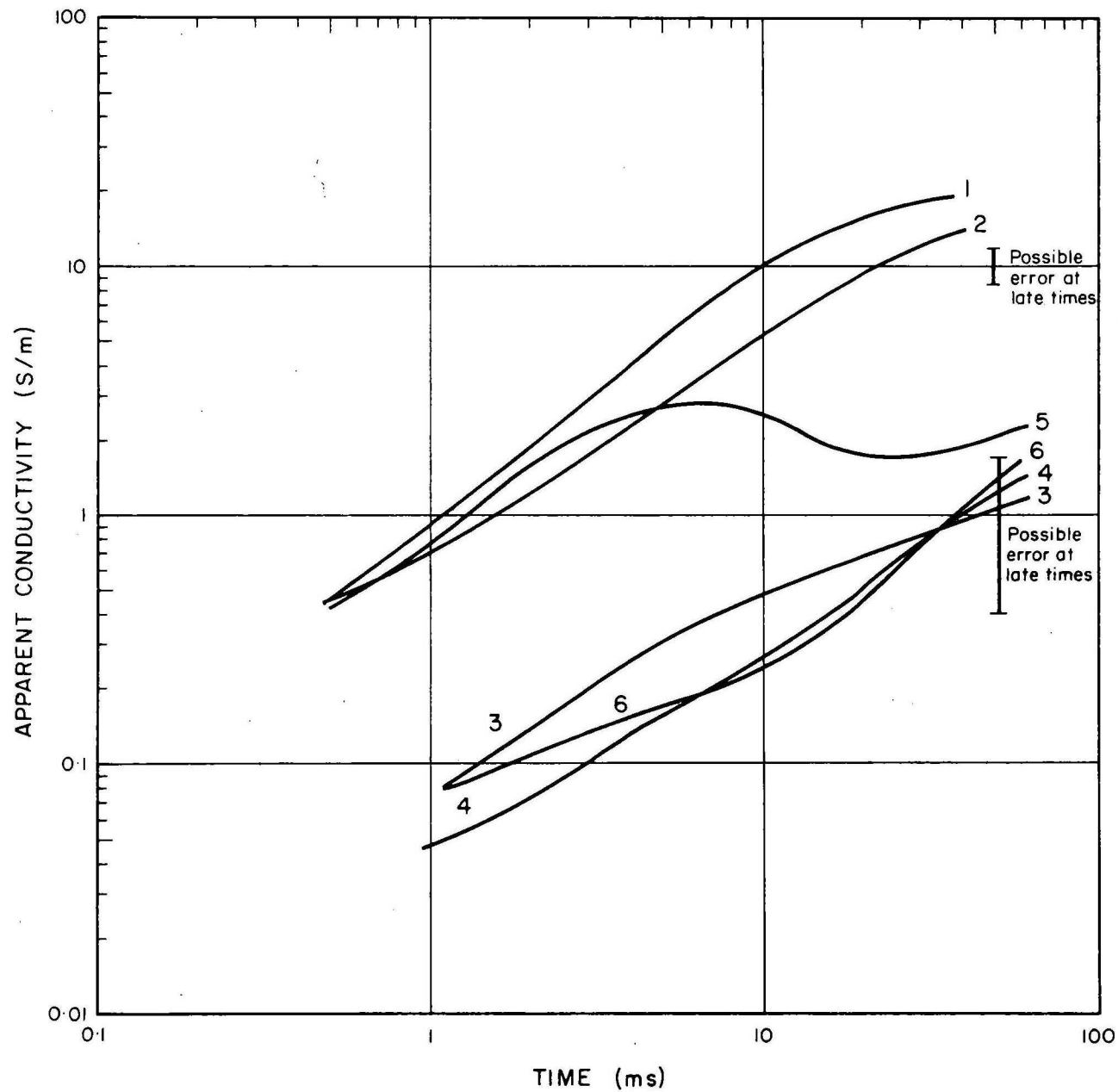


Woodlawn, NSW: Locality map
showing loop positions and
geology

(Geology after Malone et al, 1975)

Figure 21

45m LOOP



(DATA SUPPLIED BY CSIRO)

Woodlawn, NSW: Field results

7. DISCUSSION AND CONCLUSIONS

Transient electromagnetic decay curves can be easily converted into apparent conductivity curves using graphical or computer techniques described in Chapters 3 and 4. Interpretation of field results is much easier with the data in this form. However, the continued development of methods to interpret TEM apparent conductivity curves is currently hampered by lack of precision in field measurements and the difficulty of theoretically calculating TEM responses.

It has been shown that the TEM method can be used as a depth sounding technique if measurements are made over a suitable time range and high precision measurements are available at late times. Such a technique has advantages over conventional resistivity sounding methods in that TEM soundings are faster and it is not necessary to expand electrodes over a great distance.

The computation of apparent conductivity curves for various numerical and scale models shows that with suitable field techniques it may be possible to estimate the true conductivity of conductors. The apparent conductivity is a function of many factors such as sample time, depth of burial, size and conductivity of the body, and loop size. In some cases, for example a thick conductive sequence, the apparent conductivity equals the true conductivity. A unit such as a thin resistive bed will have a negligible effect on the apparent conductivity curve.

In the case of field surveys apparent conductivity calculations have been shown to assist in distinguishing surficial conductors from bedrock conductors, and to disclose the true conductivity of some sources.

In summary, the conversion of TEM data to apparent conductivity curves has many applications in interpretation of TEM results. More quantitative interpretation may be possible once further numerical or model study results are available and better field measurements are possible.

8. ACKNOWLEDGEMENTS

The assistance of Mr R.F. Moore in preparing the plotting programs, and Jododex Australia Pty Ltd for supplying data on the Woodlawn deposit is gratefully acknowledged. The permission of CSIRO to use the Woodlawn TEM results shown in Figure 21 is also gratefully acknowledged.

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APPENDIX 1

DESCRIPTION OF COMPUTER PROGRAMS TO CALCULATE APPARENT CONDUCTIVITY

Fortran program TERRY which is included as Appendix 1a is designed for use with an HP2100 computer and Gould 5000 plotter. TERRY computes the value of apparent conductivities directly from the TEM response. Input data are title, loop size, number of readings, number of loop turns, loop current, sample times, and response. The time array may be stored for consecutive runs. Output is in the form of a table and an apparent conductivity plot on the Gould 5000. This program calls subroutines EXEC and TERRZ (executive system subroutines to enable rerunning of main program), AKIMI and plotting subroutines PLOT, LOGAX, SYMB. TERRZ, AKIMI, and LOGAX are included as Appendixes 1b, 1c, and 1d respectively. A sample output from program TERRY is included as Appendix 1e.

Fortran programs HOMOG and TEMHF which are included as Appendixes 1f and 1g are also designed for use with an HP2100 computer and Gould 5000 plotter. TEMHF is used to produce plots for the construction of standard curves for various loop sizes and half-space conductivities. HOMOG is used to produce tables of the response for various loop sizes and half-space conductivities.

Input parameters for HOMOG are conductivity, loop size, and loop shape (square or circle). The TEM response is calculated for 55 sample times between 0.1 and 100 ms. ITEST is a parameter which shows which part of the theoretical TEM response was used in the calculation. If the exact expression was used ITEST = 0, if the interpolation formula was used ITEST = 1 and if the value is outside the possible range of calculations ITEST = -1. HOMOG calls subroutines HALF and AKIMI. Subroutine HALF, which is included as Appendix 1h, computes the TEM response of a homogeneous ground having a specified conductivity and loop size, for sample times from 0.1 to 100 ms. Output data from this subroutine are given in two arrays containing successive values of time and voltage. Subroutine AKIMI is an interpolation routine and is used for calculating the expression for values of t between $7.9 \times 10^{-7} \delta b^2$ and $1.2 \times 10^{-4} \delta b^2$. An example of the output from HOMOG is included as Appendix 1i.

Program TEMHF is an extension of program HOMOG and produces standard curves for various loop sizes and a range of conductivities. As well as calling AKIMI and HALF this program calls the plotting subroutines LCOMP, INTPL, and LOGAX which are included as Appendixes 1j, 1k, and 1d. Examples of the output from TEMHF have been included as Plates 1 to 7.


```

0001 FTN4
0002 PROGRAM TERRY
0003 C
0004 C COMPUTES APPARENT CONDUCTIVITY FROM TEM VALUES
0005 C INPUT DATA IS
0006 C NAME=TITLE OR LOCATION
0007 C SIZE=LOOP SIDE,M
0008 C N=NUMBER OF POINTS ON CURVE
0009 C IOPT=1 READS NO OF TURNS & CURRENT
0010 C 0 ASSUMES 1 TURN , 1 AMP
0011 C T(I)=TIME,MS
0012 C V(I)=RESPONSE,UV
0013 C
0014 C INTEGER TERRZ(3)
0015 C DIMENSION LBLX(15),LBLY(15),NAME(30),IO(5)
0016 C DIMENSION V(80),T(80),SIGMA(80),ITEST(80),A(12),B(12)
0017 C EQUIVALENCE (IO(1),IO1)
0018 C DATA LBLX/2HT1,2HME,2H ,2HMS,2H ,2H ,2H ,2H ,2H ,2H ,2H ,2H ,2H ,2H ,2H ,2H /
0019 C DATA LBLY/2HAP,2HAP,2HRE,2HNT,2H C,2HON,2HOU,2HCT,2HIV,2HIT,2HY ,2H ,2H ,2H ,2H ,2H /
0020 C DATA TERRZ/2HTE,2HRR,2HZ /
0021 C DATA A/ 39716, 5, 62946, 79245, 99763,1,25594,
0022 C *1.58114,1.99054,2.5059,3.15478,3.9717,5, /
0023 C DATA B/ .01005, .017897, .029896, .046262, .06535, .084001
0024 C * .099678, .111711, .120534, .126866, .131320, .134419/
0025 C ALOGT(0)=ALOG(0)/2.302585
0026 C CALL RMPAR(IO)
0027 C IF(IO(2).EQ.1)GO TO 1
0028 C CALL EXEC(4,1,ISTRK,IDISC,ISECT)
0029 C IO(3)=ISTRK
0030 C IO(4)=IDISC
0031 C 1 WRITE(10,4)
0032 C 4 FORMAT("TYPE NAME")
0033 C READ(10,2)NAME
0034 C 2 FORMAT(30A2)
0035 C WRITE(10,5)
0036 C 5 FORMAT("TYPE SIZE, NO.PTS, IOPT(NORMALLY 0)")
0037 C READ(10,*)SIZE,N,IOPT
0038 C IF(IOPT.EQ.0)GO TO 3
0039 C WRITE(10,6)
0040 C 6 FORMAT("TYPE N TURNS & CURRENT")
0041 C READ(10,*)NTURNS,AMPS
0042 C 3 WRITE(10,9)
0043 C 9 FORMAT("IF NEW TIMES ARE REQUIRED TYPE 1")
0044 C READ(10,*)IQ
0045 C IF(IQ.NE.1)GO TO 10
0046 C WRITE(10,7)
0047 C 7 FORMAT("TYPE IN TIMES (MS)")
0048 C READ(10,*)(T(I),I=1,N)
0049 C CALL EXEC(2,IO(4),T,N,IO(3),0)
0050 C 10 M=2*N
0051
0052

```

Program TERRY

```

0053      IF(C10.NE.1)CALL EXEC(1,I0(4),T,H,I0(3),0)
0054      WRITE(101,8)
0055      8 FORMAT("TYPE IN RESPONSE (UV)")
0056      READ(101,*) (V(I),I=1,N)
0057 C THIS SECTION IS IN CASE THE HP HAS TIMED YOU OUT
0058      WRITE(101,11)
0059      11 FORMAT(" TYPE 1 IF YOU WISH TO START AGAIN")
0060      READ(101,*)IR
0061      IF(IR EQ 1)GO TO 1
0062 C
0063 C THIS LOOP COMPUTES SIGMA FOR X LESS THAN 39
0064 C
0065      NUM:=0
0066      DO 20 I=1,N
0067      IF(I*OPT EQ 0)GO TO 17
0068      VALUE=AMPS*XNTURNS**2
0069      V(I)=V(I)/VALUE
0070      17 Y= 00039289*(V(I)*T(I)/SIZE
0071      IF(Y.GT 134)GO TO 19
0072      IF(Y.LT .01)GO TO 23
0073 C CALL THE INTERPOLATION FORMULA
0074      CALL AKIMI(B,-1 ,A,12,Y,-1 ,X,1)
0075      ITEST(I)=1
0076      GO TO 22
0077 C THIS SECTION USED FOR RANGE WHERE LEE'S EQN VALID
0078      23 ITEST(I)=0
0079      YPOW=Y**6.66667
0080      X=((+20.88351*YPOW+ 6.49229)*YPOW+2.38095)*YPOW+1.70998)*SQRT(YPOW
0081      1)
0082      22 SIGMA(I)=T(I)*10000 *((X/SIZE)**2)
0083      WRITE(46,18)Y,YPOW,X,SIGMA(I)
0084      18 FORMAT(" Y=",F14.7," YPOW=",F14.7," X=",F14.7," SIGMA=",F14.7)
0085 C
0086 C ITEST=0 IF VALUE HAS BEEN CALCULATED FROM FORMULA
0087 C =-1 IF VALUE IS OUTSIDE RANGE
0088 C =1 IF VALUE HAS COME FROM INTERPOLATION
0089 C
0090 C GO TO 20
0091      19 ITEST(I)=-1
0092      WRITE(46,16)Y
0093      16 FORMAT(" Y= ",F14.7," IS OUTSIDE RANGE")
0094      20 CONTINUE
0095 C
0096 C
0097      WRITE(46,34)NAME
0098      34 FORMAT(2X,30A2,/)
0099      WRITE(46,35)
0100      35 FORMAT(" TIME(MS) RESPONSE(UV/A) APP COND(S/M) APP RES(OHM,N)
0101      1 ITEST")
0102 C
0103      DO 40 I=1,N
0104      IF(ITEST(I) EQ -1)SIGMA(I)=.00012
0105      RO=1./SIGMA(I)
0106      WRITE(46,41)T(I),V(I),SIGMA(I),RO,ITEST(I)
0107      41 FORMAT(F8.2,4X,F10.4,3X,F10.6,5X,F10.4,6X,I8)

```

Program TERRY

```

0108      40 CONTINUE
0109 C
0110 C      THIS SECTION PLOTS THE CURVES
0111      CALL PLOTS(14.,12.,0.,-5.,-5.)
0112      CALL PLOT(1.,1.,-3)
0113      CALL LOGAX(-2.,-4,5,6,2.,1.5,LBLX,LBLY,NAME)
0114 C
0115      DO 50 I=1,N
0116      XX=ALOGT(T(I))
0117      YY=ALOGT(SIGMA(I))
0118      XX=(XX+2.)*2
0119      YY=(YY+4.)*1.5
0120      CALL SYMB(XX,YY, 03,1,0,.-1)
0121      50 CONTINUE
0122      IO(2)=1
0123 C
0124      CALL PLOT(0.,0.,999)
0125      CALL EXEC(10,TERRZ,IO(1),IO(2),IO(3),IO(4),IO(5))
0126      CALL GOPLT
0127 C
0128      STOP
0129      END
0130      END$

```

Program TERRY

```
0001  FIN4
0002      PROGRAM TERRZ
0003      INTEGER TERRY(3)
0004      DIMENSION IO(5)
0005      DATA TERRY/2HTE,2HRR,2HY /
0006      CALL RMPAR(IO)
0007      CALL EXEC(10,TERRY,IO(1),IO(2),IO(3),IO(4),IO(5))
0008      STOP
0009      END
0010      END%
```

Subroutine TERRZ

```

0001  F7N4
0002      SUBROUTINE AKIMI(X,DX,Y,N,Z,DZ,V,M)
0003      DIMENSION X(1),Y(1),Z(1),V(1)
0004  C
0005  C      INTERPOLATION ROUTINE BY AKIMA
0006  C      INPUT DATA
0007  C          X(1),Y(1),I=1,N
0008  C          DX=SPACING, ==VE IF DIFFERENT
0009  C          Z=ABSCISSAE FOR POINTS FOR INTERPOLATION
0010  C          DZ=SPACING, ==VE IF DIFFERENT
0011  C          V= ORDINATES INTERPOLATED
0012  C          M= NO OF INTERPOLATIONS
0013  C          DZ=SPACING, ==VE IF DIFFERENT
0014  C
0015      T=Z(1)
0016      IT=1
0017      XN=X(1)+(N-1)*DX
0018      IF(DX.LE 0.) XN=X(N)
0019  C *** GET DIFFS BETWEEN ABSCISSA OF 1ST 3 POINTS
0020      D21=DX
0021      IF(DX.LE 0.) D21=X(2)-X(1)
0022  C *** GET FIRST 4 CHORDAL SLOPES
0023      C3=(Y(2)-Y(1))/D21
0024      D32=DX
0025      IF(DX.LE 0.) D32=X(3)-X(2)
0026      C4=(Y(3)-Y(2))/D32
0027      C2=C3+C3-C4
0028      C1=C2+C2-C3
0029  C *** GET 1ST SLOPE
0030      C=(ABS(C4-C3)*C2+ABS(C2-C1)*C3)
0031      D=ABS(C4-C3)+ABS(C2-C1)
0032  C *** SET SLOPE AT POINT
0033      S1=(C2+C3)/2
0034      IF(D.GT 1.E-10) S1=C/D
0035  C *** SET SECTION COUNT
0036      I=2
0037  C *** SHIFT CHORDAL SLOPES
0038      1 C1=C2
0039      C2=C3
0040      C3=C4
0041      C4=C3+C3-C2
0042      IF(I.GE.N-1) GO TO 2
0043      DIF=DX
0044      IF(DX.LE 0.) DIF=X(I+2)-X(I+1)
0045  C *** GET NEW CHORDAL SLOPE
0046      C4=(Y(I+2)-Y(I+1))/DIF
0047      2 C=(ABS(C4-C3)*C2+ABS(C2-C1)*C3)
0048      D=ABS(C4-C3)+ABS(C2-C1)
0049  C *** GET SLOPE AT NEXT POINT
0050      S2=(C2+C3)/2
0051      IF(D.GT 1.E-10) S2=C/D
0052      DIF=DX

```

Subroutine AKIMI

```

0053      IF (DX .LT. 0) DIF=X(I)-X(I-1)
0054 C *** CALCULATE POLYNOMIAL COEFFS
0055      P1=S1
0056      P2=(3 *C2 -S1-S1-S2)/DIF
0057      P0=Y(I-1)
0058      P3=(S1+S2-C2-C2)/(DIF*DIF)
0059 C *** SET XA AND XB AS ABSCISSAE OF 2 EXTREEMS OF POLYNOMIAL
0060      XA=X(I)-(I-2)*DX
0061      XB=XA+DX
0062      IF (DX .GT. 1 E-10) T=Z(IT)
0063      XA=X(I-1)
0064      XB=X(I)
0065      3 IF (T .LE. XB OR T .GT. XN) GO TO 4
0066 C *** ADVANCE TO NEXT PAIR OF POINTS
0067      S1=S2
0068      I=I+1
0069      GO TO 1
0070 C *** CALCULATE POLYNOMIAL BETWEEN POINTS
0071      4 A=T-XA
0072      V(IT)=P0+A*(P1+A*(P2+A*P3))
0073      IT=IT+1
0074      IF (IT .GT. M) RETURN
0075      T=T+DX
0076      IF (DZ .LE. 0) T=Z(IT)
0077      GO TO 3
0078      END
0079      END*

```

Subroutine AKIMI

```

0001  FTN4,B
0002  C
0003  C *** "LOGAX"
0004  C
0005  C      DRAWS AND ANNOTATES LOG-LOG PLOT AXES
0006  C
0007  C      SUBROUTINE LOGAX(LX0,LY0,NXC,NYC,SCX,SCY,LBLX,LBLY,NAME)
0008  C      INTEGER FPN(4)
0009  C      DIMENSION LBLX(15),LBLY(15),NAME(30)
0010  C      DATA ALG10/2.302585/
0011  C      ALOGT(X)=ALOG(X)/ALG10
0012  C
0013  C *** DRAW PLOT AXES
0014  C
0015  C      CALL PLOT(FLOAT(NXC)*SCX,0,2)
0016  C      CALL PLOT(FLOAT(NXC)*SCX,FLOAT(NYC)*SCY,2)
0017  C      CALL PLOT(0,FLOAT(NYC)*SCY,2)
0018  C      CALL PLOT(0,0,2)
0019  C
0020  C *** SCALE OFF 'X' AXIS
0021  C
0022  C      Y0=0
0023  C      Y1=SCY*.05
0024  C      DO 115 K=1,2
0025  C      DO 110 J=1,NXC
0026  C      XC=FLOAT(J-1)*SCX
0027  C      DO 105 I=1,10
0028  C      X=XC+ALOGT(FLOAT(I))*SCX
0029  C      CALL PLOT(X,Y0,3)
0030  C      CALL PLOT(X,Y1,2)
0031  C      105 CONTINUE
0032  C      110 CONTINUE
0033  C      Y0=FLOAT(NYC)*SCY
0034  C      Y1=Y0-SCY*.05
0035  C      115 CONTINUE
0036  C
0037  C *** SCALE OFF 'Y' AXIS
0038  C
0039  C      X0=0
0040  C      X1=SCX*.05
0041  C      DO 130 K=1,2
0042  C      DO 125 J=1,NYC
0043  C      YC=FLOAT(J-1)*SCY
0044  C      DO 120 I=1,10
0045  C      Y=YC+ALOGT(FLOAT(I))*SCY
0046  C      CALL PLOT(X0,Y,3)
0047  C      CALL PLOT(X1,Y,2)
0048  C      120 CONTINUE
0049  C      125 CONTINUE
0050  C      X0=FLOAT(NXC)*SCX
0051  C      X1=X0-SCX*.05
0052  C      130 CONTINUE

```

Subroutine LOGAX

```

0053 C
0054 C *** ANNOTATE 'X' AXIS
0055 C
0056 LOG=LX0
0057 Y=-SCY*1
0058 HT= .05*SCY
0059 DO 135 I=1,NXC
0060 X=FLOAT(I-1)*SCX-2 *HT
0061 Z=10 *XLOG+ 1E-4
0062 CALL CODE
0063 WRITE(FPN,310) Z
0064 310 FORMAT(E2,1)
0065 CALL SYMB(X,Y,HT,FPN,0.,8)
0066 LOG=LOG+1
0067 135 CONTINUE
0068 C
0069 C *** ANNOTATE 'Y' AXIS
0070 C
0071 LOG=LY0
0072 X=-SCX*05
0073 HT= .05*SCX
0074 DO 140 I=1,NYC
0075 Y=FLOAT(I-1)*SCY-2 *HT
0076 Z=10 *XLOG+ 1E-4
0077 CALL CODE
0078 WRITE(FPN,310) Z
0079 CALL SYMB(X,Y,HT,FPN,90.,8)
0080 LOG=LOG+1
0081 140 CONTINUE
0082 C
0083 C *** LABEL PLOT
0084 C
0085 HT=(FLOAT(NXC)*SCX)/40
0086 X=2 *HT
0087 Y=(FLOAT(NYC))*SCY+HT
0088 CALL SYMB(X,Y,HT,NAME,0.,40)
0089 C
0090 C *** LABEL X,Y AXES
0091 C
0092 X=SCX
0093 Y=-.25*SCY
0094 CALL SYMB(X,Y,.08*SCY,LBLX,0.,30)
0095 X=-.18*SCX
0096 Y=SCY*.5
0097 CALL SYMB(X,Y,.08*SCX,LBLY,90.,30)
0098 RETURN
0099 END
0100 END#

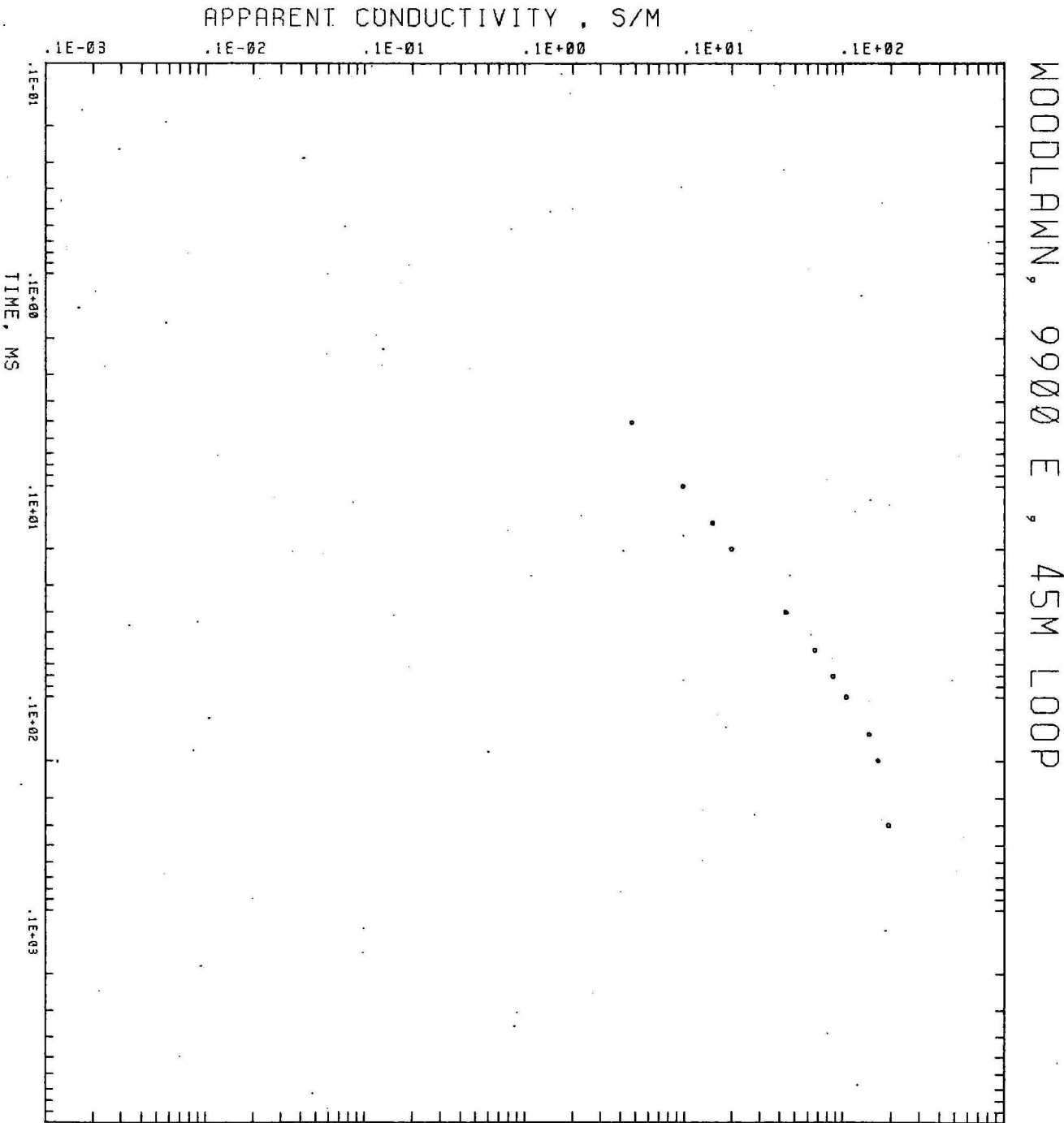
```

Subroutine LOGAX

Y=	0123758	YPCW=	0000000	X=	4454002	SIGMA=	.9796E11
Y=	0128551	YPCW=	.0000000	X=	.4532643	SIGMA=	1.5218410
Y=	0126087	YPCW=	.0000000	X=	.4492165	SIGMA=	1.9930410
Y=	0138704	YPCW=	.0000000	X=	.4683104	SIGMA=	4.3321400
Y=	0144301	YPCW=	.0000000	X=	.4735245	SIGMA=	6.6437168
Y=	.0140057	YPCW=	.0000000	X=	.4687335	SIGMA=	8.6799469
Y=	0135283	YPCW=	.0000000	X=	.4627439	SIGMA=	10.5744171
Y=	0123081	YPCW=	.0000000	X=	.4441876	SIGMA=	14.6150074
Y=	0106104	YPCW=	.0000000	X=	.4102144	SIGMA=	16.6198349
Y=	0053759	YPCW=	.0306880	X=	.3132842	SIGMA=	19.3870621

WOODLAWN, 9900 E , 45M LOOP

TIME(MS)	RESPONSE(UV/A)	APP COND(S/M)	APP RES(OHM.M)	ITEST
50	2700 0000	.472736	2.1153	1
1 00	1400 0000	.979661	1.0208	1
1 50	970 0000	1.521841	.6571	1
2 00	713 0000	1.993041	.5017	1
4 00	395 0000	4.332140	.2308	1
6 00	272 0000	6.643717	.1505	1
8 00	195 0000	8.679947	.1152	1
10 00	153 0000	10.574417	.0946	1
15 00	92 8000	14.615007	.0684	1
20 00	60.0000	16.619835	.0602	1
40 00	15.2030	19.387062	.0516	0



```

0001  FTN4
0002  PROGRAM HOMOG
0003  C COMPUTES THE TEM RESPONSE OF A HOMOGENEOUS HALFSPACE
0004  C INPUT DATA IS
0005  C COND=CONDUCTIVITY
0006  C SHAPE=SQUARE OR CIRCLE
0007  C SIZE=SIDE LENGTH OR RADIUS
0008  C SI UNITS USED THROUGHOUT
0009  C
0010  INTEGER SHAPE(3)
0011  REAL COND
0012  DIMENSION V(60),T(60),ITEST(60),IO(5)
0013  EQUIVALENCE(IO(1),IO1)
0014  CALL RHPAR(10)
0015  1 WRITE(101,2)
0016  2 FORMAT(" TYPE IN CONDUCTIVITY AND SIZE")
0017  READ(101,*)COND,SIZE
0018  IF(COND.LE.0)STOP
0019  WRITE(101,3)
0020  3 FORMAT(" SQUARE OR CIRCLE?")
0021  READ(101,4)SHAPE
0022  4 FORMAT(3A1)
0023  RES=1/COND
0024  WRITE(101,5)SIZE,SHAPE,COND,RES
0025  WRITE(6,5)SIZE,SHAPE,COND,RES
0026  5 FORMAT(" HOMOGENEOUS HALFSPACE ",F9.2," M ",3A2," LOOP",/, " CON
0027  DUCTIVITY= ",F8.4," S/M, RESISTIVITY = ",F8.4," OHM-M")
0028  CALL HALF(SIZE,SHAPE,COND,T,V,ITEST)
0029  C
0030  C NOW PRINT ANSWERS
0031  WRITE(6,6)
0032  6 FORMAT(" TIME(MS) RESPONSE(UV/A) ITEST")
0033  DO 10 I=1,55
0034  IF(ITEST(I)EQ.-1)GO TO 8
0035  C NOW FORMAT FOR MS AND UV
0036  TMS=T(I)*1000
0037  VUV=V(I)*1.E6
0038  WRITE(6,7)TMS,VUV,ITEST(I)
0039  7 FORMAT(F8.2,4X,F10.4,3X,16)
0040  GO TO 10
0041  8 TMS=T(I)*1000
0042  WRITE(6,9)TMS,ITEST(I)
0043  9 FORMAT(F8.2,4X," - " ,18)
0044  10 CONTINUE
0045  GO TO 1
0046  END
0047  END#

```

Program HOMOG

```

1  FTN4,B
2  PROGRAM TEMHF
3  C THIS PROGRAM PRODUCES AND PROVIDES DATA TO PRODUCE STANDARD CURVES
4  C FOR TEM RESPONSE OF HOMOGENEOUS HALFSACES
5  C INPUT DATA IS
6  C COND=CONDUCTIVITY
7  C SIZE=SIDE LENGTH OR RADIUS
8  C SMIN=LOWER SIZE LIMIT FOR LOOP
9  C SI UNITS USED THROUGHOUT
10 C
11 INTEGER SHAPE(3)
12 REAL COND,COND1,CONDIV
13 DIMENSION LABLY(4),LABLY(6),ISIZE(4),T(60),V(60),ITEST(60),IO(5)
14 EQUIVALENCE(IO(1),IO1)
15 DATA LABLY(2HT),ZHT,2HME,2HCM,2HS)
16 DATA LABLY(2HRE,2HSE,2HON,2HSE,2HCM,2HV)
17 ALOGT(0)=ALOG(0)/2 .302585
18 TH01(0)=1000 .0
19 C 11. COMPARE(10)
20 C
21 C 12. 100 100 100
22 C 13. 100 100 100 IN COND. 100 100 100
23 READ(101,*)COND,SIZE,SMIN
24 WRITE(101,3)
25 3 FORMAT(" TYPE IN SHAPE")
26 READ(101,4)SHAPE
27 4 FORMAT(3A2)
28 WRITE(101,5)
29 5 FORMAT(" TYPE IN SIZE & CONDUCTIVITY DIVISION FACTORS")
30 READ(101,*)SIZED,CONDIV
31 WRITE(101,6)
32 6 FORMAT(" TYPE IN LX0,LY0,NXC,NYC,SCX,SCY")
33 READ(101,*)LX0,LY0,NXC,NYC,SCX,SCY
34 C
35 C THIS LOOP IS FOR CHANGE IN LOOP SIZE
36 DO 90 L=1,30
37 COND=COND1
38 IF(SIZE LT SMIN)GO TO 100
39 CALL CODE
40 WRITE(101,11)SIZE
41 11 FORMAT(F8.2)
42 WRITE(13,12)ISIZE,SHAPE
43 WRITE(13,13)LABLY
44 WRITE(13,14)LABLY
45 WRITE(13,15)LX0,LY0,NXC,NYC,SCX,SCY
46 12 FORMAT(2A2)
47 13 FORMAT(4A2)
48 14 FORMAT(6A2)
49 15 FORMAT(4(13,1H.),F6.2,1H.,F7.2)
50 C
51 C THIS LOOP IS FOR CHANGE IN CONDUCTIVITY
52 DO 70 K=1,100
53 IF(COND.LT. .0001)GO TO 80
54 WRITE(6,21)COND,SIZE,SHAPE

```

Program TEMHF

```

55      21 FORMAT(" TRANSIENT DECAY CURVE FOR HALFSpace , CONDUCTIVITY=",F8.4
56      1" S/M" ,F9.2 " METRES",2X,3A2,2X," LOOP," )
57      WRITE(6,22)
58      22 FORMAT(17 " TIME(MS)      RESPONSE(MV)  ITEST")
59      NCOUNT=0
60      C NOW CALCULATE VALUES FOR ONE DECAY CURVE
61      CALL HALF(SIZE,SHAPE,COND,T,V,ITEST)
62      DO 24 I=1,55
63      TMS=THOU(T(I))
64      IF (ITEST(I) LT 0) V(I)=0
65      VMV=THOU(V(I))
66      WRITE(6,23)TMS,VMV,ITEST(I)
67      23 FORMAT(F9.4,F15.6,I6)
68      IF (VMV LT .0001 OR VMV GT 100.) GO TO 24
69      NCOUNT=NCOUNT+1
70      24 CONTINUE
71      IF (NCOUNT EQ 0) GO TO 60
72      WRITE(13,25)NCOUNT
73      25 FORMAT(I2)
74      DO 26 I=1,55
75      TMS=THOU(T(I))
76      VMV=THOU(V(I))
77      IF (VMV LT .0001 OR VMV GT 100.) GO TO 26
78      WRITE(13,27)TMS,VMV
79      27 FORMAT(E12.5,1H, E12.5)
80      26 CONTINUE
81      60 COND=COND/CONDIV
82      70 CONTINUE
83      80 SIZE=SIZE/SIZED
84      WRITE(13,15)NN
85      90 CONTINUE
86      100 ENDFILE 13
87      ENDFILE 13
88      STOP
89      END
90      END$

```

Program TEMHF

```

0001  FTH4
0002      SUBROUTINE HALF(SIZE, SHAPE, COND, T, V, ITEST)
0003  C    COMPUTES THE TEM RESPONSE OF A HOMOGENEOUS HALFSpace
0004  C    INPUT DATA IS
0005  C          COND=CONDUCTIVITY
0006  C          SHAPE=SQUARE OR CIRCLE
0007  C          SIZE=SIDE LENGTH OR RADIUS
0008  C    OUTPUT TIMES RANGE FROM 0.1 TO 100 MS.
0009  C    SI UNITS USED THROUGHOUT.
0010  C
0011      INTEGER SHAPE(3)
0012      REAL COND
0013      DIMENSION V(60), T(60), ITEST(60), IO(5), A(12), B(12)
0014      EQUIVALENCE(IO(1), I01)
0015      DATA A/ .39716, .5, .62946, .79245, .99763, 1.25594,
0016      *1.58114, 1.90054, 2.5059, 3.15478, 3.9717, 5./
0017      DATA B/ .01005, .017897, .029896, .046262, .06535, .084001,
0018      * .099678, .111711, .120534, .126866, .131320, .134419/
0019      FACTR=1
0020      IF(SHAPE(1) EQ 2HSQ) FACTR=.56419
0021  C
0022      IFLAG=0
0023      TIME=.00005
0024      DO 20 I=1,3
0025      II=10**I
0026      TINC=.000005**II
0027      DO 20 J=1,19
0028      IF(I NE 1 AND J EQ 1) GO TO 20
0029      TIME=TIME+TINC
0030  C    NOW CALCULATE THE RESPONSE
0031  C    ITEST=0 IF VALUE IS CALCULATED FROM FORMULA
0032  C    =-1 IF VALUE IS OUTSIDE RANGE
0033  C    =1 IF VALUE COMES FROM INTERPOLATION
0034      IFLAG=IFLAG+1
0035      X=.605E-4*SIZE*FACTR*SQRT(COND/TIME)
0036      IF(X.LT. 4) GO TO 15
0037      IF(X.GT. 5) GO TO 18
0038  C    CALL THE INTERPOLATION FORMULA
0039      CALL AKIMI(A, -1, B, 12, X, -1, Y, 1)
0040      ITEST(IFLAG)=1
0041      GO TO 16
0042  C    THIS SECTION USED WHEN LEE'S EQN VALID
0043      15 Y=(X*(.584803-.27848***2+.13813***4-.05414***6))**3
0044      ITEST(IFLAG)=0
0045      16 V(IFLAG)=4.454E-6*SIZE*FACTR*Y/TIME
0046      GO TO 19
0047      18 ITEST(IFLAG)=-1
0048      19 T(IFLAG)=TIME
0049      20 CONTINUE
0050      RETURN
0051      END
0052  ENDIF

```

Subroutine HALF

HOMOGENEOUS HALFSPACE 45.00 M SQUARE LOOP
 CONDUCTIVITY= 5000 S/M, RESISTIVITY = 2.0000 OHM-M

TIME (MS)	RESPONSE (UV/A)	ITEST
10	74749.3437	1
15	37019.1094	1
20	21557.4414	1
25	13831.0762	1
30	9513.4883	1
35	6870.2246	1
40	5136.6475	1
45	3955.0664	1
50	3128.4136	1
55	2525.5391	1
60	2071.0239	1
65	1727.2839	0
70	1456.4297	0
75	1241.5156	0
80	1068.4985	0
85	927.4431	0
90	811.1405	0
95	714.2744	0
1 00	632.8608	0
1 50	240.5064	0
2 00	119.9321	0
2 50	69.6300	0
3 00	44.5605	0
3 50	30.5160	0
4 00	21.9665	0
4 50	16.4287	0
5 00	12.6645	0
5 50	10.0055	0
6 00	8.0670	0
6 50	6.6181	0
7 00	5.5059	0
7 50	4.6399	0
8 00	3.9533	0
8 50	3.4009	0
9 00	2.9503	0
9 50	2.5799	0
10 00	2.2712	0
15 00	.8281	0
20 00	.4044	0
25 00	.2318	0
30 00	.1471	0
35 00	.1001	0
40 00	.0717	0
45 00	.0535	0
50 00	.0411	0
55 00	.0324	0
60 00	.0261	0
65 00	.0213	0
70 00	.0177	0
75 00	.0149	0
80 00	.0127	0
85 00	.0109	0
90 00	.0095	0
95 00	.0083	0
100 00	.0073	0

Computer output from program HOMOG

```

1  FTN4,B
2  C
3  C   'LCOMP' WILL PLOT A CONTINUOUS LOG-LOG CURVE
4  C   ON THE CALCOMP FROM A DISCRETE SET OF DATA
5  C   POINTS WHERE  X(I+1) > X(I)
6  C   THIS HAS THE SAME FUNCTION AS LGRPH.
7  C
8      PROGRAM LCOMP
9      DIMENSION LBLX(15),LBLY(15),NAME(30),IC(5),X(99),Y(99)
10     COMMON IOP(5)
11     DATA M1/2H-1/
12     CALL RMPAR(10)
13     IO1=IO(1)
14     DO 105 I=1,5
15     IOP(I)=IO(1)
16 105 CONTINUE
17     CALL PLOTS(0,0,7)
18 C *** READ PLOT TITLE, AXIS LABELS
19     5 READ(IO1,201)NAME
20     IF(NAME(1).EQ.M1)GO TO 30
21     READ(IO1,201)LBLX
22     READ(IO1,201)LBLY
23     201 FORMAT(30A2)
24 C *** READ PLOT BOUNDS INFORMATION
25     READ(IO1,*)LX0,LY0,NXC,NYC,SCX,SCY
26     CALL PLOT(SCX,.5*SCY,-3)
27     CALL LOGAX(LX0,LY0,NXC,NYC,SCX,SCY,LBLX,LBLY,NAME)
28     NPLTS=0
29 C *** READ NO. POINTS FOR PLOTTING
30     10 READ(IO1,*)N
31     IF(N.LE.0)GO TO 20
32     DO 110 I=1,N
33 C *** READ DISCRETE X,Y POINTS
34     READ(IO1,*)X(I),Y(I)
35     X(I)=ALOG(X(I))/2.302585
36     Y(I)=ALOG(Y(I))/2.302585
37 110 CONTINUE
38     CALL INTPL(N,X,Y,LX0,LY0,NXC,NYC,SCX,SCY)
39     NPLTS=NPLTS+1
40     FLX0=FLOAT(LX0)
41     FLY0=FLOAT(LY0)
42     DO 120 I=1,N
43     CALL SYMB((X(I)-FLX0)*SCX,(Y(I)-FLY0)*SCY,
44     *.05,5,0.,-1)
45 120 CONTINUE
46     GO TO 10
47     20 CALL PLOT(FLOAT(NXC+2)*SCX,0.,-3)
48     GO TO 5
49     30 CALL PLOT(0.,0.,999)
50     STOP
51     END
52     END#

```

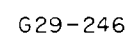
Subroutine LCOMP

```

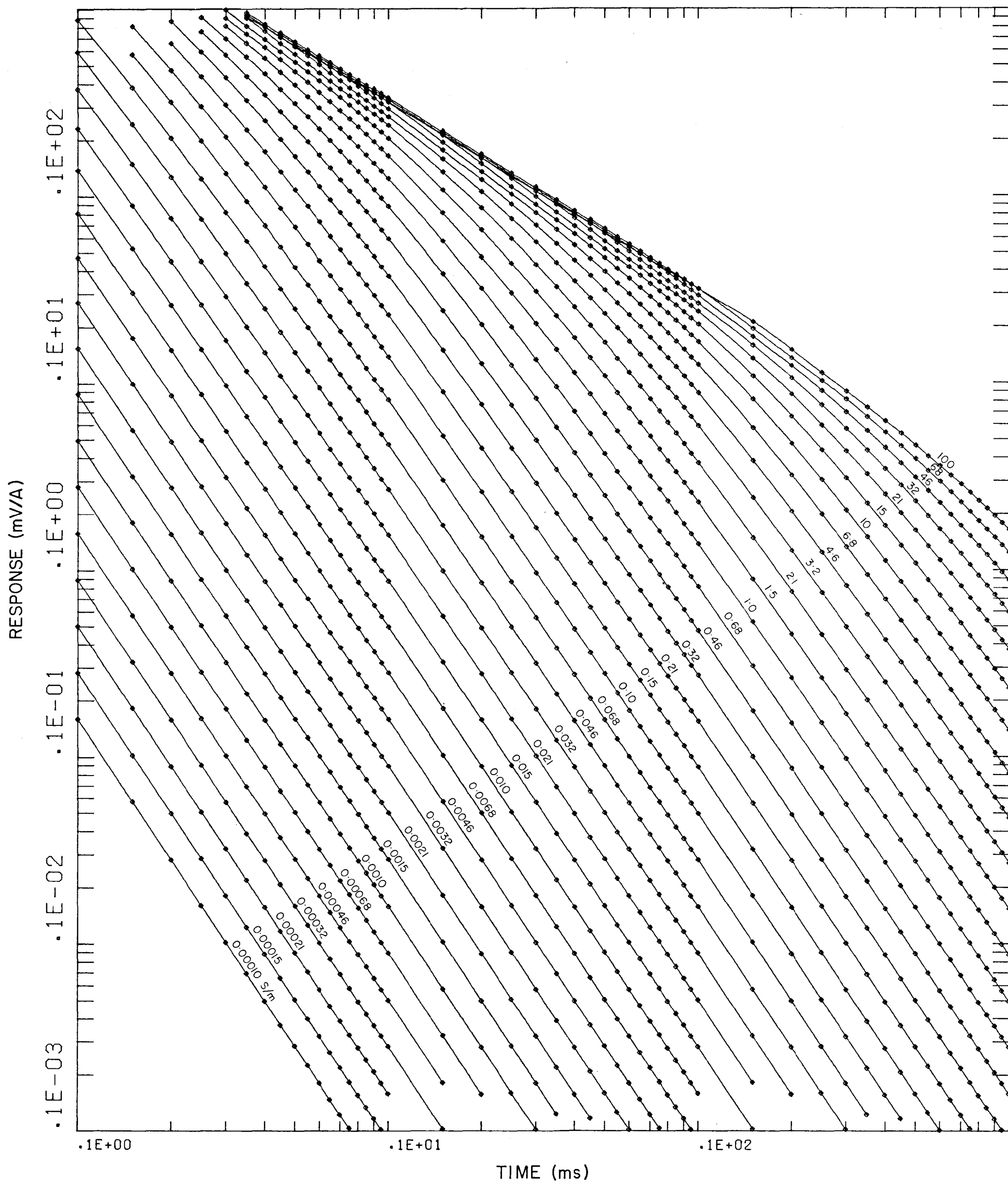
0001  FTN4.B
0002  SUBROUTINE INTPL(N,X,Y,LX0,LY0,NXC,NYC,SCX,SCY)
0003  DIMENSION X(51),Y(51),Z(2),V(51)
0004  COMMON IOP(5)
0005  IOS=IOP(2)
0006  NOP1=50
0007  FNOP1=FLOAT(NOP1)
0008  NPTS=IFIX((X(N)-X(1))*SCX*FNOP1)+1
0009  SINT=1/(SCX*FNOP1)
0010  S=X(1)
0011  IP=3
0012  DO 150 I=1,NPTS
0013  Z(1)=S
0014  CALL AKIMA(X,0.,Y,N,Z,0.,V,1)
0015  CALL LOGGR(10,*,S,10,*,V(1),
0016  ,LX0,LY0,NXC,NYC,SCX,SCY,IP)
0017  IP=2
0018  S=S+SINT
0019  150 CONTINUE
0020  RETURN
0021  END
0022  END#

```

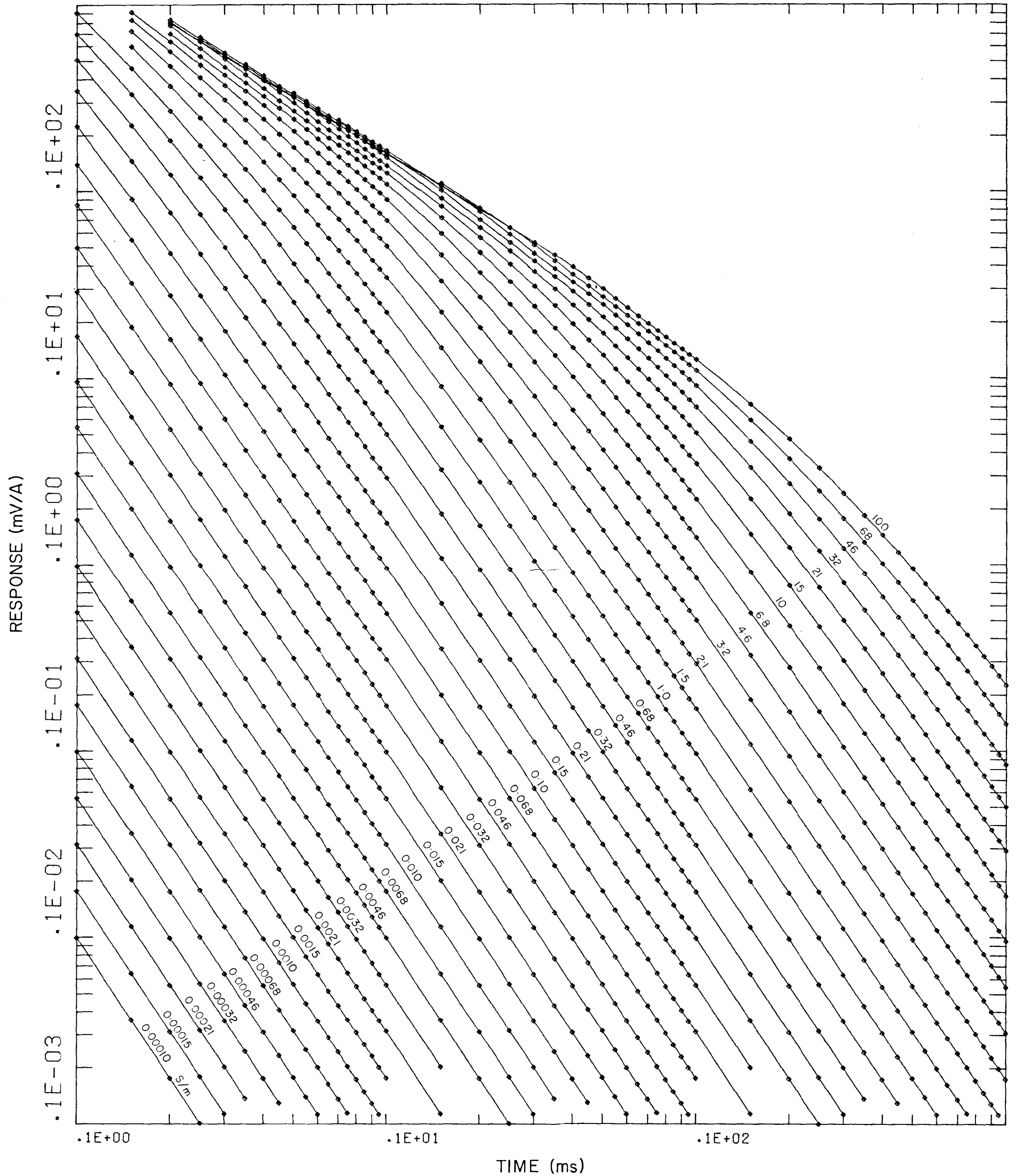
Subroutine INTPL



100.0m SQUARE LOOP

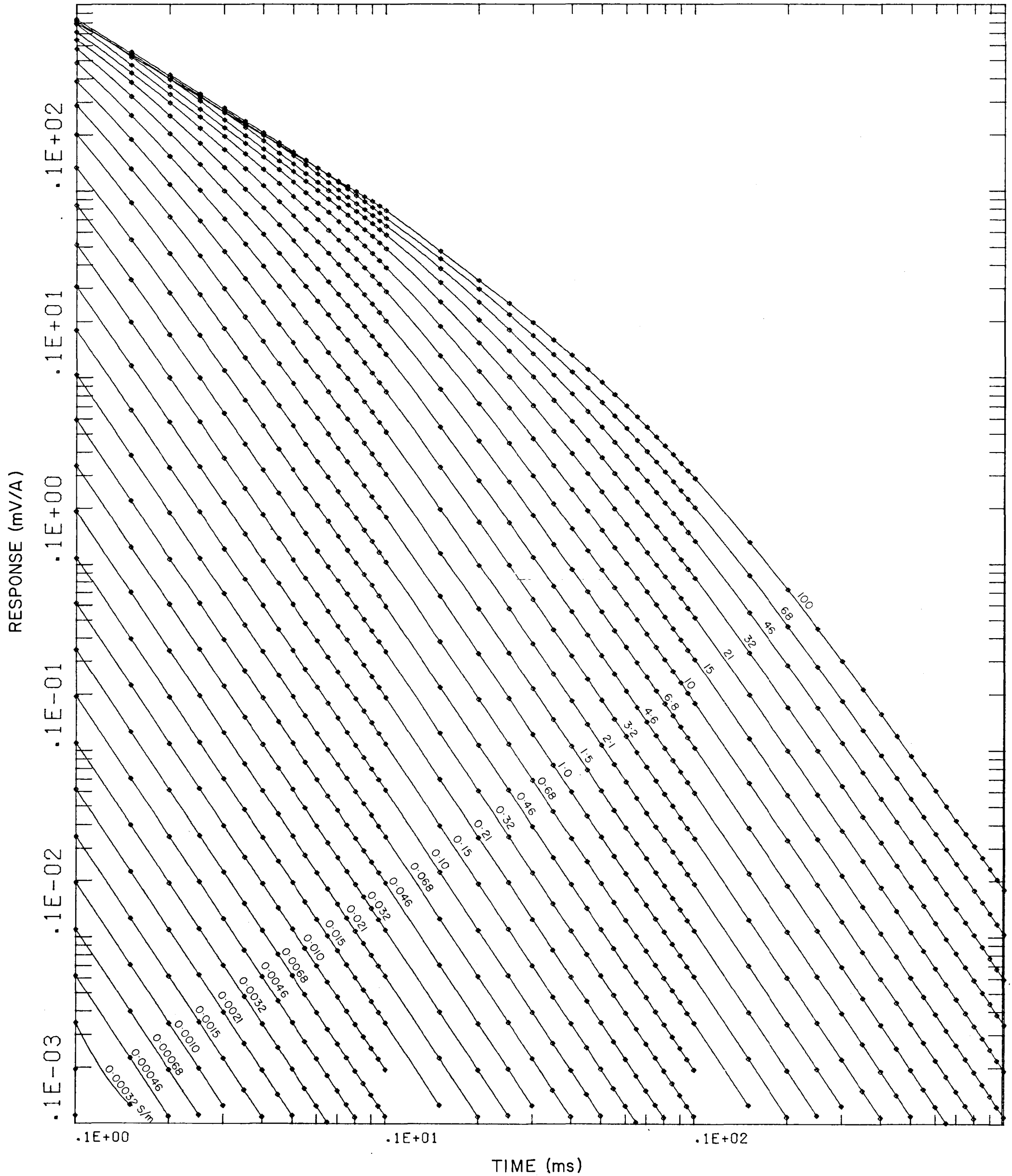


50.0m SQUARE LOOP



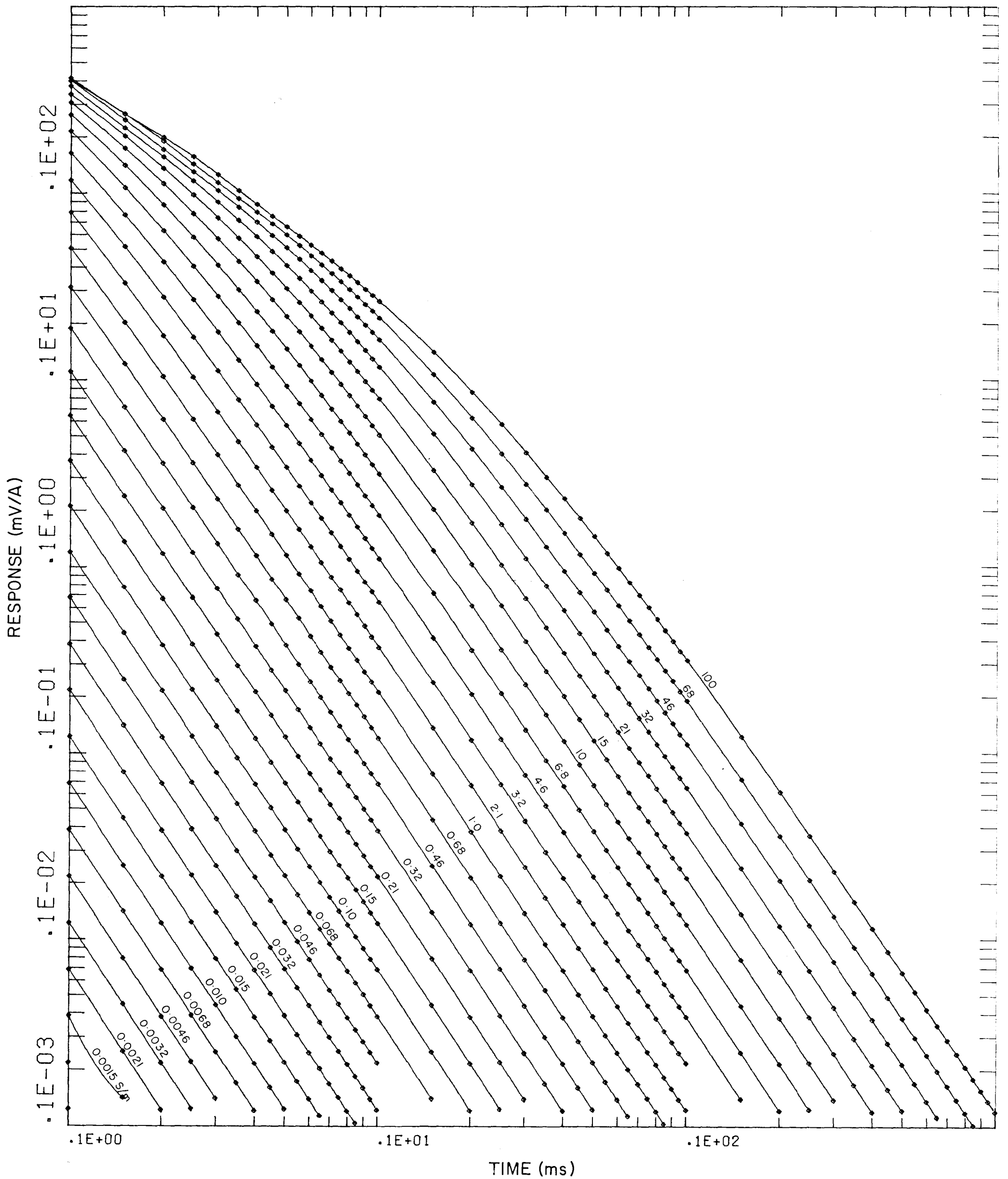
Standard curves for TEM response of homogeneous half-space (50m loop)

25.0m SQUARE LOOP



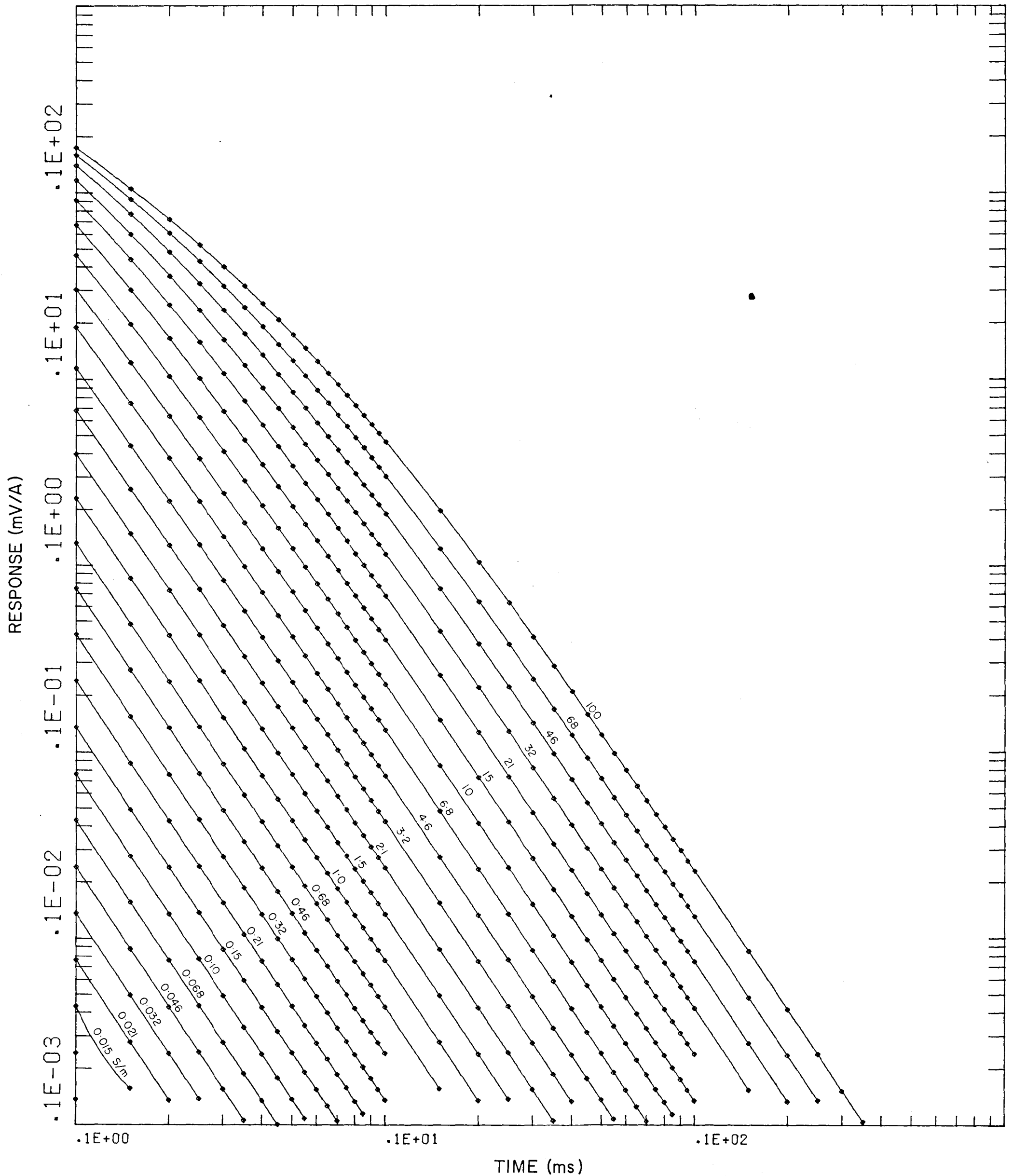
Standard curves for TEM response of homogeneous half-space (25m loop)

12.5m SQUARE LOOP



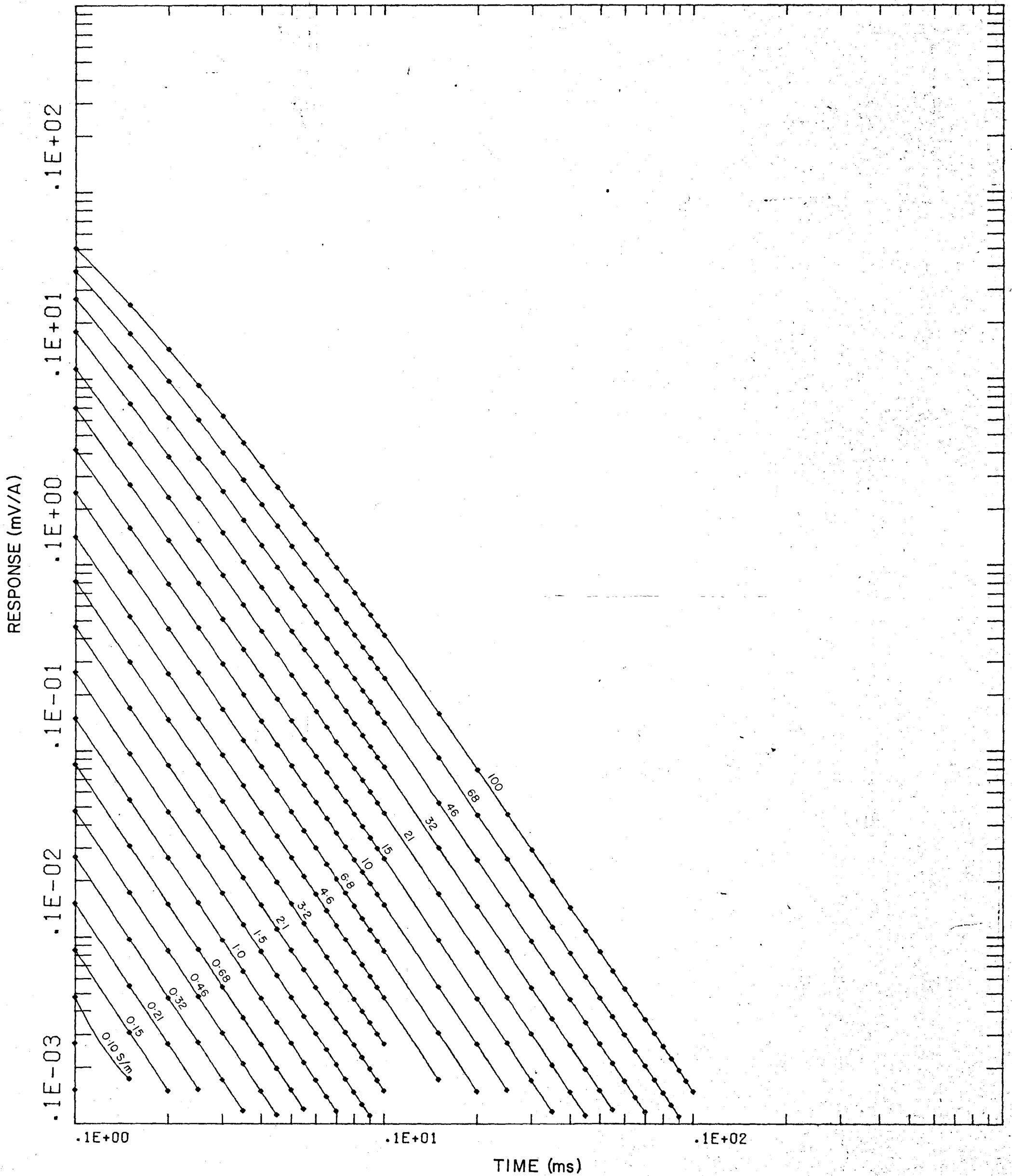
Standard curves for TEM response of homogeneous half-space (12.5m loop)

6.25m SQUARE LOOP

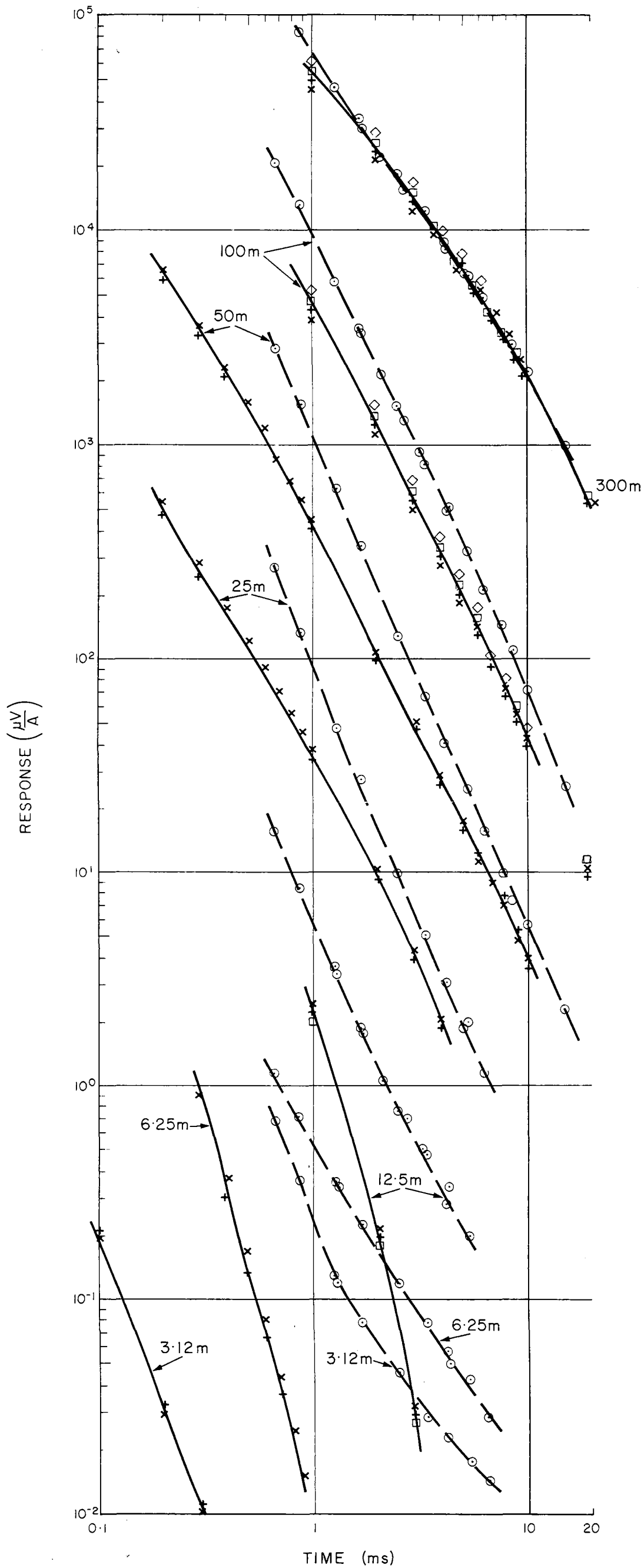


Standard curves for TEM response of homogeneous half-space (6.25m loop)

3.12m SQUARE LOOP



Standard curves for TEM response of homogeneous half-space (3.12m loop)



RESISTIVITY INVERSION MODELS

MODEL 1	
0.0477 S/m	0 m
0.606 S/m	20.1 m
0.513 S/m	38.9 m
0.0122 S/m	296 m

MODEL 2	
0.0493 S/m	0 m
0.682 S/m	21.8 m
0.0148 S/m	292 m

MODEL 3	
0.0477 S/m	0 m
0.548 S/m	19.8 m
0.0143 S/m	314 m

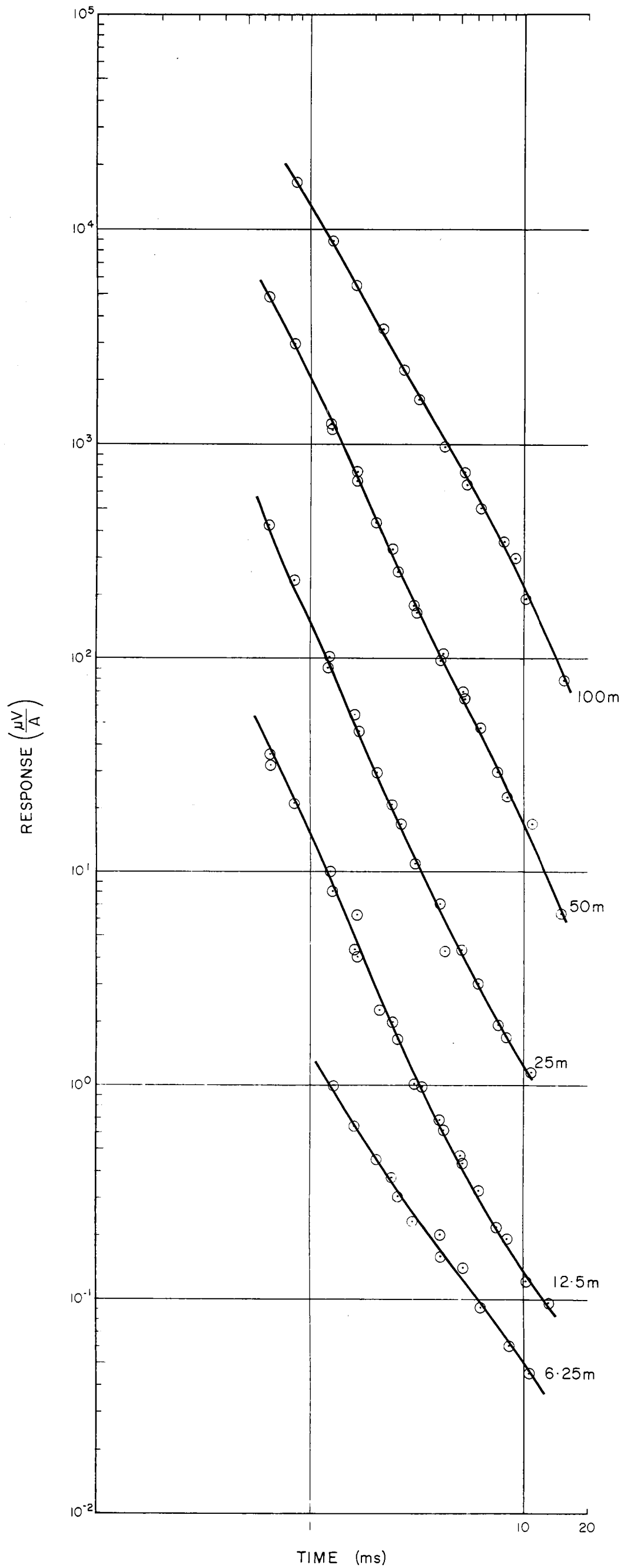
MODEL 4	
0.0491 S/m	0 m
0.361 S/m	21.1 m
0.593 S/m	8 m
0.0152 S/m	279 m

TEM RESULTS

- Observed (field) reading
- x Model 1
+ Model 2
□ Model 3
◇ Model 4
- } Computed TEM values

LOOP SIZE (m)	CURRENT (A)	No. TURNS
300	0.5	1
100	2.0	1
50	3.0	1
25	3.0	1
12.5	2.0	3
6.25	2.0	6
3.12	2.0	12

Pooncarie, N S W : Geoelectric section and TEM results



RESISTIVITY INVERSION MODEL

0.005 S/m	0 m
0.3 S/m	0.7m
0.2 S/m	4 m
2.0 S/m	25m
0.7 S/m	160 m

TEM RESULTS

⊙ Observed (field) reading

LOOP SIZE (m)	CURRENT (A)	No. TURNS
100	2.0	1
50	2.5	1
25	2.5	2
12.5	2.5	4
6.25	2.0	4

Pirlta, Vic.: Geoelectric section and TEM results