

# Australian Geographic Reference Image (AGRI) Product Information

V1.2

28 August 2015

**Unclassified** 

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# **Document History**

Revision Number	Date	Nature of Change and Reason	Author	Approval
V0.1	10/10/13	Drafted document	R. Coghlan L.W Wang	
V1.0	13/03/14	Final version incorporating PDMG edits and removal of extraneous Platform and Sensor fields.	Chris Penning	For approval
V1.1	6/05/14	Added Geocat reference	Adam Lewis	Approved
V1.2	28/08/15	Minor edits to copyright	Arek Drozda	Adam Lewis D2015- 147919

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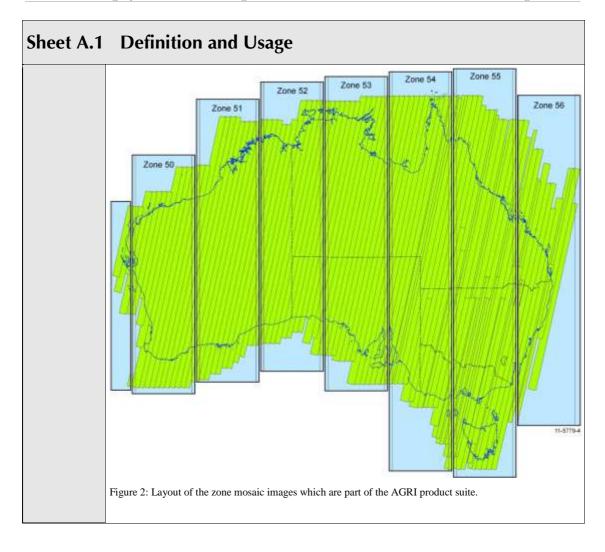
# **A** Description

Sheet A.1 Definition and Usage					
Product Name	Australian Geographic Reference Image				
Abbreviatio n	AGRI				
Product Suite	Australian Ge	ographic Reference Im	age		
Key Features of Product Suite	- UTM zone - Ground Cor	osaic - 10m georeferen mosaics - 2.5m georefe ntrol Point spatial datak ntrol Point ancillary dat	renced images	nes and image chips).	
Product Overview	The Australian Geographic Reference Image (AGRI) is a consistent and accurate reference image for rectification of imagery from multiple sources at resolutions of 2.5 metres or less The AGRI can ensure that images are consistently and accurately registered to allow the maximum extraction of information. The AGRI provides a consistent base image which will be an important foundation for future mapping and monitoring across Australia. It is a resource for both users and providers of satellite imagery covering Australia in government agencies, research institutions and academia, the spatial information industry, and international satellite operators.				
Planned	Version	Features List features that are relevant to successive versions of this p The following three features describe the ARG suite of pro		ARG suite of products.	
Product		Image Data Input	Radiance Corrections	<b>Geometric Presentation</b>	
Versions	Current- V1.0	ALOS PRISM archive from 2006 to 2010	Radiometric correction using calibration ancillary provided by JAXA	Mosaics projected to WGS84 geographic and UTM grid	
Product Background	V1.0   If of the 2010   afficility provided by   LITM grid				

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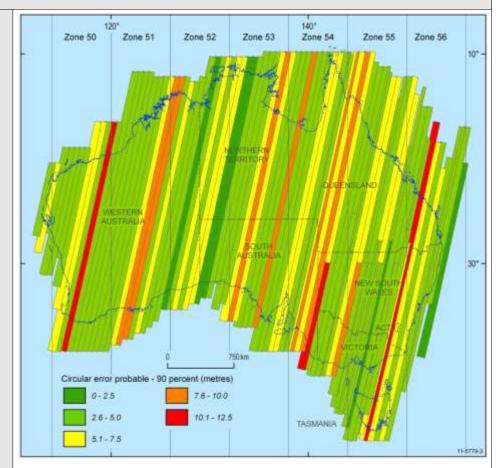
## **Sheet A.1 Definition and Usage** both Earth observation and geodesy were also essential inputs to the project (Lewis et al, 2011). The AGRI provides a consistent base image which will be an important foundation for future mapping and monitoring across Australia. It is a resource for both users and providers of satellite imagery covering Australia in government agencies, research institutions and academia, the spatial information industry, and international satellite operators. The AGRI mosaic and associated datasets are available to the public under the Creative Commons-Attribution licensing terms at cost of transfer from Geoscience Australia. Applications: Reference image – image to image rectification, image chip source, quality control layer Basemap - feature revision and verification, reference layer **Potential Applications** Government - Commonwealth, State and Local Research institutions Spatial Information Industry International satellite operators **Expected** Ongoing as is Lifespan 1201 NORTHERN SOUTH Illustrations **NEW SOUTH** Ground control point Figure 1: The location of surveyed GCPs for the Australian Geographic Reference Image. 2885 features were surveyed at 737 sites

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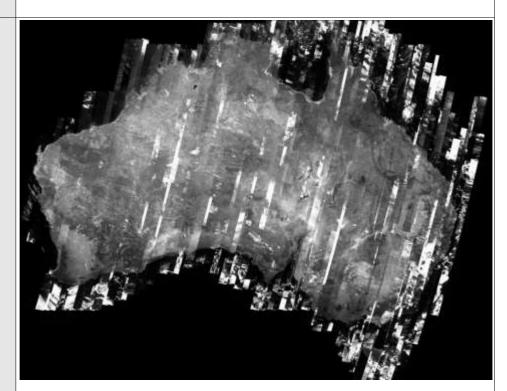


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#### **Sheet A.1 Definition and Usage**



 $Figure~3:~Check~point~residuals~(CEP90)~mapped~in~metres.~The~accuracy~is~assessed~for~each~orbit~segment.\\In~eastern~Australia~two~or~more~segments~were~often~used~to~cover~an~orbit~path.$ 



Example Images

Figure 4: The Australian Geographic Reference Image national mosaic

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### **Sheet A.1 Definition and Usage**

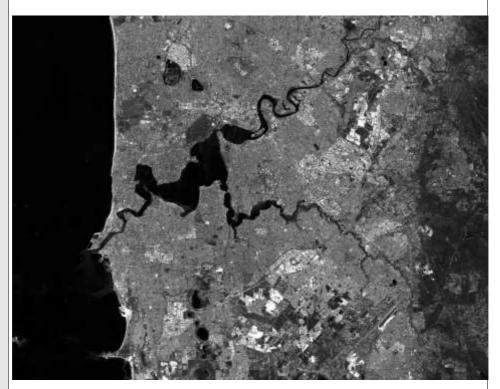


Figure 5: A subset of the Australian Geographic Reference Image over Perth, WA



Figure 6: A subset of the Australian Geographic Reference Image over the Melbourne CBD, VIC

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Sheet A.2	Revisio	ons			
Revision Number	Date	Nature of Change and Reason	Author/Approval		

Sheet A.3	Further	Information	
References		ng, L.W., Coghlan, R. (2011) AGRI: The Australian Geographic Reference Image. A eport. Geoscience Australia, Canberra, GeoCat 72657	
	ADEOS	Advanced Earth Observing Satellite	
	AGRI	Australia Geographic Reference Group	
	ALOS	Advanced Land Observing Satellite (JAXA, Japan)	
	ASCII	American Standard Code for Information Interchange	
	AVNIR	Advanced Visible and Near Infrared Radiometer	
	CCBY	Creative Commons By Attribution	
	CCD	Charge-Coupled Device	
	CEP	Circular Error Probable	
	CRCSI	Cooperative Research Centre for Spatial Information	
	DEM	Digital Elevation Model	
	DSM	Digital Surface Model	
	ECW	ER Mapper Enhanced Compressed Wavelet	
	EO	Earth Observation	
	ERS	ER Mapper ASCII format for extended metadata in raster header files	
	ESRI	An international supplier of GIS software, web GIS and geodatabase management applications.	
	GA	Geoscience Australia	
Glossary	GB	Gigabyte (106 KB)	
,	GCP	Ground Control Point	
	GDA	Geocentric Datum of Australia	
	GIS	Geographic Information System	
	GPS	Global Positioning System	
	GRS	Geodetic Reference System	
	JAXA	Japan Aerospace Exploration Agency	
	JERS-1	Japanese Earth Resources Satellite 1	
	LST	Local Standard Time	
	MGA	Map Grid of Australia	
	MOU	Memorandum of Understanding	
	NaviGAtor	GA data archive and access facility	
	NEO	National Earth Observation group within Geoscience Australia (formerly the Australian Centre for Remote Sensing, ACRES)	
	PALSAR	Phased Array type L-band Synthetic Aperture Radar	
	PRISM	Panchromatic Remote-sensing Instrument for Stereo Mapping	
	STD	Standard Deviation	
	TXT	Text File Format	

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Sheet A.3	Further I	Further Information		
	UTC	Coordinated Universal Time		
UTM Universal Tra		Universal Transverse Mercator		
Websites	http://www.ga.gov.au/image_cache/GA20164.pdf			

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# **B** Specification

Sheet B.1	Provenance and Algorithms					
	Primary	ALOS PRISM Level 1B1 imagery				
	Metadata	Satellite ephemeris data	Satellite ephemeris data			
_		Source	Derived Data			
Data Sources	Ancillary	Ground Control Points (GCPs)	X, Y and Z positional correction information			
		1-second SRTM DSM	Height, slope and aspect per pixel for topographic correction			
Major Algorithms	Apply 'full pass' or 'strip' processing - rectifies a sequential strip of images taken during a single segment of a satellite's orbit. the metadata for each separate scene are merged to produce a single, continuous set of orbit and attitude parameters, such that the entire strip of tens of images can be treated as a single image, even though the separate scenes are not actually merged. The merging of orbit data results in a considerable reduction in both the number of unknown orientation parameters and the number of control points required in the sensor orientation adjustment.  (See technical report and reference papers http://www.ga.gov.au/image_cache/GA20164.pdf)					
Processing Sequence	<ul> <li>Identify cloud-free ALOS PRISM passes</li> <li>Ingest scenes from the same pass into BARISTA software</li> <li>Identify Ground Control Points</li> <li>Full pass processing using bundle adjustment</li> <li>Ortho-processing using DSM</li> </ul>					
Validation of Underlying Algorithms	Independent Check Points from GPS survey.					
Accuracy and Limitations		Absolute geometric accuracy: 5.6m CEP90     Cloudy over some area				

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Sheet B.2 Technical Characteristics				
Sheet	B.2.1 Relevant P	latforms		
Full Na	me	Advanced Land Observing Satellite		
Abbrev	iation	ALOS		
Agency	,	Japan Aerospace Exploration Agency (JAXA)		
Application Areas		Cartography, Regional Observation, Disaster Monitoring, Resource Surveying		
Launch	Date	24 January 2006		
End of	Life	21 April 2011		
	Туре	Sun-synchronous, near polar		
	Direction	Ascending		
	Altitude	691.65 Km at equator (accuracy 2.0 x 10.° with GCP)		
Orbit	Inclination	98.16°		
Orbit	Period	98.7 minutes		
	Repeat Cycle	46 days (sub-cycle 2 days)		
	Equatorial Crossing Time	10:10 LST		
Sensors		Advanced Visible and Near Infrared Radiometer type 2 (AVNIR-2)		
		Phased Array type L-band Synthetic Aperture Radar (PALSAR)		
		Panchromatic Remote-sensing Instrument for Stereo Mapping (PRISM)		

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Sheet B.2 Technical Characteristics (continued)				
Sheet B.2.2 Relevant S	ensor	s		
Full Name	Panchromatic Remote-sensing Instrument for Stereo Mapping			
Abbreviation	PRISM			
Platform	ALOS	satellite		
Operational	No			
GA Data Reception	2007-	2010; MOL	J expired Decemb	er 2010
Sensing Mode	Passive	e		
Scanning Method			—Push broom for nd Backward (8 CC	three telescopes: Forward (8 CCDs), CDs)
<b>Application Areas</b>	Digita	l Elevation	Models	
	Band	Spectral Range (µm)	EM Region	Application
Spectral Bands	1	0.52- 0.77	Panchromatic	Digital elevation models, image sharpening, topographical mapping, disaster and environmental monitoring
Radiometric Quantisation	8 bits			
Swath Width	Triplet mode: 35 km (nadir); Wide mode: 70 km (nadir)			
<b>Ground Sampling Interval</b>		Ва	nd	Metres
(GSI or pixel size)		1		2.5 m (nadir)
Repeat Coverage Interval	See ALOS Satellite details			

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Sheet B.2 Technical Characteristics (continued)						
Sheet B.2.3 Pro	Sheet B.2.3 Product Details					
Frequency	N/A					
Temporal Extent	29/11/2006 to 28/10/20	010				
		NW	9.976°S latitude, 112.1	I 17°E longitude		
		NE	9.976°S latitude, 157.3	3667°E longitude		
6 4 15 4 4	Geographic Coverage	SW	44.2009°S latitude, 11	2.117°E longitude		
Spatial Extent		SE	44.2009°S latitude, 15	7.3667°E longitude		
	C'ID'	W–E	8,059,504 grid cells			
	Grid Dimensions	N-S	6,095,848 grid cells			
	Datum	World Geod	detic System (WGS) 84			
			Semi-major axis (a)	6,378,137 m		
Mapping Base for Continental Mosaic	Ellipsoid	WGS84	Inverse Flattening (1/f)	298.257223563		
			Eccentricity (e <sup>2</sup> )	0.006694379990		
	Projection	Plate Carrée (Equirectangular)				
	Cell Size	0.0001 deg				
Image Grid for	Туре	Custom Grid				
Continental Mosaic	Pixel Origin	Top Left				
	Orientation	North Upwards				
	Resampling Method	Cubic Conv	rolution			
	Datum	World Geod	detic System (WGS) 84	T		
			Semi-major axis (a)	6,378,137 m		
Mapping Base for	Ellipsoid	WGS84	Inverse Flattening (1/f)	298.257223563		
Zone Mosaics			Eccentricity (e <sup>2</sup> )	0.006694379990		
	Map Co-ordinate System	Projected				
	Projection	Universal T	ransverse Mercator (UT)	M)		
	Origin	Centre of U	TM zone			
	Cell Size	2.5m				
Image Grid for	Туре	Custom Gri	d			
Zone Mosaics	Pixel Origin	Top Left				
	Orientation	North Upwa				
	Resampling Method	Cubic Conv	rolution			
Grid Bit Depth	8 bit (256 levels)					

Sheet B.2 Technical Characteristics (continued)				
Sheet B.2.3a Product Details for Grid-Based Products				
Spectral Dande	Data	Band 1	Observed values from ALOS PRISM band 1	
Spectral Bands	Quicklook	Band 1	n/a	
Data RangeBand TypePanchromatic - 0 to 255				

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Sheet B.2 To	echnical Ch	aracteristics (continued)				
Sheet B.2.3b P	roduct Detail	s for Vector-Based Products				
Filename	AGRI_GCP					
Description	The database contains the precise survey locations of all of the control points. It also contains tables relating to supporting ancillary data (photographs, sketches, and image chips) for each survey point where applicable.					
Format	ESRI File Geoda	tabase				
Datum	Geocentric Datu	um of Australia (GDA) 1994				
Projection	Geographic					
Feature Layer	AGRI_GCP					
.,,	GcpID	A unique identifier assigned to each GCP				
	GPS_Long	Longitude of the GCP (GDA94 decimal degrees) as supplied by Surveyor				
	GPS_Lat	Latitude of the GCP (GDA94 decimal degrees) as supplied by Surveyor				
	GPS_Ht	Height of the GCP (GDA94 ellipsoidal height) supplied by Surveyor				
	GcpStatus	Determination of whether the GCP was a proposed GCP or a new GCP				
	Descriptn	Brief description of the surveyed point including the type of intersection if applicable.				
	SiteID	The unique site identifier the GCP was part of				
	DateSurvey	The date the GCP was surveyed				
Layer Attributes	Surveyor	The company which surveyed the GCP				
Layer Attributes	NumSat	Number of Satellites during capture				
	Averaging	Number of observations taken to obtain the average				
	PDOP	Position Dilution of Precision (PDOP) value as supplied by the surveyor				
	GPS_Hz_Acc	Horizontal positional accuracy at 1 STD expressed in metres				
	GPS_Vt_Acc	Vertical positional accuracy at 1 STD expressed in metres				
	Zone	UTM zone the GCP falls within				
	Folder	The folder supporting data (photos, sketches) are stored in				
	Photos	The number of photos available in the supporting folder of the GCP				
	Sketches	The number of sketches available in the supporting folder of the GCP				
	Chips	The number of image chips available in the supporting folder of the GCP				
	gcpChips					
Feature Tables	gcpPhoto					
	gcpSketch					
	GcpID	A unique identifier assigned to each GCP				
	FileName	The filename of the ancillary file				
Table Attributes	Direction	The direction the photograph was taken (only applicable to photos)				
	Description	Brief description of the surveyed point including the type of intersection if applicable.				

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ESRI File Geodatabase	Sheet B.2 Technical Characteristics (continued)						
The database contains approximate positions of each of the ALOS PRISM scenes and paths used to create the mosaics and associated metadata. The data layers car be used to relate metadata fields to the mosaic products.    Format	Sheet B.2.3b P	roduct Detail	s for Vector-Based Products				
Description   and paths used to create the mosaics and associated metadata. The data layers can be used to relate metadata fields to the mosaic products.	Filename	AGRI_mosaic_metadata					
Projection   Geographic	Description	and paths used to create the mosaics and associated metadata. The data layers can					
Projection   AGRL_PRISM_ortho_scenes	Format	ESRI File Geodat	tabase				
AGRL_PRISM_scenes	Datum	World Geodetic System (WGS) 1984					
Patform   The satellite name	Projection	<u>'</u>					
Platform The satellite name Instrument The instrument on-board the satellite used Resolution The resolution of the image Path A number used to identify the descending path of the satellite Row A number used to identify the placement along the path of the particular image Orbit_Numb A number used to identify the orbit of the satellite Acq_Start The date and time (UTC) image acquisition started Acq_Stop The date and time (UTC) image acquisition stopped Collec_Site The ground segment the data was downlinked to Oper_Mode The operation mode of the instrument Acq_Date The acquisition date of the image Path_ID A unique sequence assigned to identify paths that make up the ACRI mosaics Continental_mosaic_metadata AGRI_PRISM_path_accuracy Zone_**_mosaic_metadata Path_ID A unique sequence assigned to identify paths that make up the ACRI mosaics Acq_Date The acquisition date of the image DateString The acquisition date of the image DateString The acquisition date of the image DateString The acquisition date represented as a number string The order in which satellite paths were overlayed to form the final mosaicked products. The lowest number (1) appears in the mosaic as the top layer. The highest number (110) appears in the mosaic as the top layer. The highest number (110) appears in the mosaic as the top layer. The highest number (110) appears in the mosaic as the top layer. The highest number (110) appears in the mosaic as the bottom layer.  N The total number of check point.  Minimum The minimum of the observed check point errors The maximum of the observed check point errors The maximum of the observed check point errors Stdev The standard deviation of the observed check point errors The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.							
Platform   The satellite name	Feature Layers						
Resolution   The resolution of the image							
Path		Instrument	The instrument on-board the satellite used				
Path		Resolution	The resolution of the image				
Layer Attributes    Corbit_Numb		Path					
Acq_Start   The date and time (UTC) image acquisition started		Row					
Acq_Stop	Lawar Attuibutaa	Orbit_Numb	A number used to identify the orbit of the satellite				
Collec_Site Oper_Mode The operation mode of the instrument Acq_Date The acquisition date of the image Path_ID Acg_PRISM_path_accuracy Zone_**_mosaic_metadata Path_ID Acg_Date Aunique sequence assigned to identify paths that make up the AGRI mosaics Continental_mosaic_metadata AGRI_PRISM_path_accuracy Zone_**_mosaic_metadata Path_ID Aunique sequence assigned to identify paths that make up the AGRI mosaics Acq_Date The acquisition date of the image DateString The acquisition date represented as a number string The order in which satellite paths were overlayed to form the final mosaic as the top layer. The highest number (11 appears in the mosaic as the top layer. The highest number (110) appears in the mosaic as the bottom layer.  N The total number of check points. The minimum of the observed check point errors Maximum Maximum The maximum of the observed check point errors Median The median of the observed check point errors Stdev The standard deviation of the observed check point errors The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point are expected lie.	Layer Attributes	Acq_Start	The date and time (UTC) image acquisition started				
Path_ID		Acq_Stop	The date and time (UTC) image acquisition stopped				
Acq_Date		Collec_Site	The ground segment the data was downlinked to				
Path_ID  A unique sequence assigned to identify paths that make up the AGRI mosaics  Continental_mosaic_metadata  AGRI_PRISM_path_accuracy  Zone_**_mosaic_metadata  Path_ID  A unique sequence assigned to identify paths that make up the AGRI mosaics  Acq_Date  The acquisition date of the image  DateString  The order in which satellite paths were overlayed to form the final mosaicked products. The lowest number (1) appears in the mosaic as the bottom layer.  N  The total number of check points.  Minimum  Maximum  Maximum  Median  The maximum of the observed check point errors  Mean  The median of the observed check point errors  Stdev  The standard deviation of the observed check point errors  The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.		Oper_Mode	The operation mode of the instrument				
Feature Layers  Continental_mosaic_metadata  AGRI_PRISM_path_accuracy  Zone_**_mosaic_metadata  Path_ID  Aunique sequence assigned to identify paths that make up the AGRI mosaics  Acq_Date  The acquisition date of the image  DateString  The acquisition date represented as a number string  The order in which satellite paths were overlayed to form the final mosaicked products. The lowest number (1) appears in the mosaic as the top layer. The highest number (110) appears in the mosaic as the bottom layer.  N  The total number of check points.  The minimum of the observed check point errors  Maximum  Maximum  The maximum of the observed check point errors  Median  The median of the observed check point errors  Stdev  The standard deviation of the observed check point errors  The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.		Acq_Date	The acquisition date of the image				
Feature Layers  AGRI_PRISM_path_accuracy Zone_**_mosaic_metadata  Path_ID  A unique sequence assigned to identify paths that make up the AGRI mosaics  Acq_Date  The acquisition date of the image  The order in which satellite paths were overlayed to form the final mosaicked products. The lowest number (1) appears in the mosaic as the top layer. The highest number (110) appears in the mosaic as the bottom layer.  N  The total number of check points.  Minimum  Maximum  Maximum  The maximum of the observed check point errors  Median  The median of the observed check point errors  Mean  The mean of the observed check point errors  Stdev  The standard deviation of the observed check point errors  The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.		Path_ID					
Zone_**_mosaic_metadata		Continental_mos	saic_metadata				
Path_ID  A unique sequence assigned to identify paths that make up the AGRI mosaics  Acq_Date  The acquisition date of the image  The acquisition date represented as a number string  The order in which satellite paths were overlayed to form the final mosaic as the top layer. The highest number (1) appears in the mosaic as the bottom layer.  N  The total number of check points.  The minimum of the observed check point errors  Maximum  Maximum  The maximum of the observed check point errors  The median of the observed check point errors  Mean  The mean of the observed check point errors  Stdev  The standard deviation of the observed check point errors  The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.	Feature Layers	AGRI_PRISM_path_accuracy					
AGRI mosaics  Acq_Date The acquisition date of the image  DateString The acquisition date represented as a number string The order in which satellite paths were overlayed to form the final mosaic as the top layer. The highest number (1) appears in the mosaic as the bottom layer.  N The total number of check points.  Maximum The minimum of the observed check point errors  Median The median of the observed check point errors  The mean of the observed check point errors  Stdev The standard deviation of the observed check point errors  The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.		Zone_**_mosaic	z_metadata				
Path_Order  Path_Order  The order in which satellite paths were overlayed to form the final mosaic as the top layer. The highest number (1) appears in the mosaic as the bottom layer.  N The total number of check points.  Maximum The maximum of the observed check point errors  Median The median of the observed check point errors  Mean The mean of the observed check point errors  Stdev The standard deviation of the observed check point errors  The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.		Path_ID					
Path_Order  The order in which satellite paths were overlayed to form the final mosaic as the top layer. The highest number (1) appears in the mosaic as the bottom layer.  N The total number of check points.  Minimum The minimum of the observed check point errors  Maximum The maximum of the observed check point errors  Median The median of the observed check point errors  Mean The mean of the observed check point errors  Stdev The standard deviation of the observed check point errors  The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.		Acq_Date	The acquisition date of the image				
Fath_Order  final mosaicked products. The lowest number (1) appears in the mosaic as the top layer. The highest number (110) appears in the mosaic as the bottom layer.  N The total number of check points.  The minimum of the observed check point errors  The maximum of the observed check point errors  The median of the observed check point errors  The mean of the observed check point errors  Stdev The standard deviation of the observed check point errors  The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.		DateString	The acquisition date represented as a number string				
Adding The minimum of the observed check point errors  Maximum The maximum of the observed check point errors  Median The median of the observed check point errors  Mean The mean of the observed check point errors  Stdev The standard deviation of the observed check point errors  The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.	Layer Attributes	Path_Order	final mosaicked products. The lowest number (1) appears in the mosaic as the top layer. The highest number (110) appears in the				
Maximum The minimum of the observed check point errors The maximum of the observed check point errors  Median The median of the observed check point errors The mean of the observed check point errors  Stdev The standard deviation of the observed check point errors The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.		N	The total number of check points.				
Median  The median of the observed check point errors  Mean  The mean of the observed check point errors  Stdev  The standard deviation of the observed check point errors  The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.		Minimum	The minimum of the observed check point errors				
Mean The mean of the observed check point errors  Stdev The standard deviation of the observed check point errors  The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.		Maximum	The maximum of the observed check point errors				
The standard deviation of the observed check point errors  The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.		Median	The median of the observed check point errors				
The Circular Error Probable – 90 percent. Estimated as the 90th percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.		Mean	The mean of the observed check point errors				
percentile of the check point error sample, this is a non-parametric estimate of the distance from true location within which 90 percent of points are expected lie.		Stdev	The standard deviation of the observed check point errors				
		CEP90	percentile of the check point error sample, this is a non- parametric estimate of the distance from true location within				
Anciliary_data_tiles	Filename	Ancillary_data_t	iles				

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Sheet B.2 Technical Characteristics (continued)							
Sheet B.2.3b Product Details for Vector-Based Products							
Description	The spatial layer used to index ancillary (photographs, sketches, and image chips) data.						
Format	Shapefile						
Datum	Geocentric Datum of Australia (GDA) 1994						
Projection	Geographical						
	Zone	The UTM zone the ancillary data falls within					
<b>Layer Attributes</b>	Folder The folder the ancillary data falls within						
	Location	The location the ancillary data falls within					

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# **C** Availability

Sheet C.1 Licencing and Access					
Support	Supported				
Licencing	Creative Commons 4.0 Attribution International licence: http://creativecommons.org/licenses/by/4.0/legalcode				
Search Tool  NEO Webpage/NaviGAtor http://www.ga.gov.au/search/index.html					
<b>Preview Facility</b>	N/A				
Ordering and Distribution	GA Sales Centre				

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Sheet C.2 Delivery Information							
	PRISM_UTA	PRISM_UTMnn_type					
File Name		Where: nn: UTM zone for zone mosaics type: Compressed for ECW compressed files					
	Continental	Continental_Mosaic					
File Format	Data	ASCII ERS/ECW, File Geodatabase, Shapefile					
	Metadata	TXT					
	Quicklook	n/a					
			ASCII ERS	ECW			
		Continental Mosaic (10m)	142.46	11.17			
		Zone 49 Mosaic (2.5m)	74.78	1.24			
		Zone 50 Mosaic (2.5m)	296.62	19.47			
	Total Product (GB)	Zone 51 Mosaic (2.5m)	376.25	15.63			
Data Volume		Zone 52 Mosaic (2.5m)	354.37	28.62			
		Zone 53 Mosaic (2.5m)	381.81	28.88			
		Zone 54 Mosaic (2.5m)	472.50	26.79			
		Zone 55 Mosaic (2.5m)	474.06	29.49			
		Zone 56 Mosaic (2.5m)	387.50	11.41			
		TOTAL	2960.36	172.69			

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